# SSU-2000 <br> Synchronization Supply Unit and the <br> SDU-2000 Synchronization Distribution Unit 

User Guide<br>Revision C. 02 - April 2002<br>Part Number: 12713020-002-2

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## In this Chapter ...

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- Who Should Read This Manual
- About This Guide
- Typographical and Other Conventions
- Warnings, Cautions, Recommendations, and Notes
- Related Documents
- Where to Find Answers to Product and Document Questions


## Chapter 1 Introduction

The SSU-2000 User Guide provides installation, operation, and maintenance procedures for the SSU-2000 Synchronization Supply Unit (SSU-2000).

The SSU-2000, shown in Figure 1-1, provides a Stratum 1 network synchronization solution for central office (CO), end office, customer premises equipment (CPE) sites, controlled equipment vaults (CEV), and telecommunications and data communications network operations.
The SSU-2000 family of products consists of:

- SSU-2000 Synchronization Supply Unit
- SSU-2000 family of modules
- SDU-2000 Expansion Shelf (up to four units)
- Various mounting, cabling, and miscellaneous accessories as described in Appendix C, Antennas

Additional product overview information is provided in Chapter 2, Product Overview, of this manual.


Figure 1-1. SSU-2000 Synchronization Supply System

### 1.1 What's New in this Manual

The current release of this User Guide is revision C.02, which includes a general User Guide update and the following updates to the SSU-2000 hardware and software:

- Software command update of the TL1 and ICS sections
- Addition of Network Time Protocol (NTP) implementation
- Addition of four software loads available for the Communications Module
- Addition of Simple Network Management Protocol (SNMP) implementation
- Addition of Connector Pinouts to include:
- Signal Names and Definitions
- Shelf Module Slot Addressing and Assignments
- Antenna Signal Connections A3 and A5
- Implementation of the following requirements:
- EMC requirements of GR-1089-CORE Issue 2, 12-1997
- SELV equipment requirements for product safety as specified in UL 1950/CSA C22.2, 7-1995
- Addition of System Specifications and Reference Materials Sections
- Expansion of the Index and Glossary sections


### 1.2 Who Should Read This Manual

This User Guide is designed for the following categories of users:

- Systems Engineers - Chapter 1 provides an introduction to the SSU-2000, while Chapter 2 provides an overview of the product. Cross-references in these sections direct readers to detailed system information in other chapters as appropriate.
- Installation Engineers - Chapter 3 through Chapter 9 and the Appendices provide detailed information and procedures to ensure proper installation, turn-up, operation, configuration, and testing of the SSU-2000.
- Maintenance Engineers - Chapter 7, Chapter 8, and the Appendices provide preventive and corrective maintenance guidelines, as well as procedures for diagnosing and troubleshooting fault indications and alarms.

While Chapter 1 and Chapter 2 are written for non-technical audiences who need information about the SSU-2000 system, others, such as Chapter 3 through Chapter 9 contain detailed information and instructions which are intended to be performed by qualified personnel only.

### 1.3 About This Guide

This guide contains the following chapters and appendixes:

- Chapter 1, Introduction - Includes an overview of this manual, the intended audience, the stylistic and typographical conventions used and defines a list of other documents available for the reader.
- Chapter 2, Product Overview - Provides an overview of the SSU-2000 system components, describes the major hardware and software features and provides a listing of system specifications.
- Chapter 3, Installation - Provides unpacking and installation procedures for the SSU-2000 and the SDU-2000 Expansion chassis.
- Chapter 4, Turn-Up Procedures - Describes the power up procedures required to bring a new system on-line.
- Chapter 5, Operating and Provisioning Procedures - Describes the individual module LED indicators and provides procedures for connecting to the SSU-2000 for communications. This chapter also describes how to set up the Administrator and other users, provides procedures for changing software options, and lists factory default configuration settings.
- Chapter 6, Commissioning - Includes an overview of the checklist-based commissioning tests that should be performed after completing turn-up and software configuration to ensure the system is ready for normal operation.
- Chapter 7, Maintenance and Troubleshooting - Provides preventive and corrective maintenance and troubleshooting procedures for the SSU-2000 system.
- Chapter 8, Module Reference Data - Describes each available module in the SSU-2000 family. This section includes LED descriptions, a functional block diagram, and a list of specifications for each module.
- Chapter 9, Hardware Configuration Guide - Provides system hardware selection and procurement information for various SSU-2000 system configurations and optional equipment.
- Appendix A, Alarms and Events - Includes a list and description of the alarms and events that can occur with the SSU-2000 system.
- Appendix B, Communications Protocol - Provides information about the Transaction Language One (TL1), Interactive Command Set (ICS) and Simple Network Time Protocol (SNMP) control languages that are used to communicate with the SSU-2000 software.
- Appendix C, Antennas - Lists, describes, and provides installation procedures for antennas available for use with the SSU-2000 system.
- Appendix D, Connector Pinouts - Lists and describes the signal pinouts for the SSU-2000 external connectors.
- Appendix E, Default Settings - Lists and describes the factory defaults for the various modules associated with the SSU-2000 system.
- Appendix F, Regulatory Requirements- Includes safety and EMC standards and requirements for the SSU-2000 system.
- Appendix G, Specifications - Provides specifications for the SSU-2000 unit and for its functional components, such as operating conditions, power inputs, clock inputs and outputs, indicators, and chassis dimensions.
- Appendix H, Reference Materials - Lists associated reference materials in the following categories:
- American National Standards Institute (ANSI) Documents
- Generic Requirements
- Technical Advisories and Framework Technical Advisories
- Technical References
- EIA/TIA Documents
- Other Reference Documents
- Glossary - Includes a list of acronyms and abbreviations, and a definition of terms found in this guide.


### 1.4 Typographical and Other Conventions

This manual uses the following conventions:

- Acronyms and Abbreviations - Terms are spelled out the first time they appear in text. Thereafter, only the acronym or abbreviation is used. In addition, the Glossary defines the acronyms and abbreviations.
- Revision Control - The title page lists the printing date and versions of the product this guide describes.

Table 1-1. Typographical Conventions

| When Text Appears This <br> Way ... | It Means ... |
| :--- | :--- |
| SSU-2000 User Guide | The title of a document. |
| CRITICAL <br> PORT-A <br> J1 | An operating mode, alarm state, status, or chassis label. |
| Press the Enter key. <br> Press the Print Scrn key. | A named keyboard key. The key name is shown as it appears on the <br> keyboard. An explanation of the key's acronym or function immediately <br> follows the first reference to the key, if required. |
| SSU-2000 <br> Username: | Text in a source file or a system prompt or other text that appears on a <br> screen. |

## Table 1-1. Typographical Conventions (Continued)

| When Text Appears This <br> Way ... | It Means ... |
| :--- | :--- |
| ENGINE TDATA <br> STATUS | A command you enter at a system prompt or text you enter in response <br> to a program prompt. You must enter commands for case-sensitive <br> operating systems exactly as shown. |
| A re-timing application ... | A term or a word being emphasized. |
| Datum does not recommend $\ldots$ | A word or term given special emphasis so that you do not miss the idea <br> being presented. |

### 1.5 Warnings, Cautions, Recommendations, and Notes

Warnings, Cautions, Recommendations, and Notes attract attention to essential or critical information in this manual. The types of information included in each are explained below


## WARNing:

All warnings have this symbol. Do not disregard warnings. They are installation, operation or maintenance procedures, practices, or statements, which if not strictly observed, may result in personal injury or loss of life.


## Electrical Shock Hazard:

All electrical shock hazard warnings have this symbol. To avoid serious personal injury or death, do not disregard electrical shock hazard warnings. They are installation, operation, or maintenance procedures, practices, or statements that if not strictly observed, may result in personal injury or loss of life.


## Caution:

All cautions have this form and symbol. Do not disregard cautions. They are installation, operation, or maintenance procedures, practices, conditions, or statements, which if not strictly observed, may result in damage to, or destruction of, equipment or may cause a long-term health hazard.

## Caution:

All Electrostatic Discharge (ESD) cautions have this symbol. They are installation, operation, or maintenance procedures, practices, conditions, or statements that if not strictly observed, may result in electrostatic discharge damage to, or destruction of, static sensitive components of the equipment.

## 玉 <br> Recommendation: <br> All recommendations have this form and symbol. <br> Recommendations indicate manufacturer-tested methods or known functionality. They contain installation, operation, or maintenance procedures, practices, conditions, or statements, which provide you important information for optimum performance results.

## 플 <br> Nоте: <br> All notes have this form and symbol. Notes contain installation, operation, or maintenance procedures, practices, conditions, or statements that alert you to important information which may make your task easier or increase your understanding.

### 1.6 Related Documents

Other helpful documents are listed below. See your Datum representative or sales office for a complete list of available documentation.

## [

Datum offers a number of applicable training courses designed to enhance product usability. Contact your Datum representative or sales office for a complete list of courses and outlines.

SynCraft - This is a software interface program that is available to provide monitoring and configuration functionality in a Microsoft Windows graphical user interface.

## 프풀

Nоте:
Contact your Datum Sales Representative for more information on the SynCraft Graphical User Interface, P/N 14113245-000-0.

### 1.7 Where to Find Answers to Product and Document Questions

For additional information about the products described in this manual, please contact your Datum representative or sales office. You may also complete and return the Reader Comment Form located in the back of this manual. We appreciate your suggestions of ways to improve any part of this manual. Please make your suggestions on a copy of the affected page and include it with the comment form.

In this Chapter ...

- Typical System Configurations
- System Architecture
- System Components
- Communications Protocol
- Operation Overview
- Indicators and Controls
- SDU-2000 Synchronization Distribution Unit


## Chapter 2 Product Overview

The SSU-2000 Synchronization Supply Unit (SSU-2000), shown in Figure 2-1, is a highperformance, Synchronization Status Messaging (SSM)-compliant Timing Signal Generator (TSG) or Synchronization Supply Unit that provides network synchronization signals for the telephone and telecommunications industry.

ss200006
Figure 2-1. SSU-2000 Synchronization Supply Unit

The SSU-2000 conforms to specifications for International, European and North American applications as a Primary Reference Source (PRS), and Synchronization Supply Unit (SSU), and Timing Signal Generator (TSG). The SSU-2000 allows for the integration of a variety of synchronization reference schemes including GPS and land line DS1/E1. The SSU-2000 meets or exceeds performance requirements for ANSI and Telcordia Technologies (Bellcore) Stratum 2 and ITU and ETSI Type II Transit Node clocks.

The SSU-2000 is designed to comply with the application flexibility and redundancy concepts introduced in Telcordia Technologies (formerly Bellcore) GR-2830. A selection of hot-plugable modules and powerful software allow users to easily reconfigure, upgrade, or expand the SSU2000 to meet a variety of telecommunications synchronization application requirements.

The SSU-2000 fully supports Synchronization Status Messaging (SSM) as defined by ANSI, Telcordia Technologies, ITU, and ETSI.

The SSU-2000 is fully user-configurable and manageable through a software interface. Modules can be inserted or removed from the SSU-2000 while the system is operational without any degradation of output signals. Each module supports the management of critical, major and minor alarms, locally and remotely. Output modules and clock modules can be configured in redundant pairs, further increasing system availability.

The SSU-2000 has extensive event detection, reporting, alarming, and storage capabilities that permit monitoring of the system from external sites. Events are defined as changes in conditions within the unit, or at the interfaces of the unit, which may indicate abnormal operation or a change in the unit's operational status. For example, an event may be a parameter which exceeds a user-set threshold (usually 2 thresholds are provided). Each event can be assigned by the user to one of four modes, including IGNORE, REPORT, ALARM, or FAIL.

### 2.1 Typical System Configurations

The modular design of the SSU-2000 permits a great deal of flexibility in configuring the system components for a variety of applications. Three of the more common configurations include:

- Time Signal Generator (TSG) configuration
- Primary Reference Source (PRS) configuration
- Monitor-only configuration


### 2.1.1 Timing Signal Generator (TSG) Configuration

The Timing Signal Generator (TSG) configuration shown in Figure 2-2 allows for input of external references to which the Clock modules are phase and frequency locked. This configuration allows for monitoring of several inputs, and for synchronization of output signals.


Figure 2-2. SSU-2000 in TSG Configuration

### 2.1.2 Primary Reference Source (PRS) Configuration

In a Primary Reference Source (PRS) configuration (Figure 2-3), the SSU-2000 meets the specifications defined in American National Standards Institute (ANSI) T1.101-1999. ANSI defines a Primary Reference Source as "equipment that provides a timing signal whose long term accuracy is maintained at $1 \times 10^{-11}$ or better, with verification to Universal Coordinated Time (UTC), and whose timing signal may be used as the basis of reference for the control of other clocks within a network". If standard Input modules are installed in the remaining input slots, this configuration also allows for monitoring of up to 27 external signals, such as DS1, E1, composite clock, and various clock frequencies. Time-of-day functionality is available through an Ethernet port employing NTP.


Figure 2-3. SSU-2000 Configured as a Primary Reference Source

### 2.1.3 SSU-2000 Configured as a Monitor-Only System

The SSU-2000 can also be configured as a monitor-only system (Figure 2-4) in which one of the inputs is designated as the reference, and a clock module is locked directly to this signal. The remaining input signals are then compared to the phase-locked oscillators (and indirectly to the designated input reference).

The SSU-2000 continuously monitors the integrity incoming timing signal. The operator defines input acceptance criteria and sets parameters for alarming. When the incoming signal is acceptable (within the performance limits set by the operator), the SSU-2000 phase-locks to the signal on a priority basis.


Figure 2-4. SSU-2000 Configured as a Monitor Only System

### 2.2 System Architecture

The SSU-2000 system is a Timing Signal Generator that generates, monitors, controls and distributes network synchronization signals. These signals can be DS1, E1, Composite Clock (CC), sinusoids, or square waves. The SSU-2000 continuously monitors incoming timing signal integrity. The operator defines input acceptance criteria and sets parameters for alarming. If a reference signal is acceptable (within the performance limits set by an operator), the SSU-2000 frequency-locks to the signal on a priority basis. System holdover and filtering performance is dependent on the quality of oscillators used in the SSU-2000's internal clock modules (Stratum 2E or Stratum 3E).

A selection of hot-plugable modules and powerful software allow users to easily configure, upgrade, or expand the SSU-2000 system to meet a variety of telecommunications synchronization application requirements. Modules can be inserted or removed from the SSU-2000 while the system is operational without any degradation of output signals. Each module supports the management of critical, major, and minor alarms. Output modules and clock modules can be configured in redundant pairs for increased reliability.

A simplified system block diagram for the SSU-2000 is shown in Figure 2-5.


Figure 2-5. SSU-2000 System Block Diagram
As indicated in Figure 2-5, the SSU-2000 consists of four major sections:

- Input section
- Clock section
- Output section
- Communications section


### 2.2.1 Input Section

The input section consists of one, two, or three Input modules that are connected to reference signals that are tested for signal integrity. The Input modules make phase measurements between the input signal and the clock oscillator(s). From these phase measurements, the Input modules compute frequency offset and wander of the input signals. Wander is reported in terms of Maximum Time Interval Error (MTIE) and Time Deviation (TDEV). The data is then stored for use in the SSU-2000 and reported through the Communications module. Up to two of the Input modules may be GPS modules that use the satellite-based Global Positioning System GPS signals as a synchronization reference.The Input signal types supported are:

- DS 1/Clock (unframed)
- E1/Clock (unframed)
- GPS


### 2.2.2 Input Reference Selection and Reference Switching

The ICS command REF is used to determine what type of reference input selection and reference switching is used. The mode is based on either the Priority settings or on the PQL values (refer to the REF command in Section B.3, Interactive Command Set. After the reference switching mode has been selected, the Input module reads and processes the Priority level and PQL value to determine the traceability of inputs. This traceability information is then used by the Clock modules in selecting a reference signal and for embedding the SSM into the system's outputs. If Priority mode is selected, then the unit will select an input reference first based on the user defined priority settings on each input, then on the PQL (quality level, SSM) values for equal priorities. If $P Q L$ mode is selected, then the inputs reference selection is first based on the PQL levels that are assigned or read (SSM's) at the inputs, then based on the priority levels as assigned to the inputs. In either case, error codes such as Loss of Signal (LOS), Out of Frame (OOF), MTIE, TDEV, and Phase performance data collected at the inputs are used to disqualify inputs (prevent input selection) based on user defined thresholds.

If the Input module is configured for provisioned mode, it will report the provisioned SSM. If configured for automatic mode, the Input module uses the most recent valid SSM. If a valid SSM is not received, the module uses the provisioned SSM.

Also included in the REF command are options for AutoReturn, AutoSwitch, or OFF. When set to OFF, only manual switching is allowed, and failure of the selected input changes operation of the clocks to holdover mode. When set to AutoSwitch, reference selection is automatic on failure of the selected input, and AutoReturn allows automatic switching with automatic return to the highest priority or PQL input.

### 2.2.3 Output Section

The output section is implemented with one or more Output modules of up to 6 (3 redundant pairs) in the main shelf and up to 46 ( 23 redundant pairs) in a fully expanded system with four SDU-2000 expansion shelves. Each Output module type provides 20 independent output synchronization signals. Output modules are available to support the following formats:

- DS1, SF (D4) and ESF
- E1
- 2048 kHz
- Composite Clock (CC) ( $64 / 8 \mathrm{kHz}$ )
- Other typical clock frequencies


### 2.2.4 Clock Section

The clock section consists of one or two Clock modules that provide the internal reference signals for generating TSG output timing signals. The primary Clock module (Clock A) is configured as the master clock and is normally a higher stratum level than the back-up clock (Clock B). If a problem occurs in Clock A, the control is automatically passed to the back-up Clock module (Clock B). The frequency of each clock is locked to a valid reference input signal (one that is free from input faults while meeting acceptable frequency and MTIE specifications).

The SSU-2000 controls clock frequency by adjusting the control value of the Direct Digital Synthesis (DDS) function in each Clock module. The adjustments are processor-controlled and based on measurements performed and computed in the Input module(s). Clock modules may be Stratum 2E and Stratum 3E. Outputs are maintained by the active input reference signal if both clocks should ever fail or be removed from the system.

### 2.2.5 Communications Section

The Communications section consists of one Communications module, which contains hardware and software that allows the user to configure, monitor, and control the SSU-2000 system and generate local and remote alarms when fault conditions are detected. The SSU-2000 can continue to function seamlessly without the Communications module (Clock modules assume the system controller function), but all communications and alarm reporting functions are interrupted.

The master controller function for the SSU-2000 can reside in either the Communications module or in either of the clock modules. The priority of the selection of the module that will provide the master controller function rests with the Communications module, Clock A, and Clock B, in that order. In the event of removal of the module designated as the master controller, that function automatically and seamlessly switches to the next module in priority order.

The Communications module communicates with the other modules in the SSU-2000 to read configuration data, set operational parameters, and determine what type of modules are installed. When a module is replaced, the controller loads the correct operational parameters into the replacement module.

The Communications module provides an interface between the user and the $\mathrm{SSU}-2000$ system. This interface allows the user to display and control much of the activity in the SSU-2000 system and within the optional SDU-2000 expansion system. The Communications module supports three serial ports and one Ethernet port, and allows communication over each of them independently in one of several possible modes (ASCII, TL1, or packet).

The software in the Communications module allows for on-site reprogramming of the flash ROM and reconfiguration of all programmable logic devices. The Communications module also allows for this same capability for the input and clock modules. The software on all other module types installed in the SSU-2000 system can be updated by downloading it through the Communications module.

When the Communications module is installed, it performs an initial software verification test to verify operation. If the module is installed in the SSU-2000 with power already applied and with other modules installed, the Communications module reads the configuration of the modules in the SSU-2000 and the modules in all installed SDU-2000 expansion shelves. This information is saved in nonvolatile memory in the Communications module. If power is applied to the SSU2000 after the Communications module is installed, it initializes before of any of the other modules and provides configuration information to the individual modules.

## ㅍN Note..

The clock modules also store configuration information and can download this information to the various modules, if the Communications module is removed from the system.

## Alarms and Events

The SSU-2000 has extensive event detection, reporting, and alarm generation and storage capabilities that permit monitoring of the system from external sites.

Alarms are conditions within the unit or at the interfaces of the unit which may indicate abnormal operation or a change in the unit's operational status. For example, an alarm may be generated when a parameter which exceeds a user-set threshold. Most alarms can be assigned by the user to one of the following modes: IGNORE, REPORT, MINOR, MAJOR, or CRITICAL.

All Alarms detected in the SSU-2000 system are reported by three methods, including:

- Display on the module LEDs
- Relay contact closures on the back of the SSU-2000 main shelf
- Messages transmitted on all communications ports

All Alarm indications clear when the condition(s) that caused them no longer exist. In a case where a module in alarm is unplugged from the system, a command must be issued to clear the module's active alarms. In addition, normal operating status is indicated by green LEDs on the modules.

Events are conditions within the unit, or at the interfaces of the unit, which may indicate abnormal operation or a change in the unit's operational status. Recurring events may be escalated to alarm status and may require action by the user. Conversely, alarms may be de-escalated and corrected automatically. See the Config command in Appendix B, Communications Protocol.

Although every alarm is considered to be an event, not every event is an alarm. For example, a login is recorded as an event but is not considered to be an alarm. In this case, no action is required by the user.

## Ignore Mode

IGNORE means that appropriate information on the event is transmitted on all of the communications ports when the event occurs, and on demand, but no alarm is generated. For example, the status of the SSM at each input port and at the output ports is reported when it changes and when the user sends an inquiry but no alarm is generated.

## Report Mode

The REPORT mode option is used to report alarm indications only.

An ALARM command is available in the SSU-2000 that allows a user to view the current status of alarm indications on the unit and set alarm delay intervals and activation levels. Only active alarm indications are displayed unless an option is specified.

The DELAY option sets the length of time in seconds an alarm must be active before generating a hardware indication. This option also allows the user to set the level of any alarms:

- IGNORE - ignore any alarm indication
- REPORT - report only alarm indications
- MINOR - sets alarm level to MINOR
- MAJOR - sets alarm level to MAJOR
- CRITICAL - sets alarm level to CRITICAL

See Appendix B, Communications Protocol, for information on the DELAY option.

## Alarm Mode

The user sets an alarm to one of three levels of alarm severity: MINOR, MAJOR or CRITICAL. In general, events which are classified as ALARMS are those for which user intervention is required. MINOR and MAJOR alarms can be elevated automatically to the next higher level after a user-set time period.

The unit is capable of generating reports to include: local oscillator being switched, log in/out, restart, board removed/inserted, events cleared, PLL loop control, user image clear/set, phase samples, frequency control, and a keep alive output every 5 minutes. See Appendix B, Communications Protocol, for information on commands.

Alarms and all events are reported over the communication ports and contain details of the event in a single message including the time of the event. All ALARM indications clear when the conditions that caused them no longer exist. In addition, normal operating status is indicated by green LEDs on the front panel of modules.

## Fail Mode

In the FAIL mode, the SSU-2000 removes the failed module from service or usability to prevent interruption of the system. For example, a FAIL event detected in Clock A causes a switchover from Clock A to Clock B, effectively removing Clock A from the system. The FAIL event is reported on all communications ports and an alarm is generated.

### 2.3 System Components

The fully expanded SSU-2000 system contains the following physical components:

- SSU-2000 Main shelf populated with various combinations of Clock, Input, Output and Communications modules
- Input and output adapter panels
- Up to four SDU-2000 Expansion shelf containing buffer and output modules

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For additional information about each of the module types, see Chapter 8 of this manual. See Chapter 9 for component part numbers and guidelines for configuring a new system.

### 2.3.1 SSU-2000 Main Shelf (Chassis)

The SSU-2000 main shelf (shown in Figure 2-6) contains a metal chassis and a motherboard with provisions for supporting up to 12 hot-plugable modules. Filler panels are available for use in shelves that are not fully populated.

## Module Assignments

All SSU-2000 modules are equipped with card ejectors and plug in from the front of the shelf. Each module is secured in the shelf with captive fasteners. The module assignments for the SSU 2000 main shelf are listed in Table 2-1 and are shown Figure 2-7.

Table 2-1. Module Slot Locations

| Slot | Module |
| :--- | :--- |
| A1 | Clock Module A |
| A2 | Communications Module |
| A3-A5 | Input Module |
| A6-A11 | Output Module |
| A12 | Clock Module B |



Figure 2-6. SSU-2000 System Components


Figure 2-7. SSU-2000 Module Shelf Slot Assignments
As indicated in Figure 2-7, the SSU-2000 modules are assigned slots A1 through A12, numbered left to right as viewed from the front of the shelf. The first or left-most slot, A1, is assigned to the primary clock module (Clock A). Slot A2 is assigned to the Communications module and slots A3 through A11 are assigned to various combinations of input modules and output modules. Slot A12 is reserved for the B clock module.

## Main Shelf Connections

The back of the main shelf contains the connection terminal strips, BNC connectors, and SCSI-II connectors that are used to connect the SSU-2000 to other system components. These connection features are called out in Figure 2-8.


Figure 2-8. SSU-2000 Main Shelf, Rear View
The SSU-2000 main shelf connection features include:

- I/O connectors (I/O-1 through I/O-9)- 50-Pin, Micro-D female connectors (SCSI-II type) used for connecting the I/O adapter panels to the SSU-2000. Each I/O connector is associated with a specific I/O module slot. I/O adapter panels are available to convert the 50-Pin, Micro-D female connectors to telecommunications standard Balun (balanced/unbalanced) or DE9 connectors, see Chapter 8 for additional details
- Dual set of power terminals and dual set of grounding lugs for connecting external power and grounding to the SSU-2000 system
- Three communications ports including two serial port connections (Serial Port-A and Serial Port-B) and one RJ-45 Ethernet connector (Ethernet 10-Base-T). Another serial communication port is also available on the front of the Communications module
- DTE/DCE switch is a 2PDT slide switch (S1) that allows the user to select either DTE or DCE type of serial port interface.
- Reference inputs and clock outputs
- Local and remote alarm contact closures divided into three classes:
- CRITICAL Alarms - Indicate an immediate service affecting condition that requires immediate user intervention (such as loss of Communications module, loss of input power to the shelf, etc.). When a critical alarm condition is detected, the CRITICAL ALARM relay is activated (alarm condition) and the CRITICAL ALARM LED on the front of the Communications module lights red unless power was interrupted. In this case the unit no longer has power.
- MAJOR Alarms - Indicates a condition that may require immediate user intervention. When a major alarm condition is detected, the major alarm relay at the back of the SSU-2000 is activated and the MAJOR ALARM LED on the front of the Communications module lights red.
- MINOR Alarms - Indicate the unit performance is degrading. The minor relay is activated and the MINOR ALARM indicator lights.
- Two local oscillator connections - Local OSC-A and Local OSC-B are normally used as outputs to feed other equipment but can also be used as inputs when the shelf is configured with plug-in modules as a monitor only.
- Two antenna connectors - used to attach Radio Receiver antennas
- Interface connector for the optional SDU-2000 Synchronization Distribution Unit (output signal expansion system). Up to four expansion shelf can be connected in daisychain fashion to an SSU-2000 shelf. A termination plug must be installed on this connector if not using the expansion shelf.
- SDU Backup Clock (D-clock) that can be used in the expansion shelf in the event of the loss of clock A or B. The shelf also has optional rack mounting ears for mounting in 19 inch EIA, 23 inch EIA and AT\&T, and ETSI racks and cabinets.


## Main Shelf Power Distribution

The main shelf accepts redundant -48 vDC power inputs from external supplies and makes these inputs available to the modules via the motherboard connectors anytime the 5-Amp fuses are installed on the rear of the SSU-2000 main shelf.

An On/Off switch is not provided which prevents anyone from accidently shutting down the system. To shut down the system, the two fuses (Power Supply A and Power Supply B fuses) must be physically removed from the back of the shelf. If only one fuse is removed, the system senses the loss of the power input and switches to the second power input.

All power supplies for the SSU-2000 are implemented on the individual modules which increases system availability by eliminating a single point of failure in the power supply area. On each plug in module, diodes combine the two power sources and provide protection from reversal of the power connections on the shelf ( + and - reversed). Screw type lugs on the rear of the shelf are used for logic and shelf ground connections.


## Antenna Connectors

The SSU-2000 contains two TNC connectors to allow for connection of a radio antenna. These antenna connectors are wired into I/O slots A3 and A5 (the only slots that can be used for installing a Radio input module). A variety of GPS antennas are available as accessories for the SSU-2000, see Appendix C, Antennas.

### 2.3.2 Main Shelf Communication Ports

The SSU-2000 main shelf contains four communication ports including:

- Two RS-232 communication ports (Port A and Port B) on the back of the main shelf
- One RS-232 port on the face of the Communications module (Port C)
- One RJ-45 Ethernet connector on the back of the SSU-2000 (Ethernet 10-Base-T) for network connection

A user interface (software resident in the Communications module) provides various levels of password-protected access for configuration, detailed performance monitoring, and diagnostics. Refer to Appendix B, Communications Protocol for more information on configuration and detailed performance monitoring. Remote EIA-232-C ports can be assigned their own interface type, either Interactive or TL1 that is retained in NVRAM. The Local port (Port C on the Communications module) is always in Interactive mode when the Communications module restarts. Refer to Table 2-2 for the communications port assignments.

Table 2-2. Communications Port Assignments

| Port \# | Function | Protocol |  |  |
| :---: | :--- | :--- | :---: | :---: |
| Serial Ports (RS-232) |  |  |  |  |
| A (J4) | This port is user selectable as either an ICS or a TL1 interface. <br> The port defaults to ICS upon initialization | ICS (Default), TL1 |  |  |
| B (J5) | This port is user selectable as either an ICS or a TL1 interface. <br> The port defaults to ICS upon initialization | ICS (Default), TL1 |  |  |
| Local <br> (Comms <br> Module) | This port is user selectable as either an ICS or a TL1 interface. <br> The port defaults to ICS upon initialization | ICS (Default), TL1 |  |  |
| Ethernet Ports (TeInet) |  |  |  |  |
| 23 | This port is user selectable as either an ICS or a TL1 interface. <br> The port defaults to ICS upon initialization | ICS (Default), TL1 |  |  |
| 123 | This port is designated for NTP only | NTP |  |  |
| 161 | This port is designated for SNMP Interactive | SNMP Interactive |  |  |
| 162 | This port is designated for SNMP Trap transmission | SNMP Trap |  |  |
| 2000 | This port is designated for TL1 only | TL1 |  |  |

Table 2-3 shows the RS-232 Connector pin assignments for the SSU-2000 DE9 communications connectors.

Table 2-3. RS-232 Connector Pin Assignments

| Signal | Pin | Pin | Signal | Connector Orientation DE9S |
| :---: | :---: | :---: | :---: | :---: |
| FG | Shield | 5 | Logic Return |  |
|  | 9 | 4 | DSR |  |

Table 2-3. RS-232 Connector Pin Assignments

| CTS | 8 | 3 | TXD |  |
| :--- | :--- | :--- | :--- | :--- |
| RTS | 7 | 2 | RXD |  |
| DTR | 6 | 1 | DCD |  |

### 2.3.3 Main Shelf Power Connections

The SSU-2000 main shelf contains provisions for connecting redundant -48 vDC external power inputs (designated A and B input power). The power supplies, located on the internal modules, can accept input power in the range of -37 to -72 vDC .

Each power input to the main shelf is accomplished using a 2-connection terminal strip, with the negative side fused. Both connections are isolated from frame and signal grounds.In the event of the loss of either the A or B input, the system senses the loss of power, reports the loss of the power input and continues normal operation on the remaining power input. If both power supply inputs are lost, the Critical Alarm relay de-energizes to the alarm state and a Critical alarm is reported.

## Main Shelf Frame/Logic Grounds

Screw type lugs on the rear of the shelf are used for logic and shelf ground connections. Grounding for integrated or isolated ground planes are supported by two user-configured hardware straps.

### 2.3.4 SSU-2000 Family of Modules

The SSU-2000 family of modules includes the following:

- Stratum 2E Clock Module
- Stratum 3E Clock Module
- Communications Module
- 1-Port and 3-Port E1 Input Modules
- 1-Port and 3-Port DS1 Input Modules
- GPS Input Module
- 2048 kHz Output Module
- E1 Output Module
- DS1 Output Module
- Composite Clock Output Module

Some of the common module features include:

- Any module can be inserted or removed while power is applied without affecting the operation of other modules in the system.
- All modules are individually fused to protect the system in case of a short circuit on any one module.
- All modules have front panel status LEDs.
- All modules are equipped with ejector tabs for ease of installation and removal and secured in place with captured screws to provide module security and reduce the occurrence of unauthorized removal.
- All SSU-2000 modules have an integrated CPU with firmware and are software configurable.

Each module slot also has three pins connected together on its assigned Hybrid DIN connector which permits the system to detect when a particular module is removed. More information is available for each of these modules in Chapter 8, Module Reference Data.

### 2.3.5 Stratum 2E Clock Module

The Stratum 2E Clock Module uses a Rubidium oscillator and meets the requirements of ANSI and Telcordia Industries (Bellcore) for Stratum 2 clocks. This clock also meets the ITU-T and ETSI specifications for Type II Transit Node clocks.

The module reads measurement data from the input modules, provide frequency control of its oscillator through DDS circuitry, and generates a reference signal used by the input and output modules. The clock module also maintains phase synchronization with the redundant clock module.

### 2.3.6 Stratum 3E Clock Module

The 3E Clock module meets or exceeds performance requirements for ANSI and Bellcore Stratum 3E and ITU and ETSI Type III Local Node clocks.

The Stratum 3E Clock Module reads measurement data from the Input modules, provide frequency control of the oscillators through DDS circuitry, and generates a reference signal used by the Input and Output modules. The Clock module maintains phase synchronization with the redundant Clock module. Its hardware and software also provides for temperature compensation, aging compensation for quartz oscillators, an initial offset adjustment, and frequency adjustment resolution of $1 \times 10^{-13}$ or better.

### 2.3.7 Communications Module

The Communications module serves as the user interface to the SSU-2000. The module command interface supports three EIA-232-C connections and one Ethernet interface for communication with the SSU-2000 system. This module also logs the unit events into non-volatile memory for inspection at a later date and reports alarms as they occur.

### 2.3.8 1-Port and 3-Port DS1/E1 Input Modules

The DS1 and E1 Input Modules are available with both 1-Port and 3-Port configurations. These modules receive signals and perform phase measurement comparisons with the Clock modules that are installed in the SSU-2000. The Clock modules use this information to phase and frequency lock to the incoming signal. The data may also be used for monitoring the frequency of incoming signals.

The DS1 and E1 Input modules accept the following signals: sine or square wave (with frequency of $1,1.544,2.048,5$ or 10 MHz ) or framed communications type DS1 or E1. If the input signal is a communications type, the module monitors the following errors:

- Alarm Indication Signaling (AIS)
- Bipolar Violations (BPV)
- Loss of Signal (LOS)
- Out Of Frame (OOF)
- Cyclic Redundancy Check (CRC)

The module also extracts Synchronization Status Messages (SSM) from incoming data.

### 2.3.9 GPS Input Module

The GPS Input module is a one-port card that can be installed in the SSU-2000 unit. The module is used in the SSU-2000 main shelf to correct the frequency of the oscillator on the Clock module. It monitors and reports the status and performance of the module and radio signals that it receives.

### 2.3.10 2048 kHz Output Module

The 2048 kHz Output module plugs into selected input/output slots in the SSU-2000 main shelf or one of the output slots on the expansion shelf. The module generates and monitors 20 independent 2048 kHz signals that are referenced to a selected clock module. The 2048 kHz Output module receives a set of three (four if installed in an expansion shelf) 4 kHz clocks from the Clock modules and uses these clocks to develop an 8.192 MHz phase-locked signal. This phase-locked signal is then used to generate 20 sets of 2048 kHz clock outputs

### 2.3.11 E1 Output Module

The E1 Output module uses one of three 4 kHz clocks from the SSU-2000 main shelf backplane to generate a phase-locked signal of 2.048 MHz . If the unit is inserted into an SDU-2000 expansion shelf, a fourth 4 kHz clock ( D clock) is available. The phase-locked 2.048 MHz signal is used to generate a set of 20 output signals for distribution to large networks.

### 2.3.12 DS1 Output Module

The DS1 Output module generates a phase-locked signal of 1.544 MHz using one of three 4 kHz clocks from the backplane of the SSU-2000 main shelf. If the module is inserted into the SDU-2000 Synchronization Distribution Unit (expansion shelf), a fourth 4 kHz clock is available. The phase-locked signal generates a set of 20 output signals for distribution to large networks.

### 2.3.13 Composite Clock Output Module

The Composite Clock (CC) Output module can be installed in the SSU-2000 unit to generate and monitor CC signals, monitor input reference signals, accept new configuration data, and report status. This module provides 20 signal pairs (TTIP and TRING signal pairs), which are referenced to the selected clock signal.

## Output Module Redundancy Configurations

For an A/B pair of Output modules (in a redundancy configuration), it is possible to connect all of the outputs of Module B to the corresponding outputs of Module A, providing 1:1 output protection (1:1 redundancy). Figure $2-10$ shows the SSU-2000 input/output connectors.

This requires the use of a user-installed Output Summer connector. Using this connector, you can configure Output pairs I/O-2-I/O-3, I/O-4-I/O-5, I/O-6-I/O-7, and I/O-8-I/O-9 in redundant mode. See Section 3.5.2, Output Module Redundancy Configurations for more information on making redundant connections.


Figure 2-10. SSU-2000 Input/Output Connectors

### 2.3.14 Input and Output Adapter Panels

All Input and Output module signals connect to/from the back of the main shelf (and expansion shelf) using 50 -pin SCSI II type connectors.

The adaptation of signals from 50-pin SCSI connectors to conventional BNC (Balun) and 9-pin Dsub connections is accomplished using input and Output Adapter panels (I/O adapter panels) that install in the rack either directly above or directly below the main or one of four possible expansion shelf.

All SSU-2000 connections are made on the back side of the adapter panels and the customer's telecommunications system connections are on the front of the adapter panels.

There are four adapter panels available for use with the SSU-2000 Input and Output modules including:

- Input I/O adapter for 3-port Input modules (DS1 or E1) - one adapter panel is required for each 3-port Input module used in the system.
- Input I/O adapter for 1-port Input modules (DS1 or E1) - one adapter panel serves up to four 1-port Input modules.
- Output I/O adapter for Output modules ( $\mathbf{7 5} \mathbf{~ o h m}$ Balun Outputs) - one adapter panel accommodates one output module (non-redundant) or one pair of redundant modules.
- Output I/O adapter for Output modules (D9 outputs) - one adapter panel accommodates one Output module (non-redundant) or one pair of redundant modules.

These adapter panels are shown in Figure 2-11 and described in greater detail in Chapter 8, Module Reference Data.

ss200018
I/O Adapter for 3-Port Input Module



75 Ohm Balun I/O Adapter for Output Module


DE9 I/O Adapter for Output Module
Figure 2-11. I/O Adapter Panels for Input and Output Modules

### 2.4 Communications Protocol

This section summarizes the methods of controlling the SSU-2000 and the available software features, depending upon the system functionality required.

### 2.4.1 Software Interface

There are three methods of controlling the SSU-2000. The three control interfaces available are:

- TL1 - The Transaction Language One (TL1) control language, a telecommunications industry ASCII command line interface, provides a standard man-machine language.
- ICS - The Interactive Command Set (ICS) control language provides a more readable ASCII command line interface than TL1 with an instructional help facility.
- SNMP - The Simple Network Management Protocol (SNMP) protocol is based on a client server query-response mode.


### 2.4.2 Software Versions

There are four different versions of software available for the SSU-2000, as indicated in Table 2-4. The functionality and commands that are available vary from one version of software version to the next, depending on the specific features of the software package and are described in Appendix B, Communications Protocol.

Table 2-4. Communications Module Software Versions

| Part Number | Version | TL1 | ICS | NTP | SNMP |
| :--- | :--- | :---: | :---: | :---: | :---: |
| $24113012-000-0$ | Basic System Load | X | X |  |  |
| $24113012-001-0$ | Basic w/NTP Support | X | X | X |  |
| $24113012-002-0$ | Basic w/SNMP Support | X | X |  | X |
| $24113012-003-0$ | Basic w/SNMP \& NTP Support | X | X | X | X |

### 2.4.3 Basic System Load

The basic system load includes all TL1 and ICS support software.

- TL1 provides command sets to support all operation, administration, maintenance, and provisioning tasks required to maintain and control an SSU-2000 system. These tasks include configuring and provisioning security, monitoring system performance, configuring hardware, locating and handling faults, and performing equipment diagnosis and testing. Refer to Section B.2, TL1 Command Interface, for more information.
- ICS also provides command sets to support all operation, administration, maintenance, and provisioning tasks required to maintain and control an SSU-2000 system from a terminal connected to one of the SSU-2000 RS-232 serial ports. ICS commands are designed in a more readable interface for users with an instructional help facility. Refer to Section B.3, Interactive Command Set, for more information.


### 2.4.4 Adding NTP Support

The Network Time Protocol (NTP) is used to synchronize the time of a computer client or server to another server or reference time source, such as a GPS receiver or local timing source.

The SSU-2000 implements the NTP v. 3 (RFC 1305) version. It can run as a server application and a client application. In addition, a broadcast mode may be implemented as either a server or client. The NTP server always runs and the client and broadcast modes are enabled independently by assignment of addresses and setting of timers. Refer to Section B.4, NTP Support, for more information.

### 2.4.5 Adding SNMP

The Simple Network Management Protocol (SNMP) protocol is based on a client-server queryresponse mode. A manager is the client generating the queries, while an agent is the server generating the responses.

The SSU-2000 SNMP is an SNMP V2 agent that requires Ethernet connectivity. If SNMP is present, port 161 becomes the port of standard SNMP interactive communications, while port 162 becomes the trap port. Since the SSU-2000 SNMP supports all exiting functions, full system control of the SSU-2000 is maintained through SNMP.

The SSU-2000 implements an SNMP agent. A Management Information Base (MIB) Browser or the SNMP Manager is used to access, retrieve, and query information defined by the MIB.

All reports, queries, autonomous messages, control, provisioning, and administration (except for communication port parameters, Set User ID/Password, Set IP assignments, Reset connection, and SNMP community settings) are available through SNMP. Refer to Section B.5, SNMP Protocol, for more information.

### 2.4.6 Graphical User Interface

SynCraft - This is a software interface program that is available to provide monitoring and configuration functionality in a Microsoft Windows graphical user interface. Contact your Datum Sales Representative for more information on the SynCraft Graphical User Interface, P/N 14113245-000-0.

For more information on control interfaces and the software commands available for each, see Appendix B, Communications Protocol.

### 2.5 Operation Overview

After initial installation and configuration is completed, the SSU-2000 is capable of unattended operation. After power-up, where the external power supplies are turned on so that they supply power to the main shelf, the SSU-2000 performs a self-diagnostic test routine and properly initializes the hardware. Any active Alarms are time tagged and reported as Events. All Events are time tagged and the last 500 Events are stored in NVRAM. All Events can be cleared by the user with the appropriate access level. Several optional levels of password protection are available for system protection as described in Chapter 4, Turn-Up Procedures.

After the internal oscillators on any installed Clock modules have warmed up, the SSU-2000 enters the ACQUIRE mode to phase lock the oscillators to the external references. After the SSU2000 reaches the LOCKED mode on at least one of the Clock modules, any change of state is reported as an Event.

### 2.6 Indicators and Controls

All modules installed in the SSU-2000e main shelf and the SDU-2000e expansion shelf contain status indicator lamps for displaying status. The LED indicators for each module are described in Chapter 8, Module Reference Data. In addition, the Communications module collects status information from all installed modules, sets the alarm relays, and sends communications status alerting users of any Events that exceed alarm thresholds.

### 2.7 SDU-2000 Synchronization Distribution Unit

Up to four SDU-2000 Synchronization Distribution Units (expansion shelves) can be attached to the SSU-2000 for output expansion (Figure 2-12 and Figure 2-13). Each expansion shelf contains two Buffer modules and 14 output modules (can be a combination of output modules). Four expansion shelves can hold as many as 56 Output modules capable of generating an additional 1120 synchronized clock outputs for system distribution. Each expansion shelf is connected to the main shelf with redundant clock cables to protect against cable faults.

ss200022
Figure 2-12. SDU-2000 Expansion Shelf Front View
The expansion chassis is designed to be compatible with international environmental, safety and electromagnetic compliant (EMC) standards for $-48 / 60 \mathrm{vDC}$ powered telecommunication transmission equipment installed in telecommunication centers with inside telecom signal connections. The farthest expansion chassis may be located up to 61 meters from the SSU-2000 main shelf.


Figure 2-13. SDU-2000 Expansion Shelf Rear View
Figure 2-14 shows a simplified functional block diagram of the SDU-2000 expansion chassis.


Figure 2-14. SDU-2000 Block Diagram

### 2.7.1 Functional Overview

The SDU-2000 interfaces with the SSU-2000 main shelf in two-way communications through the SSU/SDU interface cables and receives synchronization clocks that are buffered and used to produce the differential output signals at the connector panel, as shown in Figure 2-14. A second interface cable supplies the SDU-2000 chassis with a backup clock (D Clock) which can sustain the expansion shelf even if the main cable is accidently disconnected. An address switch on the connector panel of the expansion shelf identifies each additional shelf to the main shelf for status and firmware downloading purposes.

Each expansion shelf extends the expansion bus and D clock to the next chassis in the daisy chain. The last expansion shelf uses a set of termination plugs on the Expansion Bus Connector and the Backup-Clock Connector.

Each expansion shelf can support any combination of up to ten 2048 kHz , Composite Clock (CC), or framed $2048 \mathrm{kbit} / \mathrm{s}$ (E1) or DS1 modules, each capable of generating 20 output signals for distribution to large networks. Each Output module generates a phase-locked signal of 1.544 Mbps (DS1) or $2048 \mathrm{kbit} / \mathrm{s}$ (E1) using one of three 4 KHz clocks supplied by the clock oscillators in the SSU-2000e main shelf. The phase locked clock signal is buffered and summed with a companion Output module in redundant pairs to generate a set of 20 independent output clock signals for distribution to large networks.

Output modules are available to support the following formats:

- $2048 \mathrm{Kbit} / \mathrm{s}(\mathrm{E} 1)$
- DS1, SF (D4) and ESF
- 2048 kHz

■ Composite Clock ( $64 / 8 \mathrm{kHz}$ )

### 2.7.2 Expansion Shelf Features

The SDU-2000 expansion shelf consists of the following major components.

- Expansion chassis
- One or two Buffer Modules; where two provide a more robust system
- Up to 10 Output modules, which can be a combination of Output module types

Connector panel with five groups of output connectors, SDU interface connector group, dual power connectors, dual frame ground connectors, and a shelf address switch.

### 2.7.2.1 Clock Source

The clock inputs for the first SDU-2000 expansion chassis in an SSU-2000 system are supplied by the A and B Clock modules in the main chassis. A multi-pin connector on the front panel of the SSU-2000e (labeled J8 EXPANSION) provides the reference signals from the main shelf Clock modules for use by the SDU-2000e expansion shelves.

### 2.7.2.2 SDU Backup Clock

For redundancy, a backup clock labeled SDU BACKUP CLK is supplied to each expansion chassis to allow each expansion chassis to continue operating if the main expansion bus (cable) is accidently disconnected or dislodged.

The SDU Backup Clock terminals, labeled J104 and J106, are 9 pin D-type female connectors that are connected in parallel. Connector J104 is used to connect to a source unit, such as the SSU-2000, or to connector J106 on another expansion shelf. Connector J106 drives an additional SDU-2000 shelf, or it is terminated using an SDU backup clock terminator, as shown in Figure 2-15.

When installing an expansion chassis, move the clock terminator from J9 on the SSU-2000e or connector J106 from a previous SDU-2000 expansion chassis, and install the terminator on J106 of the last expansion chassis in the daisy chain.


Figure 2-15. Backup Clock Terminator, Side and Front Views

### 2.7.3 Expansion Shelf Addressing

Each SDU-2000 expansion chassis must be correctly configured for its position in the daisy chain. The main shelf's address is one. The SDU shelf address selector is numbered from two to five. Set the first expansion shelf address to two. Set the address on additional shelves sequentially from three to five.

Table 2-5. Shelf Addressing

| Shelf | Address |
| :--- | :---: |
| Main Shelf | 1 |
| Expansion Shelf 1 | 2 |
| Expansion Shelf 2 | 3 |
| Expansion Shelf 3 | 4 |
| Expansion Shelf 4 | 5 |

### 2.7.4 Buffered Clocks

The signals that are provided by the main shelf Clock modules to the buffer modules in the expansion shelf are isolated versions of the signals used by the Output modules in the main chassis. This prevents the expansion shelf and its cabling from affecting the outputs of the main shelf.

### 2.7.5 SDU Module Features

The SDU-2000 expansion chassis family of modules include the E1 Output module, DS1 Output module, 2048 kHz Output module, Composite Clock module, and Buffer modules. The SDU-2000 expansion chassis can have up to 12 modules installed.

- One or two Buffer modules, assigned to chassis slots A15 and A16
- One to ten Output modules; a mixture of Output module types, where each group of two modules must be identical

The last two module slots in the expansion shelf, labeled A15 and A16, contain the Buffer modules that buffer the corresponding Clock and Communications modules in the main unit. The buffered signals from these modules are distributed through the motherboard to 10 Output modules.

Other common module features include:

- Any module can be inserted or removed while power is applied without affecting the operation of other modules in the system
- All modules are individually fused to protect the system in case of a short circuit on any one module
- The SSU-2000 and the SDU-2000 share common Output modules
- All modules have front panel LED status indicators
- All modules are equipped with ejector tabs for ease of installation and removal
- All modules are secured in place with captive screws to provide module security and reduce the occurrence of unauthorized removal
- All modules, except the Buffer module, have an integrated CPU with firmware and are software configurable through the SSU-2000, see Section 9.1, Configuring a Conventional SSU/TSG System, for additional information
- Each module slot has two associated hybrid DIN connectors on the chassis backplane. The hybrid contacts of these connectors are used for Power, Logic Ground, and Frame Ground connections
- Each module slot has three pins connected together on each hybrid DIN connector that allows the system firmware to detect module removal and insertion. This capability provides plug-and-play capability.


### 2.7.6 Connector Panel Features

The expansion chassis provides connections for external power, grounding, clock inputs, and output connections. All modules plug in from the front of the chassis.

### 2.7.7 Controls and Indicators

All modules installed in the SDU-2000 expansion shelf contain LED status indicators for displaying status. Any faults from the installed modules are sent to the SSU-2000
Communications module through the buffer modules; the appropriate alarm relays are set and communication status is sent to alert users of any events that exceed specified alarm thresholds.

Table 2-6 lists the system-level specifications for the SDU-2000.

## Table 2-6. SDU-2000e System Specifications

| Specification | Description |
| :---: | :---: |
| System Specifications |  |
| Architecture | - 2 Buffer modules and 10 mixed Output modules <br> - Expansion drive for up to three additional expansion chassis <br> - Maximum of four expansion shelves per system <br> - Maximum of 61 meters between the SSU-2000e and the farthest expansion chassis |
| Output Section |  |
| Port | - 20 Ports per Output module pair |
| Distribution Capacity | - 100 summed outputs per chassis |
| Signal Type | - DS1 <br> - $2048 \mathrm{Kbit} / \mathrm{s}(\mathrm{E} 1)$ <br> - $1 \mathrm{MHz}, 1.544 \mathrm{MHz}, 2.048 \mathrm{MHz}$ (G703/Sec. 13) <br> - 5 MHz <br> - Composite Clock (CC) |
| Expansion Chassis Mechanical |  |
| Height | 500 mm |
| Depth | 229 mm |
| Width | 530 mm with mounting ears for ETSI racks/cabinet |
| Environmental |  |
| Operating Temperature Range | $0^{\circ} \mathrm{C}$ to $50^{\circ} \mathrm{C}$ |
| Storage Temperature | $20^{\circ} \mathrm{C}$ to $75^{\circ} \mathrm{C}$ |
| Relative Humidity | 80\% Non-condensing over specified temperature range |
| Altitude | 60 m below sea level to 4000 m above sea level |

## Table 2-6. SDU-2000e System Specifications (Continued)

| Specification | Description |
| :--- | :--- |
| Power |  |
| Input Power | - Redundant Inputs: <br> 38 to 72 vDC, 3.0 A (maximum) <br> +0.1 A per Distribution Module <br> - Either positive or negative ground |
| Grounds | -48/60 V return DC Isolated from frame and logic grounds. Integrated frame <br> and logic ground. |
| Power Connections | A-BUS and B-BUS (-48/60 vDC) Input power connectors (J101 and J102) on <br> opposite sides of the connector panel. |

# In this Chapter ... <br> - Unpacking and Inspection <br> - Preliminary Procedures <br> - Rack Mounting the SSU-2000 <br> - Grounding and Power Input <br> - Connections <br> - Alarms <br> - Antennas <br> - SDU Interface <br> - Remote Reset <br> - Module Insertion <br> - Handling Modules <br> - Installation Checklist 

## Chapter 3 Installation

This chapter provides guidelines and procedures for installing the SSU-2000 Synchronization Supply Unit; these guidelines and procedures are divided into the following sections.

- Section 3.1, Unpacking and Inspection provides instruction and precautions required for unpacking and inspecting the system. Section 3.2, Preliminary Procedures, includes a pre-installation list of considerations for installing the system.
- Section 3.3, Rack Mounting the SSU-2000, and Section 3.11, Handling Modules, provides instruction for installing a complete system.
- Section 3.12, Installation Checklist, completes the system installation procedure.


### 3.1 Unpacking and Inspection

The SSU-2000 is packaged to protect it from normal shock, vibration and handling damage. Care should be taken during unpacking and installation to avoid damaging the unprotected unit.
CAUTION...
Use proper static control precautions when handling modules!
Protect the equipment against ESD (Electrostatic Discharge) by
using a grounded protective wrist strap and normal equipment
grounding.

1. Unpack all equipment carefully and check it against the purchase order.
2. Inspect the equipment for shipping damage, including bent or loose hardware, broken connectors, or other visible defects. Notify Datum and the carrier who delivered the equipment if you suspect that it was damaged in transit.

If any items are missing, contact Datum Customer Service at (512) 721-4032 or (866) 638-7962 (866 NET-SYNC) during our normal business hours (8 a.m. to 5 p.m. CST).

## Recommendation ...

Keep all packaging materials in the event the system or components must be returned or shipped to another location.

### 3.2 Preliminary Procedures

Make sure that the following preparations are in place before installation.

- Ensure that standard installation tools and materials are available, see Section 3.2.1, Installation Tools and Materials.
- Ensure system location does not cause electromagnetic interference with other equipment in the area, see Section 3.2.2, Electromagnetic Interference (EMI) Considerations.
- Ensure adequate ventilation space is available in rack or equipment cabinet to safely operate system, see Section 3.2.3, Ventilation Considerations.
- Ensure that the mounting rack or equipment cabinet is properly grounded and has power available, see Section 3.4.1, Making Ground Connections



## Warning...

Before beginning the SSU-2000 installation, be sure to remove the A-BUS and B-BUS fuses from the rear of the unit. The unit is not equipped with a power on/off switch and both fuses must be removed to ensure the system is not accidentally powered up.


### 3.2.1 Installation Tools and Materials

The following required standard tools and materials (not supplied) are required for installing the SSU-2000:

- Standard tool kit
- Cable ties or acceptable cable clamps
- 16 AWG (minimum) wire for -48 V , RTN, and frame ground
- 18 AWG wire for connecting office alarms

■ 22 AWG shielded twisted pair wire-wrap cable (Amp \#640433-7 or equivalent)

- Wire-wrap tool
- No. 10 screws, flat washers, and locking washers for mounting the equipment rack
- Digital Voltmeter
- Straight-through RS-232 cable
- Laptop or PC with a terminal emulation program such as HyperTerminal or ProComm Plus


### 3.2.2 Electromagnetic Interference (EMI) Considerations

Electromagnetic Interference (EMI) from one instrument can adversely affect the operation of nearby equipment. To prevent the SSU-2000 from interfering with other equipment, it must be installed and operated as described in the following paragraphs.

All cables connected to the SSU-2000 should be shielded with metal connector shells. The connectors on the rear of the chassis are shielded, with the shields connected to frame ground. Follow local procedures for shield grounding. The screws on all cables must be securely fastened to their corresponding connectors on the rear of the unit. While the unit is in operation, there must be a module or blank panel installed in every slot. Also, the captive screws, located at the top and bottom of the module panel, must be properly secured.

Caution...

To maintain EMC compliance, use only properly shielded cabling on all telecom signal wiring, including I/O, clocks, and Ethernet connections. Ensure that connections are appropriately grounded at both ends.

### 3.2.3 Ventilation Considerations

There should be at least 3 inches $(7.6 \mathrm{~cm})$ of free space below the bottom chassis.


## Caution ...

To avoid excessive heat build-up resulting in equipment damage, provide proper ventilation and cooling of the equipment.

### 3.3 Rack Mounting the SSU-2000

The SSU-2000 chassis, when installed, occupies 10.5 in ( 26.7 cm ) of vertical rack space, has a depth of 12 in ( 30.5 cm ), and a width of $19 \mathrm{in}(48.26 \mathrm{~cm})$. When installing more than one SSU2000, each unit must have at least one inch $(2.5 \mathrm{~cm})$ of clearance above and below to ensure proper cooling. There should be at least three inches $(7.6 \mathrm{~cm})$ of free space below the bottom chassis. It is recommended that at least one I/O adapter panel be inserted between each unit.

## CaUtion...

Failure to provide proper ventilation can result in excessive heat build-up resulting in equipment damage. It is recommended an I/O adapter panel be inserted between chassis. See Figure 3-1.

### 3.3.1 SSU-2000 Chassis

The shelves mount flush to the rack or at distances of 2 inches ( 5.1 cm ) or 5 inches $(12.7 \mathrm{~cm})$ from the front of the rack. An SSU-2000 rack mounting diagram is shown in Figure 3-1.

1. Attach a mounting bracket to each side of the chassis by aligning two columns (three holes per column) of the bracket with the holes on the side of the chassis. Use suitable screws for attaching the mounting bracket. Ensure that both brackets are attached at equal distances from the front of the unit.
2. Mount the instrument to the front of the rack rails with the appropriate number of screws and washers for the rack.
3. If not using expansion shelves, verify that the Bus Termination Assembly is inserted into J9 of the main shelf.


Recommendation...
When possible, attach chassis at eye level to aid in viewing and connecting cables.

### 3.3.2 I/O Adapter Panels

The procedure for attaching the four types of I/O adapter panels to the rack are identical. The location of the I/O adapter panels is limited only by the length of the interconnecting cable. Input adapter cables are restricted to one meter. Output adapter cables are available in lengths from one to two meters in increments of 0.1 meter, see Section 9, Hardware Configuration Guide, for part numbers.

1. The I/O adapter panels may be mounted flush the top or bottom of the chassis. Use suitable screws for attaching the I/O adapter. Ensure that both brackets are attached at equal distances from the front of the unit.
2. Mount the panels to the front of the rack rails with four screws and washers.

## Recommendation...

Although I/O adapters may be located as necessary, it is recommended that the input I/O adapters be mounted above the chassis to accommodate the shorter cable length. Output I/O adapters should be mounted below.


Figure 3-1. Chassis and I/O Adapter Rack Mounting

### 3.4 Grounding and Power Input

The SSU-2000 shelf has redundant -48VDC power input connections labeled A-BUS and B-BUS. The A-BUS connection is a 2-position \#6 terminal block in the upper left corner of the rear panel, and the B-BUS connection is a 2-position \#6 terminal block in the upper right corner of the rear panel. The terminal positions are labeled -48 V and RTN. The -48 V side of each bus is fused with a 5 Amp fuse. The -48 V power inputs are DC Isolated from frame ground and logic ground. Both the A-BUS and B-BUS are fed to the individual module slots via the backplane. Refer to Figure 3-4 for a view of the SSU-2000 rear panel.


## Caution...

For continued fire protection, replace fuse with specified type and rating. Fuse: GMT-5 (5A @ 60vDC). This unit must be grounded. Refer all servicing to qualified personnel.
$\longrightarrow$

## $\triangle$

## Caution...

To avoid equipment damage, ensure that the power terminal covers are installed after connecting the -48 V power.

## Caution...

To provide proper I/O connector grounding, ensure that when removing or installing Summer Output connectors that all screws are tightened securely.

### 3.4.1 Making Ground Connections

After the SSU-2000 is installed in a suitable rack, the chassis must be connected to a proper earth ground.

1. Run a cable from the frame ground ( FG ) lug to earth ground.

Keep this cable as short as possible. Frame ground connections are made using two \#8-32 studs labeled FG on the lower rear panel one on each side. There are also provisions for making logic ground connections when required by a specific customers installation. These connections are labeled LG and are located next to the FG studs and are strapped together with a jumper, as shown in Figure 3-2. The jumper strap can be removed to isolate the frame and logic grounds. Logic ground is AC bypassed to frame ground by capacitor C 1 on the backplane.

## 河 <br> Note...

To isolate frame ground from logic ground, remove the two jumpers connecting Frame Ground to Logic Ground. Once the connections to LG have been opened, secure the jumpers to the back panel by tightening the FG screws. If desired, either of the LG terminals may be used to connect a separate Logic Ground cable.
2. Using a digital voltmeter, measure between the ground and chassis and verify that no voltage exists between them.


Figure 3-2. Frame and Logic Ground Jumpers

### 3.4.2 Power Input

1. Locate the power terminal blocks on the rear panel, as shown in Figure 3-3.
2. Remove both 5 A fuses.
3. Using 16 AWG (minimum) stranded wire, connect primary power to the A-BUS screws and the secondary power to the B-BUS screws. Datum recommends that you use a \#6 spade lug termination for each power lead.


Figure 3-3. Power Terminal Blocks

### 3.5 Connections

### 3.5.1 I/O Connections

The SSU-2000 shelf has I/O interface connections for connecting the SSU-2000 to the corresponding I/O adapter panels. Refer to Section 9, Hardware Configuration Guide, for information regarding the different type I/O adapter panels available and the associated cables used to connect the SSU-2000 to the I/O adapter panels. Figure 3-4 shows the rear panel of the SSU-2000. All I/O connections are made through the nine 50-Pin Micro-D female connectors, J10 through J18. Each connector is associated with a specific I/O plug-in module slot. See Table for the I/O slot connector relationship. Connectors J10 through J18 are labeled I/O-1 through I/O-9. The signal connections on these I/O connectors are set up in differential pairs as Tip and Ring connections.

ss200014
Figure 3-4. SSU-2000 Rear Panel

Table 3-1. I/O Module Slot to I/O Connector Relationship

| Label (Name) | Plug-in <br> Module Slot | I/O Connector <br> Reference Descriptor |
| :---: | :---: | :---: |
| I/O-1 | A3 | J 10 |
| I/O-2 | A4 | J 11 |
| I/O-3 | A5 | J 12 |
| I/O-4 | A6 | J 13 |
| I/O-5 | A7 | J 14 |
| I/O-6 | A8 | J 15 |
| I/O-7 | A9 | J 16 |
| I/O-9 | A10 | J 17 |

### 3.5.2 Output Module Redundancy Configurations

For an $\mathrm{A} / \mathrm{B}$ pair of Output modules (in a redundancy configuration), Output Summer connectors are required on the corresponding outputs as shown in Figure 3-5. All Module A outputs are summed with the corresponding outputs of Module B, providing 1:1 output protection ( $1: 1$ redundancy). Output pairs in slots A4/A5, A6/A7, A8/A9, and A10/A11 are available for configuration in redundant mode using Output Summer connectors. Figure 3-5 shows the placement of the Output Summer connectors for redundancy. The pinout of the Output Summer connectors is the same as the I/O interface connectors.

To install the Output Summer, perform the following:

1. Remove two screws on each connector that the Output Summer connectors are to be installed on.


## Caution:

To avoid possible electro-static discharge problems after removing an Output Summer connector, you must replace the screws securing the I/O connectors on the rear panel of the SSU2000.
2. Install Output Summer connectors on all corresponding outputs requiring redundancy, see Figure 3-5.
3. Tighten all Output Summer connector screws securely.
4. Connect 50-pin Micro-D output cables as required.


Figure 3-5. SSU-2000 Input/Output Connectors

### 3.5.3 Communication Interfaces

The rear panel of the SSU-2000 shelf has connections for three communications interfaces, two RS-232 Serial Port connections, and one Ethernet connection. These ports allow communication between the SSU-2000 and a terminal or PC. Each port is configured independently.

```
IT NOTE...
A third RS-232 serial port may be connected using the Communications Module. Refer to Chapter 8 for more information on the Communications Module.
```

Refer to the Table 3-2 for the serial and Ethernet communications port assignments.

Table 3-2. Communications Port Assignments

| Port \# | Function | Protocol |  |  |
| :---: | :--- | :--- | :---: | :---: |
| Serial Ports (RS-232) |  |  |  |  |
| A (J4) | This port is user selectable as either an ICS or a TL1 <br> interface. The port defaults to ICS upon initialization | ICS (Default), TL1 |  |  |
| B (J5) | This port is user selectable as either an ICS or a TL1 <br> interface. The port defaults to ICS upon initialization | ICS (Default), TL1 |  |  |
| Local (Comms <br> Module) | This port is user selectable as either an ICS or a TL1 <br> interface. The port defaults to ICS upon initialization | ICS (Default), TL1 |  |  |
| Ethernet Ports (TeInet) |  |  |  | ICS (Default), TL1 |
| 23 | This port is user selectable as either an ICS or a TL1 <br> interface. The port defaults to ICS upon initialization | NTP |  |  |
| 123 | This port is designated for NTP only | SNMP Interactive |  |  |
| 161 | This port is designated for SNMP Interactive | SNMP Trap |  |  |
| 162 | This port is designated for SNMP Trap transmission | TL1 |  |  |
| 2000 | This port is designated for TL1 only |  |  |  |

## RS-232 Serial Port Connections

Both RS-232 serial port connections are made through filtered DE9S female connectors on the rear panel. These ports allow connection to a terminal or PC for remote monitoring and control. One is on connector J 4 and is labeled Serial Port A, the other is on connector J5 and is labeled Serial Port B. When connecting to these ports, use a shielded cable RS-232 direct connect cable with the shield connected to pin 1.

## Serial Port DTE/DCE Switch

The serial port DTE/DCE switch is located on the lower right side of the rear panel, as shown in Figure 3-6. Each port (A and B) may be configured as either DCE (default, connection to PC) or DTE (connection to modem). The right switch controls port A and the left switch controls port B.


Figure 3-6. DPDT Slide Switch
The default RS- 232 settings for both serial ports are 9600 baud, no parity, 8 data bits, 1 stop bit, echo on, ASCII mode, and handshaking disabled. To change these settings, connect the SSU-2000 to a terminal device or PC using a serial communications program protocol. See Section 5.2.1, Communicating by Serial Port, for more information.

### 3.5.4 Ethernet Connection

The Ethernet 10-Base-T connection is located on the rear panel connector J3, which is a shielded RJ45 receptacle labeled Ethernet 10-Base-T.

### 3.5.5 Local Oscillator Outputs

The SSU-2000 has two Local Oscillator (LO) connections on the rear panel. These connections are made using the BNC connector J1 labeled LOCAL OSC-A and the BNC connector J2 labeled LOCAL OSC-B. The bodies of these BNCs are connected to frame ground.

### 3.6 Alarms

The SSU-2000 has two alarm terminal blocks located on the rear panel for attaching external circuits to the SSU-2000, and are shown in Figure 3-7. Both blocks are nine-position, \#6 filtered terminal blocks. The local connections are made on TB1 and the remote connections are made on TB2. The terminal blocks are labeled Alarm Closures, Local and Remote. The connections are labeled NO (normally open), COM (common or wiper) and NC (normally closed) for each of the alarm categories CRITICAL, MAJOR and MINOR.


Figure 3-7. Alarm Terminal Blocks

## Alarm Relays

The Communications module contains six Form C relays, used for alarm reporting. The relays provide contact closures for Local Critical, Local Major, Local Minor, Remote Critical, Remote Major, and Remote Minor alarm conditions. Switching capacity is up to 1 ampere, with a voltage up to 72 vdc . When the module is installed, all relays are in the "no alarm" condition (corresponding ALARMS LEDs are off). Each Remote/Local relay pair is controlled by the same control bit in the LCA that controls the LEDs. Table 3-3 shows the default state of each relay pair (energized/de-energized), the "no alarm", and "alarm" connections.

Table 3-3. Relay Connections

| REM/LOC <br> PAIR | CONDITION <br> (default shown first) | CONNECTION: <br> TB1/TB2 |
| :--- | :--- | :--- |
| CRITICAL | Energized: no alarm <br> De-energized: alarm | COM - NC <br> COM - NO |
| MAJOR | De-energized: no alarm <br> Energized: alarm | COM - NC <br> COM - NO |
| MINOR | De-energized: no alarm <br> Energized: alarm | COM - NC <br> COM - NO |

Perform the following steps to ensure proper alarm connections to the SSU-2000.

1. Remove both fuses from the rear panel.
2. Locate the ALARM terminal blocks connectors labeled MAJOR ALARMS (TB1) and MINOR ALARMS (TB2) on the rear panel.
3. Connect office alarms to the REMOTE and LOCAL terminals with 18 AWG wire.
4. Verify that correct wiring connections have been made.
5. Reinstall both fuses.

## 1

## Caution

For continued fire protection, replace fuse with specified type and rating. Fuse: GMT-5 (5A @ 60vDC).
This unit must be grounded.
Refer all servicing to qualified personnel.

```
#
NOTE...
In an alarm condition or loss of DC power, the contact between the NO and COM closes and the contact between the NC and COM opens.
```


### 3.7 Antennas

The SSU-2000 shelf has two antenna connections on the rear panel. The antenna connections are made via isolated TNC connector J6 labeled ANTENNA-A and Isolated TNC connector J7 labeled ANTENNA-B. These TNCs are DC isolated and AC bypassed to frame ground. These connections are used for radio receiver antenna connections only. Refer to Appendix C, Antennas, for installation procedures and additional instructions.


### 3.8 SDU Interface

The SSU-2000 Main shelf has interface connectors to connect an SDU-2000 Expansion shelf. These connections are made through connector J8, a DB25S female connector with locking post, labeled SDU INTERFACE, and connector J9, a twin BNC connector, labeled SDU BACKUP CLK.

ss200040
Figure 3-8. SDU Interface (J8) and Backup Clock (J9) Connectors

If an SDU-2000 Expansion shelf is not being installed, the J8 connector on the SSU-2000 must have the expansion terminator installed. Figure 3-9 shows the SSU-2000 Expansion Terminator (P/N 12013049-000-0).


Figure 3-9. SDU Interface (J8) Expansion Terminator

## In NOTE..

The SDU backup clock signal on connector J9 is a differential pair. All signals on J 8 are in differential pairs and each pair is terminated with a series 0.001 micro farads capacitor and 120 ohm resistor via an external plug-in terminator with locking slide latch.

### 3.9 Remote Reset

The SSU-2000 shelf has a remote reset input which can be used to remotely initiate system firmware reset if the need should arise. The remote reset connections are made via connector J19 a TBNC/BNO connector labeled REMOTE RESET.

### 3.10 Module Insertion

The SSU-2000 shelf has twelve plug-in module slots. The module slots are numbered A1 through A12, from left to right looking at the front of the shelf. Each module slot has a specific address and has two hybrid DIN connectors associated with it on the backplane. The hybrid contacts of these connectors are used for Power, Logic Ground, Frame Ground and RF connections. Each module slot has three pins connected together on each hybrid DIN connector which are used for module removal detection.


## Caution...

To avoid equipment damage due to poor ventilation and EMI considerations, each slot in the SDU-2000 must contain either a module or blank filler panel. Filler panels are available from Datum for unpopulated slots.

### 3.11 Handling Modules

The following should be considered when handling any of the modules:

1. Use proper static control precautions when handling modules! Protect the equipment against ESD (Electro Static Discharge) by using a grounded protective wrist strap and normal equipment grounding. Two ground connectors are provided on the side of the unit for connection of these straps to frame ground (one on each mounting bracket).
2. Avoid touching component leads and edge connectors.
3. Avoid laying the module on an ungrounded surface.
4. Avoid allowing the module to come in contact with insulated surfaces.

## Inserting Modules

This procedure is common for all modules.

## IT Note...

Modules can be removed and inserted while system power is supplied without damaging modules or affecting system operation.

## A

## Caution...

For continued EMC compliance, replace all deformed module gaskets with the same type. Clean gaskets and mating surfaces. Secure all modules with captive screws.

All modules are inserted as follows:

1. Align the module card edges with the plastic card guides of the selected slot.
2. Slide the module into the chassis until it seats fully into its rear panel edge connector.
3. Tighten the captive screws located at the top and bottom of the module front panel.

## $!$

## Caution...

Ensure that you have completely inserted the module into the system and that you have securely tightened the captive screws. A partially inserted module can easily become damaged and cause intermittent failures.

### 3.12 Installation Checklist

1. Unpack all equipment carefully and check it against the purchase order.
2. Remove the A-BUS and B-BUS fuses from the rear of the unit.
3. Ensure chassis and I/O adapters are securely attached to mounting rack.
4. Ground the SSU-2000 using the Frame Ground lug.
5. Measure between ground and chassis and verify no voltage exists between them.
6. If an SDU-2000 Expansion Chassis is not being installed, ensure that the J 8 connection is connected to a terminator.
7. Connect office alarms to the REMOTE and LOCAL terminals with 18 AWG wire.
8. Insert modules and filler panels in designated slots. Use proper handling technique.
9. Connect primary power to A-BUS screws and secondary power to B-BUS screws.
10. Measure voltage at POWER A and POWER B (if used) and verify it is -38 to -72 vDC .
11. Insert the A-BUS and B-BUS fuses into the SSU-2000 chassis.
12. Verify all modules are receiving power and generating regulated DC outputs by checking that their POWER indicators are lit.
13. To ensure that both power inputs are valid, verify on the Communications or Buffer modules that the green POWER indicator on the front of the Communications module is on. Also verify that the -48 V Power A and B LEDs are both green. If all these indicators are not green, refer to Table 3-4 for the module color code indications. Refer to Section 7, Maintenance and Troubleshooting, if unable to obtain the correct indications

Table 3-4. Communications and Buffer Module LED Indications

| LED | State | Indication |
| :--- | :--- | :--- |
| Power | On | At least one -48V Power Supply is connected |
| Power | Off | No -48V Power Supply A or B connected |
| -48 V Power Supply A or B | On (Green) | Power Supply is connected |
| -48 V Power Supply A or B | Off | No -48V Power Supply connected to the power supply <br> input |
| -48 V Power Supply A or B | On (Amber) | -48 V Power polarity is reversed |

## IN THIS CHAPTER ...

- SSU-2000 Power Control
- Power Up Procedures
- SDU-2000 Turn-Up Procedures
- Normal System Indications During Turn-Up
- After Turn Up


## Chapter 4 Turn-Up Procedures

This chapter describes the turn-up procedures for the SSU-2000 system and bringing the system on-line after completing the system installation.

### 4.1 SSU-2000 Power Control

The SSU-2000 is not equipped with a Power switch. Power to the SSU-2000 is controlled by two $5-\mathrm{amp}$ fuses located on the rear of the SSU-2000 main chassis as shown in Figure 4-1. To power up the unit, install both fuses.


Figure 4-1. SSU-2000 Power Fuses

### 4.2 Power Up Procedures

To power up the system, insert the two fuses into the fuse slots on the back of the SSU-2000 main chassis (see Figure 4-1).

### 4.3 SDU-2000 Turn-Up Procedures

This section describes the procedures for powering up the SDU-2000 system and bringing the system on-line after completion of the system installation. After completion of the turn-up procedures, complete the commissioning tests in Chapter 6, Commissioning to ensure that the system is functioning properly.

## SDU-2000 Power Control

The SDU-2000 expansion chassis is not equipped with a Power switch. Power to the SDU-2000 is controlled by two external power supplies that provide $-48 / 60 \mathrm{vDC}$ to the SDU-2000 main chassis (A-BUS and B-BUS) at connectors J101 and J102. To power-up the shelf, turn the power on to both power supplies.

### 4.4 Normal System Indications During Turn-Up

As the system powers up and begins normal operation, the LEDs on the front of each of the installed modules go through a sequence as follows:

- Clock Module 2E - The POWER LED turns green and stays green when the fuses are installed in the Main chassis. The STATUS LED blinks green and amber for approximately 10 to 15 seconds and then stays green. The SELECTED LED turns green on the selected clock module after the ACQUIRE LED on the clock module turns green. The WARMUP LED turns amber for approximately 30 seconds to 5 minutes; it then turns off and the ACQUIRE LED turns green. The ACQUIRE LED stays green for 10 to 15 minutes until the module locks onto a signal, then the LED turns off. The LOCKED LED then turns green and stays green.
- Clock Module 3E - The POWER LED turns green when power is applied to the unit and stays green. STATUS LED blinks green and amber for approximately 10 to 15 seconds and then stays green. The SELECTED LED turns green on the selected clock module after the ACQUIRE LED turns green. The WARMUP LED turns amber for approximately 30 seconds to 20 minutes then turns off and ACQUIRE turns green. The ACQUIRE LED stays green until the module locks onto a signal ( 10 to 15 minutes); then the LED extinguishes. The LOCKED LED turns green and stays green.
- Communications Module - The POWER LED turns green when power is applied to the unit and stays green. The STATUS LED blinks green and amber for approximately 10 to 15 seconds and then stays green. The -48 V POWER LEDs A and B turn green to indicate that the power supplies are connected. If one of these LEDs are amber, the polarity of that power connection is reversed and needs to be switched. The three ALARM LEDs clear after $\sim 1$ minute. After initialization, if there are any alarms, it takes approximately 30 seconds to register and the ALARM LED turns amber. The ETHERNET LINK LED blinks green for approximately 30 seconds and stays green.
- Input Module - The POWER LED turns green when power is applied to the unit and remains green while the system is powered up. The STATUS LED blinks green and amber for approximately 10 to 15 seconds and then stays green. The PORT 1 REF LED blinks for approximately 5 to 10 seconds and turns green for the reference input and off for the others. The INPUT LED blinks for approximately 5 to 10 seconds and turns green for every valid input or amber for not valid inputs.
- Output Module - The POWER LED turns green when power is applied to the unit and stays green. The STATUS LED blinks green and amber for approximately 10 to 15 seconds and then stays green. The SOURCE LED turns green for the source clock, amber for an enabled clock that is not present and off for an enabled clock that is present but not the source clock.


### 4.5 After Turn Up

This completes the turn-up procedures. After completing the turn-up procedures perform the following:

- Assign a System Administrator and any additional users to the system using the procedures in Chapter 5, Operating and Provisioning Procedures.
- Make any required changes to the factory default configuration settings as described in Chapter 5, Operating and Provisioning Procedures.
- Complete the commissioning tests in Chapter 6, Commissioning, to ensure that the system is functioning properly.
- Refer to Chapter 7, Maintenance and Troubleshooting, to clear any system alarms that might occur.


## In this Chapter

- Controls and Indicators
- Establishing a Connection to the SSU-2000
- Adding the Administrator User to the System
- Adding Users to the System
- Checking Alarm Status
- Overview of the SSU-2000 Security System
- Restoring Factory Defaults


## Chapter 5 Operating and Provisioning Procedures

This chapter provides operating instructions and software provisioning procedures for the SSU2000 system. Section 5.1, Controls and Indicators, describes the SSU-2000 operating controls and indicators; Section 5.2, Establishing a Connection to the SSU-2000 describes the procedure for connecting to the SSU-2000. Section 5.3, Adding the Administrator User to the System, describes how to set up the Administrator user. Section 5.4, Adding Users to the System, describes how to add general users. Section 5.5, Checking Alarm Status, describes how you can use the communications interfaces to check the status of alarms. Section 5.6, Overview of the SSU-2000 Security System, describes the different types of users you can define and their associated security levels. Section 5.7, Restoring Factory Defaults, describes the various software options available with the SSU-2000, identifies all factory default settings, and provides a procedure for restoring the SSU-2000 to factory defaults.

### 5.1 Controls and Indicators

### 5.1.1 SSU-2000 Status LED Indicators

All modules used in the SSU-2000 main chassis and in the optional SDU-2000 expansion chassis contain status LED indicators that provide a visual indication of module status. The Communications module provides both system and individual module status whereas all other modules provide individual module status only. For more information on individual module status LED indicators, refer to Chapter 8, Module Reference Data.

### 5.1.2 SSU-2000 Operating Controls

The SSU-2000 contains four hardware operating controls:

- Three DCE/DTE select switches associated with the three RS-232 ports. One switch is located on the front of the Communications module and the remaining two are located on the SSU-2000 back panel. The DCE position is for connection to a PC and the DTE position is for connection to a modem.
- Reset (RST) switch on the Communications module.


### 5.2 Establishing a Connection to the SSU-2000

Setup either an ethernet telnet session (if the SSU-2000 is connected to a LAN) or a direct serial connection using a dumb terminal or a PC with terminal emulation software. For a direct connect via serial port, see Section 5.2.1, Communicating by Serial Port. If the SSU-2000 is connected to an Ethernet LAN, use the procedure described in Section 5.2.2.2, Connecting through the Ethernet LAN. Refer to Table 5-1 for the serial and Ethernet communications port assignments.

Table 5-1. Communications Port Assignments

| Port \# | Function | Protocol |  |  |
| :---: | :--- | :--- | :---: | :---: |
| Serial Ports (RS-232) |  |  |  |  |
| A (J4) | This port is user selectable as either an ICS or a TL1 interface. <br> The port defaults to ICS upon initialization | ICS (Default), TL1 |  |  |
| B (J5) | This port is user selectable as either an ICS or a TL1 interface. <br> The port defaults to ICS upon initialization | ICS (Default), TL1 |  |  |
| Local <br> (Comms <br> Module) | This port is user selectable as either an ICS or a TL1 interface. <br> The port defaults to ICS upon initialization | ICS (Default), TL1 |  |  |
| Ethernet Ports (TeInet) |  |  |  | ICS (Default), TL1 |
| 23 | This port is user selectable as either an ICS or a TL1 interface. <br> The port defaults to ICS upon initialization | NTP |  |  |
| 123 | This port is designated for NTP only | SNMP Interactive |  |  |
| 161 | This port is designated for SNMP Interactive | SNMP Trap |  |  |
| 162 | This port is designated for SNMP Trap transmission | TL1 |  |  |
| 2000 | This port is designated for TL1 only |  |  |  |

### 5.2.1 Communicating by Serial Port

Three RS-232-C ports are available on the SSU-2000 for communication with the system. Attach either a dumb terminal or a PC with terminal emulation software to one of the ports as shown in Figure 5-1 (this example shows connecting to the local port on the front of the Communications module). The PC or terminal must be configured for 8 data bits, no parity, 1 stop bit, and 9600 baud rate.


Figure 5-1. Direct Connection Using the Serial Port

### 5.2.2 Communicating by Ethernet

To communicate by Ethernet, the Ethernet port must be configured, see Section 5.2.2.1, Configuring the Ethernet Port. If this has already been performed, proceed to Section 5.2.2.2, Connecting through the Ethernet LAN.

### 5.2.2.1 Configuring the Ethernet Port

Use the following procedure to configure the SSU-2000 Ethernet parameters (IP Address, Subnet Mask, and Gateway Address).

1. Establish a direct serial connection to the SSU-2000 as described in Section 5.2.1, Communicating by Serial Port.
2. At the system prompt, type ip addr followed by the IP address expressed in dotted decimal notation (for example, 192.168.18.1), and press Enter.
3. Type ip mask followed by the mask in dotted notation (for example, 255.255.0.0 for a class B network, or 255.255.255.0 for a class C network), and press Enter.
4. Type ip gate followed by the IP address of the gateway (expressed in dotted decimal notation, for example, 192.168.0.1), and press Enter.
5. Type restart $\mathbf{1 A 0 2}$ and press Enter to restart the Communications module.
6. The system responds with, Are you sure? Type YES and press Enter.
7. Type ip and press Enter to verify that the information is correct.
8. Type bye and press Enter to log off the system.

### 5.2.2.2 Connecting through the Ethernet LAN

1. Connect the SSU-2000 to a LAN using category 3, 4, or 5 cabling with RJ45 terminations on both ends, see Chapter 3, Installation for installation details.
2. Plug one end of the network cable into the Ethernet 10baseT jack located on the rear of the SSU-2000 and the other end of the cable into the network interface jack.
3. Telnet from your PC to the IP address assigned to the SSU-2000 system.
4. Type your user name and press the Enter key. If you have not yet been assigned as a user to the system, contact the System Administrator for the SSU-2000 system.
5. Enter your assigned password and press Enter. The system prompt appears.

### 5.3 Adding the Administrator User to the System

An Administrator user must be added to the system when you log in for the first time. The Administrator user performs initial setup and can assign user privileges and access codes as needed, as well as configuring all system parameters at this access level. Refer to Section B.2.2, User Access Levels, for more information on user access levels.
CAUTION ...
You must add the Administrator user and password before adding any
other users. If you add a user that is not at the administrator security
level before adding the administrator, you will not be able to log into the
unit at that level again without a service call.

Perform the following steps to add the administrator user to the system.

1. Type admin at the username prompt for the first-time system login (otherwise enter your username) and press Enter. The system prompts for a password.
2. Press the Enter key for the first-time system login (otherwise enter your password) and press Enter. The system prompt appears.
3. Type user add and press Enter. The system prompts you for a user name.
4. Enter a "username" and press Enter. The name you enter will be the log-in name for the system administrator. The system prompts you for a password.
5. Enter a "password" and press Enter. The password you enter will be the log-in password for the system administrator. The system prompts you for an access level.
6. Type 4 and press Enter. This selects the administrator access level. The system prompt appears.
7. Type bye and press Enter to log off the system.
8. Log back in as the new system administrator to verify that the account exists (repeat steps 4 and 5).
9. Type bye and press Enter to log off the system.

### 5.4 Adding Users to the System

Only an administrator-level user can add new users to the SSU-2000 system. Perform the following steps to add a user to the system.

1. Type the administrator's user name and press Enter. The system prompts for a password.
2. Type the administrator's password and press Enter. The system prompt appears.
3. Type user add and press Enter. The system prompts for the new username.
4. Enter the new username and press Enter. The system prompts for the new user's password.
5. Enter the new user's password and press Enter. The system prompts for an access level.
6. Enter the appropriate access level and press Enter. Refer to Section B.2.2, User Access Levels, for more information.
7. Type bye and press Enter to log off the system.
8. Log back in using the new user's username and password to verify that the account exists.
9. Type bye and press Enter to log off the system.

### 5.5 Checking Alarm Status

All alarm indication lights should be extinguished and the POWER indication lights should be green after completing the power up sequence. The valid input reference alarm clears, rubidium lock clears, frequency alarms clear, and the ACQUIRE LED is ON. Use the following procedure with the STATUS and ALARM commands to verify that the unit is operational.

1. Log in to the SSU-2000 system and press the Enter key.
2. Type alarm and press the Enter key to verify that there are no active alarms.
3. Type bye to and press the Enter key log off the system.

### 5.6 Overview of the SSU-2000 Security System

The SSU-2000 security system software contains a hierarchy of user levels that permit an increasing level of access to system parameters. This allows the system administrator to add users that can, for example, view but not change system parameters; other users can view and change system parameters.

The users assigned to each security level have a different set of options available. For example, a User-level user does not have as many options available as a Technician-level user.

Table 5-2 summarizes each security level, ID number, and the privileges available at each level. To determine your security level, contact the System Administrator.

For a first-time installation, the default login is at the administrator level. When adding users, add the administrator-level user and password first to avoid a service call. Users at the administrator level set up other users and their level of security. For more information on user security and access levels, see Section B.2.2, User Access Levels.

## Table 5-2. User Access (Security) Levels

| Level | ID | Description |
| :--- | :--- | :--- |
| Idle | 0 | Security level 0 is available when no user is logged in. This level allows Idle users <br> to view a list of available commands (HELP), syntax, software version number, <br> unit id, or to login. |
| User | 1 | User-level users can: <br> - Perform level 0 functions <br> - View information about the current configuration and operation <br> - Change communication settings such as line termination and echo <br> Changes made by users at this level remain in effect only until the user logs out. |
| Technician | 2 | Technician-level users (CRAFT persons) can: <br> - Perform level 0 through 1 functions <br> - Read or set all installation functions |

## Table 5-2. User Access (Security) Levels (Continued)

| Level | ID | Description |
| :---: | :---: | :---: |
| Supervisor | 3 | Supervisor-level users can: <br> - Perform level 0 through 2 functions <br> - Read or set all functions |
| Administrator | 4 | Administrator-level users can: <br> - Perform level 0 through 3 functions <br> - View and set software configurations <br> - Add, delete, or modify the user table <br> - Log off any user from any port |

### 5.6.1 Factory Default (Basic) Configuration

Prior to shipping, Datum-Austin loads all required operational software. The SSU2000e ships with a factory default (basic) configuration set and often does not require further configuration. Refer to Appendix E, Default Settings, for a list of the factory default settings and the default Priority Quality Level (PQL) values.

### 5.6.2 Changing Factory Defaults

Use the following steps to change the factory default or any configuration settings in the SSU2000. This example changes an alarm from minor to major.

1. Log in to the system using one of the methods described in Section 5.2, Establishing a Connection to the SSU-2000. The system prompts for a user name.
2. Type your user name press Enter. The system prompts for a password.
3. Type your password and press Enter.
4. Type alarm 1A12 03 (1=shelf; 12=slot; 03=alarm number), and press Enter.
5. Type alarm 1A12 and press Enter to verify that 03 changed to major.
6. Type bye and press Enter to log off the system.

### 5.6.3 Adding or Enabling a Module

Use this procedure when replacing one type of module with a different type of module in the same slot. The following example procedure adds a module to shelf $1, \operatorname{slot} 12$.

1. Insert the module into slot 12 of the main shelf.
2. Log on to the system using one of the methods described in Section 5.2, Establishing a Connection to the SSU-2000.
3. Type your user name press Enter. The system prompts for a password.
4. Type your password and press Enter.
5. Type config 1A12 enable and press Enter.
6. Type config and press Enter to verify that the module is registered.
7. Type bye and press Enter to log off the system.

### 5.6.4 Disabling a Module

Use this command to temporarily disable a module without removing it from the system. The following example procedure disables the module in shelf 1 , slot 12 .

1. Log in to the system using one of the methods described in Section 5.2, Establishing a Connection to the SSU-2000. The system prompts for a user name.
2. Type your user name press Enter. The system prompts for a password.
3. Type your password and press Enter. The system prompt appears.
4. Type config 1A12 disable and press Enter.
5. Type bye and press Enter to log off the system.

### 5.6.5 Removing a Module

Use this procedure to permanently remove a module from the system. The following example procedure removes the module in shelf 1 , slot 12 from the registry.

1. Log in to the system using one of the methods described in Section 5.2, Establishing a Connection to the SSU-2000. The system prompts for a user name.
2. Type your user name press Enter. The system prompts for a password.
3. Type your password and press Enter. The system prompt appears.
4. Remove the module.
5. Type config 1A12 remove and press Enter.
6. Type config and press Enter to verify that the module is not in the registry.
7. Type bye and press Enter to log off the system.

### 5.6.6 Customizing Other Configuration Options

The SSU-2000 allows the user to change any or all configuration settings. Use the following procedures to customize the system for a particular environment.

1. Log in to the system using one of the methods described in Section 5.2, Establishing a Connection to the SSU-2000. The system prompts for a user name.
2. Type your user name press Enter. The system prompts for a password.
3. Type your password and press Enter. The system prompt appears.
4. Use the commands listed in Section B.3, Interactive Command Set, to configure the system.


## Recommendation:

Do not perform any command whose function you do not understand. This could result in improper provisioning of the network.
5. Type setup save and press Enter to save the current configuration as the user default setting.
6. Type bye and press Enter to log off the system.

### 5.7 Restoring Factory Defaults

Use the following procedure to reset the configuration to the factory default.

1. Log in to the system using one of the methods described in Section 5.2, Establishing a Connection to the SSU-2000. The system prompts for a user name.
2. Type your user name press Enter. The system prompts for a password.
3. Type your password and press Enter. The system prompt appears.
4. Type setup xAy factory and press Enter.
5. Type bye and press Enter to log off the system.

## In this Chapter ...

- Readiness to Test Checklist
- SSU-2000 Commands
- Equipment Requirements
- Commissioning Tests
- Commissioning Test Data Sheet


## Chapter 6 Commissioning

The commissioning tests for the SSU-2000 system are checklist-based operational tests that field engineers perform at the installation site after completion of installation, system turn-up, and provisioning to verify that the system is correctly installed, configured and operating properly. At this point, the system is ready to be placed in service.

Record the results on the data sheet provided in Section 6.5, Commissioning Test Data Sheet.

### 6.1 Readiness to Test Checklist

Before performing the commissioning tests in this section, ensure that all items in the Readiness Checklist have been performed.

Table 6-1. SSU-2000 Readiness Checklist

| Item <br> No. | Task | Checked |
| :---: | :--- | :---: |
| 1 | The SSU-2000 is installed in the rack with a minimum of 3 inches of clearance <br> between the bottom of the lowest chassis and the floor or other equipment. An <br> I/O adapter panel can be installed adjacent to the bottom of the chassis without <br> restricting the necessary cooling airflow. |  |
| 2 | The SSU-2000 main chassis has a minimum of 1 inch of clearance between the <br> top of the chassis and an adjacent chassis (except that an SSU-2000 I/O adapter <br> panel can be installed adjacent to the chassis with no clearance since it does not <br> impact airflow). |  |
| 3 | An SSU-2000 Clock Module is installed in chassis slot A1 and A12 as required <br> (Stratum E2 must be in slot A1, if used). |  |
| 4 | An SSU-2000 Communications module is installed in slot A2. |  |
| 5 | An SSU-2000 Input Module is installed in the chassis. |  |

Table 6-1. SSU-2000 Readiness Checklist (Continued)

| Item <br> No. | Task | Checked |
| :---: | :--- | :--- |
| 6 | An Input I/O Adapter is installed above the SSU-2000 main chassis and cabled to <br> the corresponding I/O connector on the back of the SSU-2000 main chassis. |  |
| 7 | If using optional GPS Input module, it is installed in SSU-2000 Chassis slot A3 or <br> A5 and a Radio antenna is attached to the corresponding Radio antenna <br> connector on the back of the SSU-2000 chassis. |  |
| 8 | At least one output module is installed in chassis slot A4 through A10 (unless the <br> monitor only configuration is being used) |  |
| 9 | One output type I/O adapter panel is installed near the SSU-2000 main chassis <br> for each output module (or redundant pair) in the main chassis. |  |
| 10 | One output type I/O adapter panel is installed adjacent to an SDU-2000 <br> expansion chassis for each output module (or redundant pair) installed in an <br> optional SDU-2000 expansion chassis. |  |
| 11 | An SDU Termination Plug is installed on the SDU Connector (if the optional SDU- <br> 2000 expansion chassis is not installed) |  |
| 12 | -48 Vdc inputs from external power supplies are connected to the A and B Power <br> terminal strips on the back of the SSU-2000 main chassis. |  |
| 13 | The selected set of critical, major and minor alarms terminals on the back of the <br> SSU-2000 are connected to the customer's alarm circuitry. |  |
| 16 | At least one reference input is connected to each input module in the SSU-2000 <br> main chassis. | If the ethernet connection is being used, the ethernet connection on the back of <br> the SSU-2000 is connected into the local area network. |
| 15 | Two fuses are installed in the SSU-2000 main chassis. <br> and saved and IPs assigned for the Ethernet interface. |  |
| 17 | A System Administrator and user access levels have been assigned to the SSU- <br> 2000 (see Chapter 5, Operating and Provisioning Procedures). |  |
| 18 |  |  |
| 10 |  |  |

### 6.2 SSU-2000 Commands

Several SSU-2000 commands may be useful while performing the following testing. These include:

- CONFIG - reports the modules installed in the system with part numbers and other information;
- SETUP - reports current settings for the module options;
- STATUS - reports the current operating status of all modules in the system.

Each of these commands can also be used with a module ID\# (slot position) to obtain additional detail for a module. The CLK, INPUT, and OUTPUT commands provide status for only the indicated type modules, and can also be used with the module ID\# to obtain detailed information.

### 6.3 Equipment Requirements

The following equipment is required to perform the commissioning tests:

- Digital Voltmeter (DVM)
- Communications analyzer to check for correct framing, Sync Status Messaging (SSM), and line coding.
- Oscilloscope with correct load terminations and cables to verify outputs.

Note ..
If the Communications analyzer has the ability to test the pulse mask, an oscilloscope is not required.

- PC or laptop with serial port and TCP/IP connectivity and terminal emulation software such as Microsoft HyperTerminal or ASCII terminal.
- If testing stability and accuracy of output against another primary reference source (PRS), a phase recorder will also be required.


### 6.4 Commissioning Tests

The following paragraphs contain the SSU-2000 commissioning test procedures. These procedures consist of the following tests:

- Testing the Ethernet Communications Interface
- Testing the RS-232 Ports
- Testing the SSU-2000 Minor alarms
- Testing the SSU-2000 Major alarms
- Testing the SSU-2000 Critical alarms
- Testing the Reference Input Signals
- Testing the SSU-2000 Output signals


### 6.4.1 Testing the Ethernet Communications Interface

If an Ethernet connection to a network has been installed, use the following procedure to test the ethernet connection.

1. Telnet from the PC to the IP address assigned to the SSU-2000 system. The system prompts for a user name.
2. Type your assigned "username" and "password" and press Enter. The system prompt appears.
3. Type bye and press Enter to log off the system.

### 6.4.2 Testing the EIA-232 Ports

To test the EIA-232 port A:

1. Connect the PC or terminal to EIA-232 Port A as described in Chapter 5, Operating and Provisioning Procedures.
2. Type HELP and press Enter.
3. Verify a response to the command entered.
4. Exit the serial communication session. Move the direct connect cable to each of the remaining two serial ports and repeat steps 2 and 3.

### 6.4.3 Testing The MINOR Alarms

To test the MINOR alarm relay closures and software:

1. Enter the ALARM command and set Power A to the alarm level to MINOR.
2. Remove Power A input by removing the A-bus fuse (or the fuse that supplies Power A).
3. Verify that the MINOR alarm indicator is ON.
4. Verify that a MINOR alarm is reported to the communications terminal.
5. Enter EVENTS and press Enter; verify that a MINOR alarm was logged into the event log.
6. Replace the fuse to restore Power A to the unit.
7. Verify that the alarm clears, is reported and logged.

### 6.4.4 Testing the MAJOR Alarms

To test the MAJOR alarm relay closures and software:

1. Type AlARM and press Enter.
2. Set the Power A alarm level to MAJOR.
3. Remove Power A input by removing A-bus fuse (or fuse that supplies Power A).
4. Verify that the MAJOR alarm indicator is ON.
5. Verify that the MAJOR alarm is reported to the communications terminal.
6. Enter EVENTS command and verify a MAJOR alarm was logged in event log.
7. Replace the fuse to restore Power A to the unit.
8. Verify that the alarm clears, is reported and logged.

### 6.4.5 Testing the CRITICAL Alarms

To test the CRITICAL alarm relay closures and software:

1. Type ALARM and press Enter.
2. Set the Power A alarm level to CRITICAL.
3. Remove Power A input by removing A-bus fuse (or fuse that supplies Power A).
4. Verify that the CRITICAL alarm indicator is ON.
5. Verify that the CRITICAL alarm is reported to the communications terminal.
6. Enter EVENTS command and verify a CRITICAL alarm was logged in event log.
7. Replace the fuse to restore Power A to the unit.
8. Verify that the alarm clears, is reported and logged.
9. Type ALARM and press Enter to restore Power A to the original alarm level.

### 6.4.6 Testing the Reference Signals and Selection

To test the reference signals and selection:

1. Type INPUT to verify each input signal is present with no alarms. Each reference input will be listed by module position and port number, status, phase A and B readings, input PQL, signal alarms, and MTIE alarms.
2. The status should be $\mathbf{O K}$ and the Priority Quality Level (PQL) should indicate the received Sync Status Message (SSM) level or the provisioned value. The phase values will be dependent on the received signal. The signal alarms should be //I// (no alarms present, F indicates an alarm) and the MTIE alarms should all be OK.
3. Type REF and press Enter to determine the current selection of input reference signal. Disconnect this input signal and verify a Loss Of Signal (LOS) is reported for the input, and the unit selects an alternate input for the reference signal.
4. Reconnect the input signal and verify that the LOS condition is cleared and the reference input is selected according to the system configuration. This depends on the setting for Revertive Selection, Input Priorities, and Reference Selection mode.
5. Type EVENT and press Enter; verify that the alarms and events created are recorded in the event log.

### 6.4.7 Testing the Clock Section

To test the clock section:

1. Type CLK and press Enter to verify each clock is operating properly.

The system displays the clocks by module position (1A1 for Clock A and 1A12 for Clock B) and the status for each clock (SEL for the selected clock and OK for the standby clock).
2. Verify that the PLL mode for each clock is in LOCK at this time, and that the Tau value is at the maximum time constant set for each clock, dependent on the clock type of ST2 or ST3E.

The PQL should be the level the clock is supplying to the output modules, dependent on the reference input when in lock mode. The frequency offset will be dependent on the clock type, typically less than 2E-10 for ST2 and 1E-6 for ST3E. This only indicates the uncorrected frequency offset of the oscillator which is being removed by the clock DDS circuitry.

The sigma value indicates the stability of the clock, which should be less than $1 \mathrm{E}^{-9}$.

### 6.4.8 Testing the Output Section

To test the output section:

1. Type OUTPUT and press Enter to verify each output module is operating with no alarms. This will display the output modules by position with module status OK and the selected clock. The clock status will indicate the presence or absence of the four possible clocks: A, $\mathrm{B}, \mathrm{C}$ (bypass), or D (expansion shelf only).
2. Verify that any outputs configured for redundant pairs are so indicated in the status report. The PQL will indicate the output SSM level for all ports and is supplied by the selected clock.
3. Verify that all output ports which are intended to be active indicate $Y$ in the port status.

### 6.4.9 Testing the System Stability and Accuracy (Optional)

This test is only to be performed if a PRS (primary reference source) and the necessary test equipment is available. If the above tests have been passed, the system output will meet the stability and accuracy of the reference input.

1. Connect one of the system outputs and the PRS signal to the test equipment to monitor the stability and accuracy. This test should be allowed to run for 24 hours to collect sufficient data to verify the system output meets specifications.
2. Process the collected 24 hour data and verify that the frequency and stability (MTIE and TDEV) meet the specifications.

This completes the commissioning tests. The system is ready to be placed in service.

### 6.5 Commissioning Test Data Sheet

The following test data sheet should be completed as an indicator of operational readiness of the SSU-2000.

Table 6-2. Commissioning Test Data Sheet

| Test | Pass | Fail |
| :--- | :--- | :--- |
| Ethernet communications |  |  |
| EIA-232 Port A communications |  |  |
| EIA-232 Port B communications |  |  |
| EIA-232 Port C communications (on front of <br> Communications module) |  |  |
| MINOR Alarms |  |  |
| MAJOR Alarms |  |  |
| CRITICAL Alarms |  |  |
| Reference Signals and Selection |  |  |
| Clock Section |  |  |
| Output Section |  |  |
| System Stability and Accuracy (optional) |  |  |

## In this Chapter ...

- Responding to SSU-2000 Alarms
- Preventive Maintenance
- Corrective Maintenance
- Troubleshooting
- Re-ordering Information


## Chapter 7 Maintenance and Troubleshooting

This chapter provides preventive and corrective maintenance procedures, equipment re-ordering/ return procedures and troubleshooting procedures for the SSU-2000 system.

Note ..
Datum offers a 24 -hour technical support line and a 2-hour response time for each trouble call. For Customer Service, Call: (512) 721-4032 or (866) 638-7962 (866 NET-SYNC) during normal business hours (8 a.m. to 5 p.m. CST), or (512) 721-4000 after hours and on weekends, Fax: (512) 251-9685, or E-mail: austinsupport@datum.com.

### 7.1 Responding to SSU-2000 Alarms

The SSU-2000 monitors various system parameters and stores this information as alarms and event messages which is extremely useful in troubleshooting the system. If an alarm occurs, follow the troubleshooting procedures in Section 7.4, Troubleshooting, to clear the alarm.

### 7.2 Preventive Maintenance

The SSU-2000 requires no preventive maintenance. Care should be taken to ensure the unit is not exposed to hazards such as direct sunlight, open windows, or extreme heat. See Section 3.2.2, Electromagnetic Interference (EMI) Considerations, for other conditions that may cause damage.

Should the unit require cleaning, the exterior chassis may be wiped off using a soft cloth dampened with mild soapy water.

## Caution...

To avoid damage to the system, under no circumstances should the interior chassis of the SSU-2000 be allowed to come in contact with water.


## CAUTION ...

To avoid damage to the system, never attempt to vacuum the interior of the SSU-2000.


## Caution ...

To avoid the possibility of the lithium battery exploding in the Communications module or Clock modules, do not replace the battery. Return the entire module to Datum Service Department for battery replacement and disposal.

## Caution ...

To avoid electrostatic discharge (ESD) and damage to the internal circuitry, never attempt to vacuum the interior of the SDU-2000e. If damaged, return the unit to the Datum Service Department for corrective service.

## Caution ...

To avoid personal injury and electrostatic discharge (ESD) damage to equipment, follow the ESD precautions as listed in this guide.

### 7.3 Corrective Maintenance

The SSU-2000 and SDU-2000 have a modular design and field service is limited to replacing the FRUs (field replaceable units) identified in Table 7-1 and Table 7-2. These tables also outline possible component problems and corrective action. Refer to Section 7.5, Re-ordering Information for information on re-ordering, re-packing, or returning equipment to the factory.

## Warning ...

To avoid serious personal injury or death, exercise caution when working near high voltage lines. In particular:

- Use extreme caution when installing the GPS antenna near, under or around high voltage lines.
- Follow local building electrical codes for grounding the antenna system that is used with the SSU-2000e unit.


## CAUTION .

For continued fire protection, fuse the interface "A" power feeds at the power distribution source for ( $5 \mathrm{~A}-\mathrm{-z} \mathrm{vDC}$ ).
This unit must be grounded. Refer all servicing to qualified personnel.


## Caution ...

For continued EMC compliance, replace all deformed module gaskets with the same type. Clean gaskets and mating surfaces. Secure all modules with captive screws.

## Caution

To maintain EMC compliance, use only properly shielded cabling on all telecom signal wiring, including I/O, clocks, and Ethernet connections. Ensure that connections are appropriately grounded at both ends.

Table 7-1. $\quad$ SSU Corrective Action Table

| Component | Corrective Action | Part Number |
| :--- | :--- | :--- |
| Motherboard or Main Chassis Fault | Contact Datum Customer Service. | 25413020-000-0 |
| Defective Cable | Replace defective cable. | See Chapter 9, Hardware <br> Configuration Guide |
| Module Fault(s) | a. Check that module(s) is seated <br> correctly. <br> b. Address any fault LED lights. <br> c. If present, press RST button on <br> Comms module. <br> d. Check both Power A and Power B <br> inputs for a tripped breaker or blown <br> fuse on the input power control panel. <br> e. Replace module. <br> f. If unable to correct the problem, <br> contact Datum Customer Service. | All Modules |

Table 7-1. SSU Corrective Action Table (Continued)

| Component | Corrective Action | Part Number |
| :--- | :---: | :---: |
| Module Replacement |  | $23413012-000-0$ |
| Communications Module | $23413016-000-0$ |  |
| 2E Clock Module | $23413015-000-0$ |  |
| 3E Clock Module | $23413018-000-0$ |  |
| E1 Output Module | $23413013-001-0$ |  |
| 1-Port DS1 Input Module | $23413013-002-0$ |  |
| 3-Port DS1 Input Module | $23413017-000-0$ |  |
| DS1 Output Module | $23413014-001-0$ |  |
| 1-Port E1 Input Module | $23413014-002-0$ |  |
| 3-Port E1 Input Module |  |  |

Table 7-2. SDU Corrective Action Table

| Component | Corrective Action | Part Number |
| :---: | :---: | :---: |
| Motherboard or Main Chassis Fault | Contact Datum Customer Service. | 25413023-000-0 |
| Defective Cable | Replace defective cable. | 805SCSI-0050 (1 m cable; other lengths available |
| Module Fault(s) | a. Check that module(s) is seated correctly. <br> b. Address any fault LED lights. <br> c. If present, press RST button on Comms module. <br> d. Check both Power A and Power $B$ inputs for a tripped breaker or blown fuse on the input power control panel. <br> e. Replace module. <br> f. If unable to correct the problem, contact Datum Customer Service. | All Modules |
| Module Replacement |  |  |
| Buffer Module <br> E1 Output Module DS1 Output Module 2048 kHz Output Module Composite Clock Output Module |  | $\begin{aligned} & 25413022-000-0 \\ & 23413018-000-0 \\ & 23413017-000-0 \\ & 23413159-000-0 \\ & 23413158-000-0 \end{aligned}$ |

### 7.4 Troubleshooting

The SSU-2000 incorporates many alarms and event messages to alert that a possible problem exists. These alarm and event message reports can be accessed via the Comms module serial ports using a dumb terminal or PC. Communication may also be established using the RJ-45 Ethernet connector (ETHERNET 10-BASE-T) on the connector interface panel of the chassis. Section 5.2.1, Communicating by Serial Port, outlines the procedures for connecting to the SSU-2000 using the Come module serial ports. Section 5.2.2.2, Connecting through the Ethernet LAN, outlines the procedures for connecting via the Ethernet connection. Appendix A, Alarms and Events, details event and alarm descriptions, default event and alarm levels, status messages and corrective action.

### 7.4.1 Establishing a Connection



## Note ...

An SSU-2000 Administrator must be appointed prior to connecting to the system. The Administrator will assign User privileges and access codes. See Chapter 5, Operating and Provisioning Procedures for more details.

To perform troubleshooting on the SSU-2000, you must establish a serial connection to a terminal, laptop or PC with terminal emulation software. This is done using port A or B (located on the back panel), or the Local, located on the front panel of the communications module. If the SSU-2000 is connected to a LAN, an Ethernet telnet session may be established. Refer to Section 5.2.1, Communicating by Serial Port to establish a serial connection and Section 5.2.2.2, Connecting through the Ethernet LAN to establish an Ethernet connection.

### 7.4.2 Troubleshooting Guide

This section describes troubleshooting procedures for the SSU-2000. Table 7-3 details common system faults and the corrective action to correct the problem.

The modular design of the SSU-2000 offers a high level of stability and reliability. After installation and self-diagnostics, the majority of events and alarms can be attributed to fluctuations in signal quality, which may be self-clearing. Others may be caused by faulty hardware and software configurations. Regardless of the cause, hardware seldom needs to be replaced. If corrective action has been taken and the problem persists, call Customer Service.

```
#
Note ..
Datum offers a 24 -hour technical support line and a 2 -hour response time for each trouble call. For Customer Service, call (512) 721-4032 during our normal business hours (8 a.m. to 5 p.m. CST), or (512) 721-4000 after hours and on weekends.
```

When a Comms module is installed and functioning properly, it monitors the SSU-2000 and logs unit events into non-volatile memory for inspection at a later date. Events are conditions within the unit, or at the interfaces of the unit, which may indicate abnormal operation or a change in the unit's operational status.

Although every alarm is considered to be an event, not every event is an alarm. For example, a login is recorded as an event but is not considered to be an alarm. In this case, no action is required by the user. Recurring events may be escalated to alarm status and may require action by the user. Conversely, alarms may be de-escalated and corrected automatically. Section 7.3, Corrective Maintenance explains how to interpret status messages and take corrective action if needed.

### 7.4.3 Interpreting Status Messages

The SSU-2000e provides two types of status messages: alarm and event. The following sections describe these messages.

## Alarm Messages

With the exception of loss of power alarms (on main chassis and expansion unit) all alarms are module alarms. Table A-1 lists each module with corresponding alarm descriptions, alarm levels, status messages, and corrective action. Since a "no fault" alarm requires no action, the "Corrective Action" category applies only to fault messages requiring user intervention.

## Event Messages

Table A-2 lists event messages categorized by module. Each section lists status messages associated with each module and an event description of each message.

Figure 7-1 shows the structure of a typical Alarm and Event report status messages.


Figure 7-1. Alarm and Event Status Breakdown
Table 7-3 outlines SSU-2000 Troubleshooting Procedures.
Table 7-3. SSU-2000 Troubleshooting Procedures

| Symptom | Probable Cause | Troubleshooting Procedure/ <br> Corrective Action |
| :--- | :--- | :--- |
| No LED lit on any module | No power to unit | Check to ensure that UPS (if <br> applicable) is operating correctly. |
|  | Both A and B fuses are blown | Remove both fuses and replace. |
|  | Loss of ground | Re-attach ground wires. |
|  | Loose power cabling to unit | Check that power cables to unit are <br> securely fastened. |
|  | Main shelf is faulty | Contact Datum Customer Service. |

Table 7-3. SSU-2000 Troubleshooting Procedures (Continued)

| Symptom | Probable Cause | Troubleshooting Procedure/ Corrective Action |
| :---: | :---: | :---: |
| Unable to communicate with system | Loose cabling | Check that cabling is securely fastened. |
|  | Bad peripheral device configuration | Check that communication device is properly configured (refer to Section 7.4.1, Establishing a Connection, for more information). |
|  | Improperly installed or faulty Comms module | 1. Re-seat the Comms module. <br> 2. Press the RST button located on the front panel of module. <br> 3. If problem is not rectified, call Datum Customer Service. |
|  | Software emulator is configured to Com1, but cable is physically attached to Com2 | Either attach cable to Com1 or reconfigure software emulator to Com2. |
|  | Software emulator is set to 9600 baud, but system baud rate is 19,200. | Change to the software emulator to 19,200 baud. |
|  | Bad serial port(s) | Connect to another serial port. If none of the ports are functional, call Datum Customer Service. |
| Status LED on input module is amber | Firmware compromised | Press the RST button on front panel of Input module. |
| Fault LED on output module is lit | Loose module | Reseat module. |
|  | Loss of signal to output module | Reseat or replace input module (or clock module if necessary). |
|  | Line fault | Remove the Tx Cable |
|  | Improper redundancy configuration | Adjust accordingly. Main chassis: <br> - left slot = even <br> right slot = odd <br> Expansion chassis: <br> left slot = odd <br> right slot = even |
| Fault LED on output module is flashing amber | Fault on distribution cabling | Verify cabling is connected properly. Replace cabling. |
| No LED lit on modules | Power supply failure | Check connection to power supply. |
|  | Blown fuse | Replace module. |

Table 7-3. SSU-2000 Troubleshooting Procedures (Continued)

| Symptom | Probable Cause | Troubleshooting Procedure/ Corrective Action |
| :---: | :---: | :---: |
| No alarms being reported when there is an alarmed condition | Compromised firmware | Press RST on Comms module front panel. |
|  | Faulty Comms module | Replace Comms module. |
|  | Alarmed module is faulty | Replace module. |
| Loss of power from expansion chassis | No power to unit | Check to ensure that UPS (if applicable) is operating correctly. |
|  | Both $A$ and $B$ fuses on expansion chassis unit are blown | Remove fuses and replace. |
|  | Loss of ground | Re-attach ground wires. |
|  | Loose power cabling to expansion unit | Check that power cables to unit are securely fastened. |
|  | Expansion shelf is faulty | Call Customer Service. |
| Loss of signal from expansion chassis | D clock not connected while loose SDU cable to the expansion shelf | Check SDU cable and connect D clock. |
| Any source LED on the output module amber | Loss of clock signal | Ensure clock modules are inserted properly. |
|  | Clock modules are in warmup mode | No action necessary. |
| Any LED on input module amber | No signal to the input panel | Ensure signals are properly routed to the input panel. |
|  | No input signal on cable connected to input panel. | Replace no-signal cable with signaled cable. |
|  | I/O input adapter panel is not connected to the input module. | Connect the I/O input adapter panel to the input module. |
| No output signal on the output panel | Port is not turned on. | Use the interactive command to turn the port on. |
|  | The I/O output adapter panel is not connected to the output module. | Connect the I/O output adapter panel to the output module. |

### 7.4.4 Troubleshooting the SDU-2000e

The buffer module in the SDU-2000e collects status information from the Output modules and relays status messages to the SSU-2000e. The status messages alert the SSU-2000e when a possible problem exists; they can be accessed through the SSU-2000e using a terminal or PC using a terminal emulation software. Refer to Section 5.2, Establishing a Connection to the SSU-2000, for more information on connecting to an SSU-2000e for troubleshooting. Table 7-4 outlines troubleshooting procedures for the SDU-2000e.


## Note ...

If fault isolation and corrective action have been performed and the problem persists, contact Datum Customer Service. Datum offers a 24-hour technical support line and a 2 -hour response time for each trouble call. For Datum Customer Service, Call: 001-512-721-4000, Fax: 001-512-251-9685, or E-mail: austinsupport@datum.com

Table 7-4. SDU-2000e Troubleshooting Procedures

| Symptom | Probable Cause | Troubleshooting Procedure/Correc- <br> tive Action |
| :--- | :--- | :--- |
| Output module Fault <br> indicator is on | Loose module | Re-seat module. |
| Output module Fault <br> indicator is flashing Amber | Fault on distribution cabling | Verify that cabling is connected <br> properly. Replace cabling as needed. |
| Output module Source <br> indicator amber | Loss of clock signal | Ensure cabling to main chassis is <br> secure and correctly installed. |
|  | Clock modules in main <br> chassis are in Warm-up mode | No action necessary. |
| Indicators on any module <br> are not illuminated | No power to unit | Verify that there is power to BUS-A and <br> BUS-B, and that the power inputs are <br> providing the required -48/60 vDC to <br> the unit. |
|  | Loss of ground | Re-attach ground wires. |
|  | Loose power cabling to unit | Check that power cables to unit are <br> securely fastened. |
|  | Expansion shelf is faulty | Contact Datum Customer Service. |
| Loss of signal to/from <br> expansion chassis | Loose SDU cable to the <br> expansion chassis <br> Both clocks not connected | Check SDU cable. <br> Connect one or both clocks. |

### 7.5 Re-ordering Information

To re-order any module or accessory, contact the Sales Department at Datum. Supply the module or accessory name and its part number along with the purchase order number. A current list of SSU-2000 system components modules/accessories and their part numbers is provided in Chapter 9, Hardware Configuration Guide. Accessories are provided in Appendix E, Default Settings. For additional information, contact the Sales Department at Datum at: (512) 721-4032 during our normal business hours ( $8 \mathrm{a} . \mathrm{m}$. to 5 p.m. CST), or (512) 721-4000 after hours and on weekends, Fax: (512) 251-9685, or E-mail: austinsupport@ datum.com

### 7.5.1 Equipment Return Procedure

To return equipment to the factory or local representative for repair:

1. Call Customer Service at 1-512-721-4000 to obtain a return authorization before returning the product for service.
2. Provide a description of the problem, product item number, serial number, and warranty expiration date.
3. Provide the return shipping information (customer field contact, address, telephone number, and so forth.)
4. Ship the product to Datum, transportation prepaid and insured, with the Return Material Authorization (RMA) number and serial numbers clearly marked on the outside of the container to:

## Datum, Inc.

15811 Vision Drive
Pflugerville, TX 78660

## Attention: Service Department

### 7.5.2 Repacking

Use standard packing procedures to protect the SSU-2000 or any of the SSU-2000 modules during shipment. Connectors should be protected with connector covers or the instrument should be wrapped in plastic before packaging. Custom foam packing material is preferred because it conforms to the shape of the instrument. Take special care to protect the front and rear panels.

## IN THIS CHAPTER ...

- Stratum 2E Clock Module
- Stratum 3E Clock Module
- Communications Module
- 1-Port and 3-Port E1 Input Modules
- 1-Port and 3-Port DS1 Input Modules
- GPS Input Module
- 2048 kHz Output Module
- E1 Output Module
- DS1 Output Module
- Composite Clock Output Module
- I/O Adapter for 1-Port Input Module
- I/O Adapter for 3-Port Input Module
- Balun Output I/O Adapter for Output Module
- DE9 Output I/O Adapter Panel for Output


## Chapter 8 Module Reference Data

This chapter contains reference information for the various modules available for use in the SSU-2000 system.

The module types include:

- Stratum 2E Clock Module
- Stratum 3E Clock Module
- Communications Module
- 1-Port and 3-Port E1 Input Modules
- 1-Port and 3-Port DS1 Input Modules
- GPS Input Module
- 2048 kHz Output Module
- E1 Output Module
- DS1 Output Module
- Composite Clock Output Module

The I/O adapter panel types include:

- I/O Adapter for 1-Port Input Module
- I/O Adapter for 3-Port Input Module
- Balun Output I/O Adapter for Output Module
- DE9 Output I/O Adapter Panel for Output Module


### 8.1 Stratum 2E Clock Module

This section provides user reference information for the Stratum 2E Clock module.

### 8.1.1 Stratum 2E Clock Module Functional Overview

The Stratum 2E Clock module uses the Rubidium oscillator and meets or exceeds the performance requirements for ITU and ETSI Type II Transit Node clocks and ANSI and Telcordia Technologies (Bellcore) Stratum 2 clocks.

The Clock module reads measurement data from the Input modules, provides frequency control of the oscillators through DDS circuitry, and generates reference signals used by the input and Output modules.

A typical SSU-2000 system contains dual redundant Clock modules. Each Clock module maintains phase synchronization with the redundant Clock module. Its hardware and software also provides for temperature compensation, an initial offset adjustment, and frequency adjustment resolution of $1 \times 10-13$ or better.

With redundant Clock modules, one is selected as the master and the other as backup, with automatic switching on module removal or failure.

The master Clock module controls the operation of the Input and Output modules and downloads module configuration information to all modules (except for the Communications module), requests measurement data and status from the Input modules, and sets the Output modules to use currently selected clock signals. The Clock modules maintain an internal time-of-day clock that is used to time stamp events to within 0.1 second of detection of the event.

This module provides an 8 kHz signal used by the Input modules and a 4 kHz signal used by the Output modules. Each Clock module provides one set of signals for use by the modules in the main chassis, and a separate set for the expansion shelves.

### 8.1.2 Stratum 2E Clock Module Functional Block Diagram

A simplified block diagram of the Stratum 2E Clock module is shown in Figure 8-1.


Figure 8-1. Stratum 2E Clock Module Block Diagram

### 8.1.3 Stratum 2E Clock Module Status LED Indicators

The Stratum 2E Clock module status LED indicators are shown in Figure 8-2 and are described in Table 8-1.


Figure 8-2. Stratum 2E Clock Module Status LED Indicators

Table 8-1. Stratum 2E Clock Module Status LED Indicators

| Indicator | Color | Description |
| :--- | :--- | :--- |
| Power | Green | On = The Clock module is receiving power <br> Off = No power present |
| Status | Green/Amber | On (Green) = No faults detected <br> On Amber blinking = Clock module Is downloading firmware <br> On (Amber) = Unknown Clock module status or fault detected |
| Selected | Green | On = Module selected for providing outputs. <br> Off = Module not selected |

Table 8-1. Stratum 2E Clock Module Status LED Indicators

| Indicator | Color | Description |
| :--- | :--- | :--- |
| Warmup | Amber | $\mathrm{On}=$ Clock module is in warm-up mode <br> $\mathrm{Off}=$ Clock module has completed warmup |
| Acquire | Green | $\mathrm{On}=$ Clock module is acquiring a lock on a signal <br> $\mathrm{Off}=$ Not acquiring a lock on a signal |
| Locked | Green | $\mathrm{On}=$ Clock module is locked on a signal <br> $\mathrm{Off}=$ Clock module is not locked on a signal |
| Holdover | Amber | $\mathrm{On}=$ Clock module is in Holdover mode of operation <br> $\mathrm{Off}=$ Clock module is not in Holdover mode |

### 8.1.4 Stratum 2E Clock Module Functional Specifications

Table 8-2 lists the specifications for the Stratum 2E Clock module.

Table 8-2. Stratum 2E Clock Module Specifications

| Performance Characteristic | Specification |
| :--- | :--- |
| Free Running Accuracy | Within $\pm 5 \times 10^{-10}$ the first year <br> Within $\pm 5 \times 10^{-9}$ after 10 years |
| Holdover Stability (Rubidium LO) <br> 0 to 24 hrs, $@+10$ to $+50^{\circ} \mathrm{C}$ <br> 0 to 24 hrs, @ 0 to $+50^{\circ} \mathrm{C}$ <br> 30 days @ +10 to $+40^{\circ} \mathrm{C}$ <br> 30 days @ 0 to $+50^{\circ} \mathrm{C}$ | $\pm 9 \times 10 \mathrm{E}-11$ <br> $\pm 1 \times 10-10$ <br> $\pm 1.5 \times 10 \mathrm{E}-10$ <br> $\pm 1.7 \times 10 \mathrm{E}-10$ |
| Numeric Controlled Oscillator <br> (NCO) PLL lock range | $\pm 5 \times 10^{-4}$ |
| Tuning Resolution (Locked Mode) | $<1 \times 10^{-13}$ |
| Warm-up Time (Warm-up Mode) | 20 minutes |
| Wander Output (Holdover) | Includes effects of all SSU-2000 modules: <br> Compliant with clock levels per ITU-T G.812, T1.101-1999, and <br> Telcordia Technologies GR-378-CORE and GR-1244-CORE. <br> Meets SONET requirements per T1.105. <br> Meets or exceeds performance requirements for ITU-T G.812 <br> Type II and ETSI Transit Node clocks and T1.101 and Telcordia <br> Technologies (Bellcore) Stratum 2 clocks. |
| Jitter (Locked or Holdover) | $<4$ ns p-p (measured at the CLKA/BIN 8kHz output) |

### 8.1.5 Stratum 2E Clock Module Configuration Data

Table 8-3 contains a listing of software configuration options and factory defaults for the Stratum 2E Clock module.

Table 8-3. Stratum 2E Clock Module Options/Defaults

| Setting | Default | Range |
| :--- | :--- | :--- |
| Warmup Time | 1200 seconds | $900-3600$ seconds |
| Min Tau Limit | 300 seconds | Constant |
| Max Tau Limit | 10000 seconds | Constant |
| Min Tau | 300 seconds | In the range specified in Min/Max Tau limits |
| Max Tau | 9000 seconds | In the range specified in Min/Max Tau limits |
| Clk Switch AR | On | On/Off |
| Input Switch | AutoReturn (AR) | AR (2)/AS On (1)/AS Off (0) |
| Input Selection Mode | Priority | Priority (0)/PQL (1) |
| Local Oscillator (LO) | On | On/ Off |
| Frequency Offset | 57 ppb | Constant |
| Elevation Time | 86400 seconds | 60 to 500,000 seconds |

### 8.2 Stratum 3E Clock Module

This section provides user reference information for the Stratum 3E Clock module used in the SSU-2000. This module provides a lower cost backup clock solution for the system.

### 8.2.1 Stratum 3E Clock Module Functional Overview

The Stratum 3E Clock module meets or exceeds the performance requirements for ITU and ETSI Type III Local Node clocks and ANSI and Telcordia Technologies (Bellcore) Stratum 3E clocks.

The Stratum 3E Clock module receives measurement data from the Input modules, provides frequency control of the outputs through DDS circuitry, and generates a reference signal for use by the Input and Output modules. The Stratum 3E Clock module communicates with the Communications module and the Stratum 2E Clock module to maintain phase synchronization with the redundant Clock module. The Stratum 3E Clock module's hardware and software provides for temperature compensation, aging compensation for the Quartz oscillator, an initial offset adjustment, and frequency adjustment resolution of $1 \times 10^{-13}$ or better.

When serving as the master clock, the Stratum 3E Clock module controls the operation of the Input and Output modules and downloads module configuration information to all modules, requests measurement data and status from the Input modules, and sets the Output modules to use currently selected Clock signals. The Stratum 3E Clock module also contains a battery powered clock that maintains the clock for timestamping events. The Clock module software reads the clock on startup and sets the clock when the system time is changed. The timestamp is referenced as the number of seconds since 00:00:00 January $1,1980$.

### 8.2.2 Stratum 3E Clock Module Functional Block Diagram

A simplified block diagram of the Stratum 3E Clock module is provided in Figure 8-3.


Figure 8-3. Stratum 3E Clock Module Block Diagram

### 8.2.3 Stratum 3E Clock Module Status LED Indicators

The Stratum 3E Clock module status LED indicators are shown in Figure 8-4 and listed and are described in Table 8-4.


Figure 8-4. Stratum 3E Clock Module Status LED Indicators

Table 8-4. Stratum 3E Clock Module Status LED Indicators

| Indicator | Color | Description |
| :--- | :--- | :--- |
| POWER | Green | On = The Clock module is receiving power <br> Off = No power present |
| STATUS | Green/Amber | On (Green) = No faults detected <br> On (Amber) blinking = Clock module is downloading firmware <br> On (Amber) = Unknown Clock module status or fault detected |
| SELECTED | Green | On = Module selected for providing outputs <br> Off = Module not selected |

Table 8-4. Stratum 3E Clock Module Status LED Indicators (Continued)

| Indicator | Color | Description |
| :--- | :--- | :--- |
| WARMUP | Amber | On = Clock module is in warm-up mode <br> Off = Clock module has completed warmup |
| ACQUIRE | Green | On = Clock module is acquiring a lock on a signal <br> Off = Not acquiring a lock on a signal |
| LOCKED | Green | On= Clock module is locked on a signal <br> Off = Clock module is not locked on a signal |
| HOLDOVER | Amber | On = Clock module is in holdover mode of operation <br> Off = Clock module is not in holdover mode |

### 8.2.4 Stratum 3E Clock Module Functional Specifications

Specifications for the Stratum 3E Clock module are provided in Table 8-5.

Table 8-5. Stratum 3E Clock Module Functional Specifications

| Performance Characteristic | Specification |
| :--- | :--- |
| Free Running Accuracy | Within $\pm 2.5 \times 10^{-7}$, the first year (vendor spec) <br> Within $\pm 3.7 \times 10^{-6}$ after 20 years (vendor spec) |
| Holdover Stability <br> 0 to 24 hrs, @ +10 to $+50^{\circ} \mathrm{C}$ <br> 0 to 24 hrs, @ 0 to $+50^{\circ} \mathrm{C}$ | $\pm 5 \times 10^{-9}$ <br> $\pm 1 \times 10^{-8}$ |
| Numeric Controlled Oscillator (NCO) <br> PLL lock range | $\pm 5 \times 10^{-4}$ |
| Tuning Resolution (Locked Mode) | $<1 \times 10^{-13}$ |
| Warm-up Time (Warm-up Mode) | 20 minutes |
| Wander Output (Holdover) | Includes effects of all SSU-2000 modules: <br> Exceeds requirements of (ANSI) T1.101-1994, T1.105.09, ITU <br> G.811, T1X1.3 (proposed new limits for wander generation), <br> and G.823 |
| Jitter (Locked or Holdover) | $<4$ ns p-p (measured at the CLKA/BIN 8 kHz output) |

### 8.2.5 Stratum 3E Clock Module Configuration Data

The Stratum 3E Clock Module is software configurable through one of the serial or Ethernet ports. The default values and the ranges for the configurable parameters are listed in Table 8-6.

Table 8-6. Stratum 3E Clock Default Values and Ranges

| Setting | Default | Range |
| :--- | :--- | :--- |
| Warmup Time | 1200 seconds | 900 to 3600 seconds |
| Min Tau Limit | 300 seconds | Constant |
| Max Tau Limit | 500 seconds | Constant |
| Min Tau | 300 seconds | In the range specified in Min/Max Tau limits |
| Max Tau | 450 seconds | In the range specified in Min/Max Tau limits |
| Clk Switch AR | On | On/ Off |
| Input Switch | AutoReturn (AR) | AR (2)/AS On (1)/AS Off (0) |
| Input Selection Mode | Priority | Priority (0)/PQL (1) |
| Local Oscillator (LO) | On | On/Off |
| Frequency Offset | 57 ppb | Constant |
| Elevation Time | 86400 seconds | 60 to 500,000 seconds |

### 8.3 Communications Module

This section provides reference information on the Communications module that functions as a master controller for the SSU-2000 system.

### 8.3.1 Communications Module Functional Overview

The Communications module installs in slot A2 and provides an interface between the user and the SSU-2000 system. This interface allows users to display and control much of the activity in the SSU-2000 system and the optional SDU-2000 expansion system. The Communications module supports three serial ports (including one local craft port) and one Ethernet port, and allows communication over each of them independently in one of several possible modes (ASCII mode, TL1 mode, and packet mode).

The software in the Communications module allows for reprogramming of its flash ROM and for reconfiguration of all programmable logic devices, while installed at the user's location. The Communications module also allows for this same capability for all other modules installed in the SSU-2000 system by downloading it through the Communications module.

When the Communications module is installed, it performs an initial software verification test to verify operation. If the module is installed in the SSU-2000 with power already applied and with other modules installed, the Communications module reads the configuration of the modules in the SSU-2000 and the modules in all installed SDU-2000 expansion shelves. This information is saved in nonvolatile memory on the Communications module. If power is applied to the SSU2000 after the Communications module is installed, it initializes before any other module and provides configuration information to the individual modules.

The master controller function for the SSU-2000 can reside in the Communications module or in either of the Clock modules. The priority of the selection of the module that will provide the master controller function rests with the Communications module, Clock A, and Clock B, in that order. In the event of removal of the module designated as the master controller, that function automatically and seamlessly switches to the next module in priority order.

All man/machine communications are controlled by the Communications module. This module then communicates with the other modules in the SSU-2000 to read configuration data, set operational parameters, and determine what type of modules are installed. When a module is replaced, the controller loads the correct operational parameters into the replacement module.

### 8.3.2 Communications Module Functional Block Diagram

A simplified block diagram of the Communications module is shown in Figure 8-5.


Figure 8-5. Communications Module Block Diagram

### 8.3.3 Communications Module Status LED Indicators

The module contains a group of eight status LED indicators that convey visual status to the user, as shown in Figure 8-6 and described in Table 8-7.

ssu00032
Figure 8-6. Communications Module Status LED Indicators

Table 8-7. Communications Module Status LED Indicators

| Indicator | Color | Description |
| :--- | :--- | :--- |
| Power | Green | On = The module is receiving power <br> Off = No Power Present |
| Status | Green/Amber | On (Green) = No faults detected <br> On (Amber) Blinking = Module is downloading firmware <br> On (Amber) = Module fault detected |

## Table 8-7. Communications Module Status LED Indicators (Continued)

| Indicator | Color | Description |
| :--- | :--- | :--- |
| -48 vDC <br> A and Bower | Green | On = Power connected <br> Off = Power not connected |
| Critical Alarm | Red | On = System alarm is set to Critical <br> Off = No critical system alarm |
| Major Alarm | Amber | On = Major system alarm <br> $\mathrm{Off}=$ No major system alarm |
| Minor Alarm | Amber | On = Minor system alarm <br> Off = No minor system alarm |
| Ethernet Link | Green | On = Physical Ethernet connection is made <br> Off = No physical Ethernet connection |

### 8.3.4 Communications Module Alarm Logic

Events are an indication that something has occurred within the unit. Alarms are a subset of events. All alarms are events, but not all events are alarms. All events log the following information:

- Timestamp
- Event type
- Event/alarm level
- Condition that caused the event


## Communications Module Event Log

The Communications module maintains an event history of the last 500 events in non-volatile RAM that can be retrieved by the user. In the interactive mode, the Communications module always returns the events with the last generated event output last.

Using one of the available communication ports, a user can request the following:

- List of events by a given type of REPORT or ALARM
- List of events based upon a start and stop time
- Clear the event log

Interactive mode ports can request:

- Latest event logged
- A number of last events be displayed
- All information currently logged in the history buffer


## Alarm Levels

The Communications module alarm logic incorporates three alarm levels:

- CRITICAL Alarms - This class of alarms requires immediate user intervention. When a critical alarm condition is detected, the CRITICAL ALARM relay at the back of the SSU-2000 is activated and the CRITICAL ALARM LED on the front of the Communications module lights red.
- MAJOR Alarms - A class of alarms that may require immediate user intervention. When a major alarm condition is detected, the major alarm relay at the back of the SSU-2000 is activated and the MAJOR ALARM LED on the front of the Communications module lights red.
- MINOR Alarms - A class of alarms that indicate the unit performance is degrading. The minor relay is activated and the MINOR ALARM indicator lights.

Alarms are elevated from MINOR to MAJOR to CRITICAL on a per module basis with a user-set time, from 60 to 500,000 seconds, default is ( 86,400 seconds or one day). The elevation time is kept in each module.

The user can select delay periods for software alarms from 0 to 86400 seconds. Changing the delay period generates an event. The setting is stored in each module. Note: if the original value is set to IMMED ( -1 ), it means this error delay is not allowed to change and will happen immediately.

Table 8-8 lists and describes the Communications module alarms.

Table 8-8. Communications Module Alarms

| ID | Description | Alarm Level | Error Delay <br> Default | Error Delay <br> Settable |
| :--- | :--- | :--- | :--- | :--- |
| $0 \times 0$ | Backplane Communication Errors | MINOR | 5 sec | Yes |
| $0 \times 1$ | Mastership Problems | MINOR | 5 sec | Yes |
| $0 \times 2$ | Loss of Power A | MINOR | Immed | No |
| $0 \times 3$ | Loss of Power B | MINOR | Immed | No |
| $0 \times 4$ | SPI Watchdog Timeout | MAJOR | Immed | No |

### 8.3.5 Communications Module Configuration Data

Table 8-9 lists the factory default settings and ranges for the communication module software configuration options.

Table 8-9. Communications Module Configuration Data

| Configuration Setting | Factory Default |
| :--- | :--- |
| Unit Name | SSU-2000 |
| Module Information <br> configurations | Current Configuration - the configuration that is currently in use <br> User Default Configuration - configuration the user specifies as the <br> default if the current configuration is invalid or not present <br> Factory Configuration - the factory default configuration |
| User List configurations | Maximum of 25 users including four built-in users |
| EIA-232-C Port | All comm ports are set to 9600 baud, Interactive Mode, CRLF, and Echo on <br> Five minutes for all (Interactive Mode). (Note: the unit should have one <br> user added. I.e. Not in the INITUSERTABLE state). If it is in the <br> INITUSERTABLE state, no timeout is applied <br> No Timeout is assigned for the TL1 Mode |
| Eomms Port Timeout | IP Address 0.0.0.0 <br> Gateway Address 0.0.0.0 <br> Network Mask 255.255.255.0 IP Address |

### 8.3.6 RS-232 Ports

The Communications module implements four RS-232 ports that provide for local and remote communications with the SSU-2000 system.

A user interface (software resident in the Communications module) provides various levels of password-protected access for configuration and detailed performance monitoring and diagnostics. Use either the interactive command set or the TL1 user interface for configuring and detailed performance monitoring, see Appendix B, Communications Protocol.

The ports include:

- Port A and Port B - Tied to external connectors on the rear panel of the SSU-2000 Main chassis.
- One local port - Tied to the connector on the front panel of the Communications module.
- Backplane communications port - Used to communicate with other modules in the system.


### 8.3.7 Ethernet Port

The Communications module implements one Ethernet port (ETHERNET 10-BASE-T) that is routed to an RJ-45 connector on the back of the main chassis. For more information on Ethernet settings, see Section 5.2.2, Communicating by Ethernet.

### 8.4 1-Port and 3-Port E1 Input Modules

This section describes the 1-port and 3-port E1 Input modules that may be installed in an SSU-2000 system.

### 8.4.1 E1 Input Module Functional Overview

The 1-Port and 3-port E1 Input modules receive signals and performs phase measurement comparisons with the Clock modules that are installed in the SSU-2000. The Clock modules use this information to phase and frequency lock to the incoming signal. The data may also be used for monitoring the frequency of incoming signals.

The input ports accept one (1-Port Input modules), or three (3-Port Input modules) of the following signals: sine or square wave, with a frequency of $1,1.544,2.048,5$ or 10 MHz , or framed communication type E 1 . If the input signal is a communications type, the module monitors for Alarm Indication Signaling (AIS), Bipolar Violations (BPVs), Loss of Signal (LOS) and Out Of Frame (OOF) errors. In addition, the module extracts Synchronization Status Messages (SSMs) from the incoming framed signals.

The E1 Input module receives signals and performs phase measurement comparisons (at a sampling rate of 40 Hz ) with the Clock modules that are installed in the SSU-2000. The Clock modules use this information to phase lock to the incoming signal. The data may also be used for monitoring the frequency of incoming signals.

### 8.4.2 1-Port and 3-Port E1 Input Modules Functional Block Diagram

A simplified block diagram of the E1 X-Port Input modules is shown in Figure 8-5.


Figure 8-7. 1-Port and 3-Port E1 Input Modules Block Diagram

### 8.4.2.1 Phase Measurement Averages

The Input module also maintains averages of past phase measurements including:

- 7000100 -second averages
- 7001000 -second averages
- 7010000 -second averages

To account for momentary jumps in phase, the Input module uses a phase buildout algorithm for phase jumps greater than or equal to 1 microsecond per tenth of a second. To prevent confusing frequency offsets with phase jumps, the phase build out algorithm does not build out more than eight consecutive samples. If the phase is build out, the Input module sends an event message to the Communications module.

The firmware running in the E1 Input module performs the following functions:

- Determines module type (distinguishes between E1 and DS1 frame chips)
- Supports unframed clock signals at the following rates: $1 \mathrm{MHz}, 1.544 \mathrm{MHz}, 2.048 \mathrm{MHz}$, 5.0 MHz, 10.0 MHz
- Enables/disables the Input module on command (when disabled, it does not report any alarms or measurement data and blinks the STATUS LED repeatedly)
- Enables or disables individual ports on command (disabled ports clear all existing alarms and do not report any additional alarms or measurement data)
- Maintains a provisioned SSM for each port
- Stores a priority for each port


### 8.4.2.2 Three-Sigma Test

The Input module uses a three-sigma test as part of the phase averaging algorithm in order to avoid the use of erroneous phase readings. In such tests, the standard deviation sigma of the phase readings is maintained. Any reading which falls more than three sigma above or below the mean is considered erroneous.

### 8.4.2.3 MTIE Calculation

MTIE is a measurement of the relative noisiness of an input signal. The Input module automatically (without user intervention) calculates MTIE for its inputs in accordance with the specifications in (ANSI) T1.101 and reported on demand for a 24 hour period.

MTIE data is retrieved on hour boundaries, though the stop time used may be current time. Reported time periods include: $0.05,0.1,1.0,10.0,100.0,1000.0,10000.0$, and 100000.0 seconds.

### 8.4.2.4 MTIE Alarms

The Input module monitors the ongoing MTIE calculations and logs an alarm if the MTIE calculation for any of several window sizes exceeds user-set masks.

The input module software maintains two alarm masks, each with thresholds at $10,100,1000$, 10,000 , and 100,000 seconds. MTIE readings which violate either mask at any point cause an alarm at a user-set level (Minor, Major, or Critical). Refer to Section 5.6.2, Changing Factory Defaults for more information on setting alarm levels.

Although MTIE is continuously calculated against both clocks, MTIE alarms are logged only if the measurements against the currently selected clock violate one of the MTIE alarm masks.

### 8.4.2.5 TDEV Calculation

The Input module automatically (without user intervention) calculates TDEV (the measurement of the frequency components in a series of phase readings) for all its inputs and reports on the past 24 hours of TDEV history. TDEV is retrieved on hour boundaries, though the stop time used may be current time.

Reported time periods include: $0.05,0.10,0.30,0.60,1.0,2.0,3.0,6.0,10.0,30.0,60.0,100.0$, $300.0,600.0,1000.0,3000.0,6000.0$, and 10000.0 seconds

The E1 Input module also contains provisions for zeroing the phase readings for one channel in response to a command from the Communications module. Once the phase is zeroed, all subsequent phase measurements are expressed in terms of how much they differ from the reading at the time the phase was zeroed.

Zeroing the phase invalidates all past phase averages, TDEV, and MTIE.

### 8.4.2.6 Sync Status Messages

The E1 Input module reads and processes Sync Status Messages (in accordance with specification ITU-T Composite Clock (CC) for E1 signals), to determine the traceability of inputs. This traceability information is then used by the Clock modules in selecting a reference signal and embedded into the system's outputs. For E1 inputs, an SSM is valid if three consecutive matching SSMs are received.

### 8.4.2.7 SSM Selection Criteria

If the E1 Input module is configured for provisioned mode, it will use the provisioned SSM. If configured for automatic mode, the Input module uses the most recent valid SSM. If a valid SSM is not received, the module uses the provisioned SSM. Refer to Section E.3, DS1 and E1 Input Module Default Configuration for more information on provisioning SSM's.

### 8.4.2.8 E1 Input Module Alarm Modes

The E1 Input module responds to various alarm conditions according to user-set alarm levels. Each level is associated with a set of actions as follows:

Table 8-10. E1 Input Module Alarm Modes

| Alarm Mode | Action | Alarm Elevation |
| :--- | :--- | :--- |
| IGNORE | Do nothing | Cannot be elevated to a higher severity level |
| REPORT | Do nothing | Cannot be elevated to a higher severity level |
| MINOR | Generate event message | Elevate to Major if the alarm condition persists beyond <br> the user-set elevation time limit |

Table 8-10. E1 Input Module Alarm Modes (Continued)

| Alarm Mode | Action | Alarm Elevation |
| :--- | :--- | :--- |
| MAJOR | Generate event message | Elevate to Critical if the alarm condition persists beyond <br> the user-set elevation time limit |
| CRITICAL | -Generate event <br> message <br> Fault Port | Cannot be elevated as there is no higher severity level |

### 8.4.2.9 E1 Input Module Hardware Alarms

The following alarms are generated due to hardware problems:

- External Clock Signal PLL Unlocked
- Report event message and perform any other actions as required by the user-set severity level
- Fault channel, even if severity is less than MAJOR
- Monitor PLL for recovery
- Input Signal PLL Unlocked
- Report event message and perform other actions as required by severity
- Fault port, regardless of severity.
- Monitor PLL for recovery
- Phase Measurement Circuitry Fault
- Report event message and perform any other required actions
- Fault Port
- Monitor phase hardware for recovery


### 8.4.2.10 E1 Input Signal Glitches

The following alarms are caused by problems with the incoming input signal's formatting or content:

- Errors Tracked:
- Framed signals: LOS, AIS, OOF, BPV and CRC
- Unframed signals: LOS


## - Error and Clear Counters

The E1 Input module maintains a count of the number of consecutive errored seconds for each error type for each port. Once this error count exceeds a user-set limit, the input signal which has experienced the errors said to be in episode. Refer to Section 5.6.2, Changing Factory Defaults, for more information on setting the error count.

The Input module maintains a count of the number of consecutive seconds in which the input signal for each port was free of each type of error. This clear count must exceed a user-set limit before the input signal is no longer in episode. Refer to Section 5.6.2, Changing Factory Defaults, for more information on setting the clear count.

### 8.4.2.11 E1 Input Signal Glitch Handling

For LOS (loss of signal) and before going into episode:

- Coast over brief occurrences of LOS, reporting the last known good phase measurements for the port until signal returns or the signal goes into episode
- The duration of a brief occurrence of LOS is defined by the value of the error count for LOS. The default is 10 seconds.

Once in episode:

- Log LOS alarm, taking appropriate action per the assigned severity level
- Invalidate current phase measurements

Others (AIS, BPV, CRC, and OOF)
Once in episode, the system takes appropriate action according to the severity level assigned to the alarm.

LOS Phase Considerations:

- Phase reading not valid when in episode
- Zero phase reading when episode ends
- If signal returns before the port goes into episode, normalize subsequent phase measurements to show continuous phase numbers before and after the loss of signal.
- Others
- Phase reading valid


### 8.4.2.12 Hierarchy of Signal Glitches

- LOS
- AIS
- OOF
- BPV/CRC

The Input module does not report lower alarms if upper alarms are active.

### 8.4.2.13 Cesium Fault

- Facilitates compatibility with older Hewlett Packard units
- Only valid if port one is configured to receive an unframed input signal
- User can select high or low logic level as alarmed
- If the hardware indicates that the cesium fault level matches the alarmed setting, $\log$ an AIS alarm against port 1
- Clear the alarm when the hardware's cesium fault level no longer matches the alarmed level


### 8.4.2.14 Input Measurement Problems

If the MTIE values for a selected clock exceed either of the MTIE masks, the Input module takes appropriate action according to the severity level associated with the MTIE alarms. If a received SSM has a lower PQL than the provisioned value assigned to the port and the port has SSMs enabled, the Input module performs the action required by the alarm mode.

### 8.4.2.15 E1 Input Module Events Reported

The E1 Input module reports the event types listed in Table 8-11 when they occur:

Table 8-11. E1 Input Module Event Reporting

| Event | Parameter One | Parameter Two |
| :--- | :--- | :--- |
| Module installed | - | - |
| Module enabled | - | - |
| Module disabled | - | - |
| Module restarted | Delay before restart (in seconds) | - |
| Input Signal Episode, <br> Alarm, and Faults | - | - |
| Hardware Faults | - | - |
| Received SSM Changed | New PQL | Old PQL |
| Phase Buildout | Phase value being built out | Corrected phase value |
| Configuration Changes | New Value (if necessary) | Old Value (if not implied by new <br> value) |
| Input phase zeroed | - | - |

### 8.4.3 E1 Input Module Status LED Indicators

The E1 Input module is equipped with a set of status LED indicators that indicate module and incoming signal status. These LEDs are shown in Figure 8-8 (3-port model illustrated) and described in Table 8-12.


Figure 8-8. E1 Input Module Status LED Indicators

Table 8-12. E1 Input Module Status LED Indicators

| Indicator | Color | Description |
| :--- | :--- | :--- |
| POWER | Green | On = The module is receiving +5 vDC |
| STATUS | Green/Amber | Green = Unit is in Normal mode of operation; no faults <br> Amber = Fault condition detected |
| PORT 1 REF | Green/Amber | On (Green) = Selected <br> On (Amber) = Not good and ignored <br> Off = ignored or good and not selected |
| PORT 1 INPUT | Green/Amber | On (Green) = Selected <br> On (Amber) = Not good and ignored <br> Off = ignored or good and not selected |
| PORT 2 REF | Green/Amber | On (Green) = Selected <br> On (Amber) = Not good and ignored <br> Off = ignored or good and not selected |
| PORT 2 INPUT | Green/Amber | On (Green) = Selected <br> On (Amber) = Not good and ignored <br> Off = ignored or good and not selected |
| PORT 3 REF | Green/Amber | On (Green) = Selected <br> On (Amber) = Not good and ignored <br> Off = ignored or good and not selected |
| PORT 3 INPUT | Green/Amber | On (Green) = Selected <br> On (Amber) = Not good and ignored <br> Off = Ignored or good and not selected |

### 8.4.4 E1 Input Module Configuration

The E1 input module maintains factory default and current user configuration information in nonvolatile memory. This information is retrieved at power up and modified by commands from the communication module. In the event that the current user configuration cannot be used, the module automatically reverts to factory defaults.

### 8.4.5 E1 Input Module Software Options

The factory settings and ranges for all E1 Input Module software parameters are listed in Table 8-13.

Table 8-13. E1 Input Module Configuration

| Configuration Setting | Factory Default | Range |
| :---: | :---: | :---: |
| Framing Enabled | On/On/Off | On/Off |
| Input Frequency (for unframed signals) | 10MHz | $1 \mathrm{MHz}, 1.544 \mathrm{MHz}, 2.048 \mathrm{MHz}, 5 \mathrm{MHz}, 10 \mathrm{MHz}$ |
| Framing Type | CCS | CAS or CCS |
| Zero Suppression | On | On/Off |
| CRC | Off | On/Off |
| SSM | Off | On/Off |
| Provisioned PQL | 3/4/3 | 1-16 |
| Priority | 0 | 0 to 10 (0 = Monitor) |
| E1 Bit Position | 8 | 4 to 8 |
| Cesium Fault Nominal | Low | Low/High/Off |
| Input Signal Error Limit | 10 seconds | 1 to 100 for LOS and AIS, 1 to 10000 for BPV, CRC and OOF |
| MTIE T10 Limit1 | 325/1000/325 | 0 to 100000 |
| MTIE T10 Limit2 | 330/1010/330 | 0 to 100000 |
| MTIE T100 Limit 1 | 550/2000/550 | 0 to 100000 |
| MTIE T100 Limit 2 | 560/2010/560 | 0 to 100000 |
| MTIE T1000 Limit1 | 1010/2000/1010 | 0 to 100000 |
| MTIE T1000 Limit2 | 1020/2010/1020 | 0 to 100000 |
| MTIE T10000 Limit 1 | 1100/2835/1100 | 0 to 100000 |
| MTIE T10000 Limit 2 | 1110/2840/1110 | 0 to 100000 |
| MTIE Limit 1 Alarm Mode | Minor | Ignore, Report, Minor, Major, or Critical |
| MTIE Limit 2 Alarm Mode | Major | Ignore, Report, Minor, Major, or Critical |
| Alarm Initial Severity | Minor (except LOS and level 2 MTIE, which are Major) | Ignore, Report, Minor, Major, or Critical |
| Alarm Initial Delay | 0 seconds | 0 to 86400 seconds |
| Alarm Elevation Time | 86400 seconds | 0 to 500000 seconds |
| Port Status | Disabled | Enabled/Disabled |
| Port Name |  | Any user-selected string from 0 to 20 characters |

## $8.5 \quad$ 1-Port and 3-Port DS1 Input Modules

This section describes the 1-port and 3-port DS1 Input modules that may be installed in an SSU2000 system.

The 1-Port and 3-port DS1 Input modules receive signals and perform phase measurement comparisons with the Clock modules that are installed in the SSU-2000. The Clock modules use this information to phase and frequency lock to the incoming signal. The data may also be used for monitoring the frequency of incoming signals.

The input ports accept one (1-Port Input modules), or three (3-Port Input modules) of the following signals: sine or square wave, with frequency of $1,1.544,2.048,5$ or 10 MHz , or framed communication type DS1. If the input signal is a communications type, the module monitors for Alarm Indication Signaling (AIS), Bipolar Violations (BPVs), Loss of Signal (LOS) and Out Of Frame (OOF) errors. In addition, the module extracts Synchronization Status Messages (SSMs) from the incoming data.

### 8.5.1 DS1 Input Module Functional Overview

The DS1 Input module (1-port and 3-port versions) consists of a microcontroller and firmware, SRAM for data storage, FLASH (contains the firmware), input signal ports, and other support circuitry. The primary function of these modules is to perform time-interval-measurements on Clock module A and Clock module B, using the reference input signals. These measurements are used to adjust the frequency of the oscillators on the two Clock modules.

### 8.5.2 1-Port and 3-Port DS1 Input Modules Functional Block Diagram

A simplified block diagram of the DS1 X-Port Input modules is shown in Figure 8-5.


Figure 8-9. 1-Port and 3-Port DS1 Input Modules Block Diagram

### 8.5.2.1 Phase Measurement Averages

The Input module also maintains averages of past phase measurements including:

- 1000 one-second averages
- 1000100 -second averages
- 1001000 -second averages
- 10 10000-second averages

To account for momentary jumps in phase, the Input module uses a phase buildout algorithm for phase jumps greater than or equal to 1 microsecond per tenth of a second. To prevent confusing frequency offsets for phase jumps, the phase build out algorithm does not build out more than eight consecutive samples. If the phase is build out, the Input module sends an event message to the Communications module.

### 8.5.2.2 Three-Sigma Test

The Input module uses a three-sigma test as part of the phase averaging algorithm in order to avoid the use of erroneous phase readings. In such tests, the standard deviation, sigma, of the phase readings is maintained. Any reading which falls more than three sigma above or below the mean is considered erroneous.

### 8.5.2.3 MTIE Calculation

MTIE is a measurement of the relative noisiness of an input signal. The Input module automatically (without user intervention) calculates MTIE for its inputs in accordance with the specifications in (ANSI) T1.101 and reported on demand for a 24 hour period.

MTIE data is retrieved on hour boundaries, though the stop time used may be current time. Reported time periods include $0.05,0.1,1.0,10.0,100.0,1000.0,10000.0$, and 100000.0 seconds.

### 8.5.2.4 MTIE Alarms

The Input module monitors the ongoing MTIE calculations and logs an alarm if the MTIE calculation for any of several window sizes exceeds user-set masks.

The Input module software maintains two alarm masks, each with thresholds at 10, 100, 1000, and 10000 seconds. MTIE readings which violate either mask at any point cause an alarm at a user-set level. Refer to Section 5.6.2, Changing Factory Defaults, for more information on setting alarm levels.

Although MTIE is continuously calculated against both clocks, MTIE alarms are logged only if the measurements against the currently selected clock violate one of the MTIE alarm masks.

### 8.5.2.5 TDEV Calculation

The Input module automatically (without user intervention) calculates TDEV (the measurement of the frequency components in a series of phase readings) for all its inputs and reports on the past 24 hours of TDEV history. TDEV is retrieved on hour boundaries, though the stop time used may be current time.

Reported time periods include $0.05,0.10,0.30,0.60,1.0,2.0,3.0,6.0,10.0,30.0,60.0,100.0$, $300.0,600.0,1000.0,3000.0,6000.0$, and $10,000.0$ seconds.

The input card also contains provisions for zeroing the phase readings for one channel in response to a command from the Communications module. Once the phase is zeroed, all subsequent phase measurements are expressed in terms of how much they differ from the reading at the time the phase was zeroed.

Zeroing the phase invalidates all past phase averages, TDEV, and MTIE.

### 8.5.2.6 Sync Status Messages

The Input module reads and processes Sync Status Messages (in accordance with specifications (ANSI) T1.403 for DS1 signals), to determine the traceability of inputs. This traceability information is then used by the Clock modules in selecting a reference signal and embedded into the system's outputs.

For a DS1 input signal, an SSM is considered valid only after seven of the last ten received SSMs match. For DS1 signals, the Input module logs an alarm (user-set level) if 10 seconds elapse and no SSM is detected.

### 8.5.2.7 SSM Selection Criteria

If the Input module is configured for provisioned mode, it will use the provisioned SSM. If configured for automatic mode, the Input module uses the most recent valid SSM. If a valid SSM is not received, the module uses the provisioned SSM. Refer to Section 5.6.2, Changing Factory Defaults, for more information on SSM settings.

### 8.5.2.8 DS1 Input Module Alarm Modes

The Input module responds to various alarm conditions according to user-set alarm levels. Each level is associated with a set of actions (or non-actions) as shown in Table 8-14:

Table 8-14. DS1 Input Module Alarm Modes

| Alarm Mode | Action | Alarm Elevation |
| :--- | :--- | :--- |
| IGNORE | Do nothing | Cannot be elevated to a higher severity level |
| REPORT | Do nothing | Generate event message |
| MINOR | Elevate to Major if the alarm condition persists beyond <br> the user-set elevation time limit |  |
| MAJOR | Generate event message | Elevate to Critical if the alarm condition persists beyond <br> the user-set elevation time limit |
| CRITICAL | - Generate event <br> message | Cannot be elevated as there is no higher severity level |

### 8.5.2.9 DS1 Input Module Hardware Alarms

The following alarms are generated due to hardware problems:

- External Clock Signal PLL Unlocked
- Report event message and perform any other actions as required by the user-set severity level
- Fault channel, even if severity is less than MAJOR
- Monitor PLL for recovery
- Input Signal PLL Unlocked
- Report event message and perform other actions as required by severity
- Fault port, regardless of severity
- Monitor PLL for recovery
- Phase Measurement Circuitry Fault
- Report event message and perform any other required actions
- Fault Port
- Monitor phase hardware for recovery


### 8.5.2.10 DS1 Input Signal Glitches

The following alarms are caused by problems with the incoming input signal's formatting or content:

- Errors Tracked:
- Framed signals: LOS, AIS, OOF, BPV and CRC
- Unframed signals: LOS
- Error and Clear Counters

The Input module maintains a count of the number of consecutive errored seconds for each error type for each port. Once this error count exceeds a user-set limit, the input signal which has experienced the errors is said to be in episode.

The Input module maintains a count of the number of consecutive seconds in which the input signal for each port was free of each type of error. This clear count must exceed a user-set limit before the input signal is no longer in episode.

### 8.5.2.11 DS1 Input Signal Glitch Handling

For LOS (loss of signal) and before going into episode:

- Coast over brief occurrences of LOS, reporting the last known good phase measurements for the port until signal returns or the signal goes into episode
- The duration of a brief occurrence of LOS is defined by the value of the error count for LOS

Once in episode:

- Log LOS alarm, taking appropriate action per the assigned severity level
- Invalidate current phase measurements

Others (AIS, BPV, CRC, and OOF)
Once in episode, take appropriate action according to the severity level assigned to the alarm.
LOS Phase Considerations:

- Phase reading not valid when in episode
- Zero phase reading when episode ends
- If signal returns before the port goes into episode, normalize subsequent phase measurements to show continuous phase numbers before and after the loss of signal
- Others
- Phase reading valid


### 8.5.2.12 Hierarchy of Signal Glitches

The following alarms are listed in the order of most to least severe:

- LOS
- AIS
- OOF
- BPV/CRC

The Input module does not report lower level alarms if higher level alarms are active.

### 8.5.2.13 Cesium Fault

- Facilitates compatibility with older Hewlett Packard units
- Only valid if port one is configured to receive an unframed input signal
- User can select high or low logic level as alarmed
- If the hardware indicates that the cesium fault level matches the alarmed setting, $\log$ an AIS alarm against port 1
- Clear the alarm when the hardware's cesium fault level no longer matches the alarmed level


### 8.5.2.14 Input Measurement Problems

If the MTIE values for a selected clock exceed either of the MTIE masks, the Input module takes appropriate action according to the severity level associated with the MTIE alarms. If a received SSM has a lower PQL than the provisioned value assigned to the port and the port has SSMs enabled, the Input module performs the action required by the alarm mode. Refer to the Alarm command in Section B.3, Interactive Command Set, for more information on alarm settings.

### 8.5.2.15 DS1 Input Module Events Reported

The 3-Port DS1 Input module reports the event types listed in Table 8-15 when they occur:

Table 8-15. DS1 Input Module Event Reporting

| Event | Parameter One | Parameter Two |
| :--- | :--- | :--- |
| Card installed | - | - |
| Card enabled | - | - |
| Card disabled | - | - |
| Card restarted | Delay before restart (in seconds) | - |
| Input Signal Episode, <br> Alarm, and Faults | - | - |
| Hardware Faults | - | - |
| Received SSM Changed | New PQL | Old PQL |
| Phase Buildout | Phase value being built out | Corrected phase value |
| Configuration Changes | New Value (if necessary) | Old Value (if not implied by new value) |
| Input phase zeroed | - | - |

### 8.5.3 DS1 Input Module Status LED Indicators

The DS1 Input module is equipped with eight status LEDs that indicate module status. These LEDs are shown in Figure 8-10 and are listed and described in Table 8-16.


Figure 8-10. DS1 Input Module Status LED Indicators

Table 8-16. DS1 Input Module Status LED Indicators

| Indicator | Color | Description |
| :--- | :--- | :--- |
| POWER | Green | On = The module is receiving +5 vDC. |
| STATUS | Green/Amber | Green = Unit is in Normal mode of operation; no faults. <br> Amber = Fault condition detected. |
| PORT 1 REF | Green/Amber | On (Green) = Selected <br> On (Amber) = Not good and ignored <br> Off = Ignored or good and not selected |
| PORT 1 INPUT | Green/Amber | On (Green) = Selected <br> On (Amber) = Not good and ignored <br> Off = Ignored or good and not selected |
| PORT 2 REF | Green/Amber | On (Green) = Selected <br> On (Amber) = Not good and ignored <br> Off = Ignored or good and not selected |
| PORT 2 INPUT | Green/Amber | On (Green) = Selected <br> On (Amber) = Not good and ignored <br> Off = Ignored or good and not selected |
| PORT 3 REF | Green/Amber | On (Green) = Selected <br> On (Amber) = Not good and ignored <br> Off = Ignored or good and not selected |
| PORT 3 INPUT | Green/Amber | On (Green) = Selected <br> On (Amber) = Not good and ignored <br> Off = Ignored or good and not selected |

### 8.5.4 DS1 Input Module Configuration

The DS1 input module maintains factory default and current user configuration information in nonvolatile memory. This information is retrieved at power up and can be modified by commands from the Communications module. In the event that the current user configuration cannot be used, the module automatically reverts to factory defaults.

### 8.5.5 DS1 Input Module Software Options

The factory settings and ranges for all DS1 Input module software parameters are listed in Table 8-17.

Table 8-17. DS1 Input Module Configuration

| Configuration Setting | Factory Default | Range |
| :---: | :---: | :---: |
| Framing Enabled | On/On/Off | On/Off |
| Input Frequency (for unframed signals) | 10MHz | $1 \mathrm{MHz}, 1.544 \mathrm{MHz}, 2.048 \mathrm{MHz}, 5 \mathrm{MHz}, 10 \mathrm{MHz}$ |
| Framing Type | ESF | D4 or ESF |
| Zero Suppression | On | On/Off |
| CRC | Off | On/Off |
| SSM | Off | On/Off |
| Provisioned PQL | 3/4/3 | 1 to 16 |
| Priority | 0 | 0 to 10 (0 = Monitor) |
| Cesium Fault Nominal | Low | Low/High/Off |
| Input Signal Error Limit | 10 seconds | 1 to 100 for LOS and AIS <br> 1 to 10000 for BPV, CRC and OOF |
| MTIE T10 Limit1 | 325/1000/325 | 0 to 100000 |
| MTIE T10 Limit2 | 330/1010/330 | 0 to 100000 |
| MTIE T100 Limit 1 | 550/2000/550 | 0 to 100000 |
| MTIE T100 Limit 2 | 560/2010/560 | 0 to 100000 |
| MTIE T1000 Limit1 | 1010/2000/1010 | 0 to 100000 |
| MTIE T1000 Limit2 | 1020/2010/1020 | 0 to 100000 |
| MTIE T10000 Limit 1 | 1100/2835/1100 | 0 to 100000 |
| MTIE T10000 Limit 2 | 1110/2840/1110 | 0 to 100000 |
| MTIE Limit 1 Alarm Mode | Minor | Ignore, Report, Minor, Major, or Critical |
| MTIE Limit 2 Alarm Mode | Major | Ignore, Report, Minor, Major, or Critical |
| Alarm Initial Severity | Minor (except LOS and level 2 MTIE, which are Major) | Ignore, Report, Minor, Major, or Critical |
| Alarm Initial Delay | 0 seconds | 0 to 86400 seconds |
| Alarm Elevation Time | 86400 seconds | 0 to 500000 seconds |
| Port Status | Disabled | Enabled/Disabled |
| Port Name |  | Any user selected string from 0 to 20 characters |

### 8.6 GPS Input Module

This section provides user-reference data for the GPS Input module that is used in the SSU-2000 main chassis to provide a timing reference signal to phase and frequency lock the internal clocks and to produce phase locked output signals.

### 8.6.1 GPS Input Module Functional Overview

The module consists of a Micro-controller and firmware, SRAM for data storage, FLASH (which contains the firmware), a GPS receiver (radio), and other support circuitry. The primary function of these modules is to perform time-interval measurements on Clock module A and Clock module B, using the 1PPS provided by the radio. These measurements are used to adjust the frequency of the oscillators on those modules.

In addition, this module supports the Network Time Protocol (NTP), which is a function provided by the Communications module. Time-of-day from the Radio is transferred to the Communications module for distribution to clients connected to the same network. The Communications module's internal 1PPS is synchronized to the 1PPS from the Radio.

The GPS Input modules monitor and report the status and performance of the module and the received radio signals. Each module type communicates with the Communications module to receive user configuration commands and to report status and performance back to the Clock modules for frequency control.

### 8.6.2 GPS Input Module Functional Block Diagram

A simplified block diagram of the GPS Input module is shown in Figure 8-5.


Figure 8-11. GPS Input Module Block Diagram

### 8.6.3 GPS Input Module Status LED Indicators

The GPS Input module is equipped with four status LEDs as shown in Figure 8-12. The LED status assignments are described in Table 8-15.

ssu00035
Figure 8-12. GPS Input Module Status LED Indicators

Table 8-18. GPS Input Module Status LED Indicators

| Indicator | Color | Description |
| :--- | :--- | :--- |
| POWER | Green | On = The module is receiving +5 vDC |
| STATUS | Green/Amber | Green = Unit is in Normal mode of operation; no faults <br> Amber = Fault condition detected (firmware timed out) |
| ACQUIRE | Green/Amber | On (Green) = Selected as the clock reference <br> Off = Not selected as clock reference |
| TRACKING | Green/Amber | On (Green) = RADIO is tracking <br> On (Amber) = Tracking problem without antenna fault <br> Blinking (Amber) = Antenna fault |

### 8.6.4 GPS Input Module Configuration Settings

The configuration settings for the GPS Input module are listed in Table 8-19.

Table 8-19. GPS Input Module Configuration Settings

| Configuration Setting | Factory Default | Range |
| :---: | :---: | :---: |
| Position (GPS only) <br> Latitude <br> Longitude <br> Altitude <br> Averages <br> PDOP <br> Pos Mode | $\begin{aligned} & 0 \\ & 0 \\ & 0 \\ & 300 \\ & 0 \\ & \text { Calc } \end{aligned}$ | $\begin{aligned} & \text { +/- } 90 \text { degrees } \\ & \text { +/-180 degrees } \\ & -60 \text { to } 4000 \text { meters } \\ & 10 \text { to } 3600 \\ & 1 \text { to } 10 \\ & \text { User/Calc } \end{aligned}$ |
| Min Elevation for position | 5 | 0 to 50 degrees |
| Min PDOP for position | 3 | 1 to 10 |
| Min Elevation for timing | 10 | 0 to 50 degrees |
| Module Status | Enabled | Enabled/Disabled |
| Priority | 0 | 0 to 10 |
| Sigma limit | 25 | 10 to $1000 \mu \mathrm{~S}$ |
| PQL | 2 | 1 to 16 |
| Disabled SV list | None | Up to 31 SV numbers |
| Min PDOP for position | 3 | 1 to 10 |

### 8.72048 kHz Output Module

This section describes the 2048 kHz Output module.

### 8.7.1 2048 kHz Output Module Functional Overview

The 2048 kHz Output module receives a set of three (four if installed in an expansion chassis) 4 kHz clocks from the Clock modules and uses these clocks to develop an 8.192 MHz phaselocked signal. This phase-locked signal is then used to generate 20 sets of 2048 kHz clock outputs.

The 20 sets of 2048 kHz signal pairs TTIP and TRING represent a transformer-coupled symmetrical pair. Each output can be turned on/off independently of other channels; relays on each output allow for disconnecting the driver output from the output pins. Each output signal is monitored for a failed output on an independent basis. An output signal is designated failed when the level falls below 0.75 volts base to peak.

In non-redundant configuration a failed output will not be turned off, as some equipment may tolerate a wide range of level and still be operating. In redundant operation a failed output will be turned off in one module at a time to try and isolate the source of the problem. The outputs meet the criteria set forth in ITU-T CC for signal type, amplitude, and waveshape.

### 8.7.2 2048 kHz Output Module Functional Block Diagram

A simplified block diagram of the 2048 kHz Output module is shown in Figure 8-13.


Figure 8-13. 2048 kHz Output Module Block Diagram

### 8.7.3 2048 kHz Output Module Status LED Indicators

The 2048 kHz Output module has seven status LED indicators along the front edge of the module that are used for visually conveying status information to the user. The LEDs are shown in Figure 8-14 and described in Table 8-20.


Figure 8-14. 2048 kHz Output Module Status LED Indicators

## Table 8-20. 2048 kHz Output Module Status LED Indicators

| Indicator | Color | Description |
| :--- | :--- | :--- |
| POWER | Green | On = +5 vDC power available on the Output module <br> Off = +5 vDC not present on the module |
| STATUS | Green/Amber | On (Green) = module functioning correctly <br> Blinking Amber = Output module is downloading firmware <br> On (Amber) = Output module failure |
| SOURCE A | Green/Amber | On (Green) = Source A is the selected source clock <br> On (Amber) = Faulty or missing A source clock <br> Off = Source A is ignored or good and not selected |
| SOURCE B | Green/Amber | On (Green) = Source B is the selected source clock <br> On (Amber) = Faulty or missing B source clock <br> Off = Source B is ignored or good and not selected |
| SOURCE C | Green/Amber | On (Green) = Source C is the selected source clock <br> On (Amber) = Faulty or missing source C clock <br> Off = Source C is ignored or good and not selected |
| SOURCE D | Green/Amber | On (Green) = Source D is the selected source clock <br> On (Amber) = Faulty or missing source D clock <br> Off = Source D is ignored or good and not selected |
| OUTPUT FAULT | Amber | On = Module has detected one or more faulty outputs <br> Off = All output signals are good |

Specifications for the 2048 kHz Output module are provided in Table 8-21.

Table 8-21. 2048 kHz Output Module Specifications

| Performance Characteristic | Specification |
| :--- | :--- |
| Frequency | 2048 kHz |
| Waveshape | Per ITU-T CC (Oct. 98) Table 11 and Figure 20 |
| Pulse Amplitude | 1.0 to $1.9 \mathrm{Vpk}, 1.5 \mathrm{Vpk}$ nominal into $120 \Omega$ <br> 0.75 to $1.5 \mathrm{Vpk}, 1.0 \mathrm{Vpk}$ nominal into $75 \Omega$ |
| Jitter | $\leq 0.01 \mathrm{Ulpp}, 20 \mathrm{~Hz}$ to 100 kHz |
| Number of Outputs | 20 Independent |

### 8.8 E1 Output Module

This section provides user-reference data for the E1 Output module that is used in both the SSU2000 main chassis and in the optional SDU-2000 expansion shelf.

### 8.8.1 E1 Output Module Overview

The E1 Output module uses one of three 4 kHz clocks from the SSU-2000 main chassis backplane to generate a phase-locked signal of 2.048 Mbps . If the unit is inserted into an SDU-2000 expansion shelf, a fourth 4 kHz clock (D-clock) is available. The phase-locked 2.048 Mbps signal is used to generate a set of 20 output signals for distribution to large networks.

A microcontroller unit on the E1 Output module communicates with other boards in the main shelf and performs Output module configuration. The module's memory subsystem (EEPROM, RAM and serial EEPROM) stores the executable image, the PLD image and other configuration and temporary information for an on-module microprocessor.

The E1 Output modules may be used individually or configured for operation as redundant pairs in the shelf.

### 8.8.2 E1 Output Module Functional Block Diagram

A simplified block diagram of the E1 Output module is shown in Figure 8-15.


Figure 8-15. E1 Output Module Block Diagram

### 8.8.3 E1 Output Module Status LED Indicators

The E1 Output module has seven status LED indicators along the front edge of the module that are used for visually conveying status information to the user. The LEDs are shown in Figure 8-16 and described in Table 8-22.


Figure 8-16. E1 Output Module Status LED Indicators

Table 8-22. E1 Output Module Status LED Indicators

| Indicator | Color | Description |
| :--- | :--- | :--- |
| POWER | Green | On = +5 vDC power available on the Output module <br> Off = +5 vDC not present on the module |
| STATUS | Green/Amber | On (Green) = Module functioning correctly <br> Blinking Amber = Output module is downloading firmware <br> On (Amber) = Output module failure |
| SOURCE A | Green/Amber | On (Green) = Source A is the selected source clock <br> On (Amber) = Faulty or missing A source clock <br> Off = Source A is ignored or good and not selected |
| SOURCE B | Green/Amber | On (Green) = Source B is the selected source clock <br> On (Amber) = Faulty or missing B source clock <br> Off = Source B is ignored or good and not selected |
| SOURCE C | Green/Amber | On (Green) = Source C is the selected source clock <br> On (Amber) = Faulty or missing source C clock <br> Off = Source C is ignored or good and not selected |
| SOURCE D | Green/Amber | On (Green) = Source D is the selected source clock <br> On (Amber) = Faulty or missing source D clock <br> Off = Source D is ignored or good and not selected |
| OUTPUT | Amber | On = Module has detected one or more faulty outputs <br> Off = All output signals are good |
| FAULT |  |  |

### 8.8.4 E1 Output Module Performance Specifications

The E1 Output Module performance specifications are provided in Table 8-23.

Table 8-23. E1 Output Module Performance Specifications

| Performance <br> Characteristic | Specification |
| :--- | :--- |
| Signal | Alternate Mark Inversion (AMI) |
| Waveshape | Per ITU-T CC (10/98) |
| Risetime | $<100 \mathrm{~ns}$ |
| Pulse Width | 244 ns, nominal into $120 \Omega$ |
| Pulse Interval | 488 ns, nominal |
| Duty Cycle | $50 \%$ |

Table 8-23. E1 Output Module Performance Specifications (Continued)

| Performance <br> Characteristic | Specification |
| :--- | :--- |
| Pulse Amplitude | 2.2 to 3.3 Vpp |
| Jitter | $<0.01 \mathrm{UI}$ |
| Number of Outputs | 20 |

### 8.9 DS1 Output Module

This section provides user-reference data for the DS1 Output module that is used in both the SSU2000 main chassis and in the optional SDU-2000 expansion shelf.

### 8.9.1 DS1 Output Module Overview

The DS1 Output module generates a phase-locked signal of 1.544 Mbps using one of three 4 kHz clocks from the backplane of the SSU-2000 main shelf (A, B, and, C clocks). If the module is inserted into the SDU-2000 Synchronization Distribution Unit (expansion shelf), a fourth 4 kHz clock ( D clock) is available. The phase-locked signal generates a set of 20 output signals for distribution to large networks.

A microcontroller unit on the DS1 Output module communicates with other boards in the main shelf and performs Output module configuration. The module's memory subsystem (EEPROM, RAM and serial EEPROM) stores the executable image, the PLD image and other configuration and temporary information for an on-module microprocessor.

The DS1 Output modules may be used individually or configured for operation as redundant pairs in the shelf.

### 8.9.2 DS1 Output Module Functional Block Diagram

A simplified block diagram of the DS1 Output module is shown in Figure 8-17.


Figure 8-17. DS1 Output Module Block Diagram

### 8.9.3 DS1 Output Module Status LED Indicators

The DS1 Output module status LED indicators are shown in Figure 8-18 and are described in Table 8-24.


Figure 8-18. DS1 Output Module Status LED Indicators

## Table 8-24. DS1 Output Module Status LED Indicators

| Indicator | Color | Description |
| :--- | :--- | :--- |
| POWER | Green | On = +5 vDC power available on the Output module <br> Off = +5 vDC not present on the module |
| STATUS | Green/Amber | On (Green) = Module functioning correctly <br> Blinking Amber = Output module is downloading firmware <br> On (Amber) = Output module failure |
| SOURCE A | Green/Amber | On (Green) = Source A is the selected source clock <br> On (Amber) = Faulty or missing A source clock <br> Off= Source A is ignored or good and not selected |
| SOURCE B | Green/Amber | On (Green) = Source B is the selected source clock <br> On (Amber) = Faulty or missing B source clock <br> Off= Source B is ignored or good and not selected |
| SOURCE C | Green/Amber | On (Green) = Source C is the selected source clock <br> On (Amber) = Faulty or missing source C clock <br> Off = Source C is ignored or good and not selected |
| SOURCE D | Green/Amber | On (Green) = Source D is the selected source clock <br> On (Amber) = Faulty or missing source D clock <br> Off = Source D is ignored or good and not selected |
| OUTPUT <br> FAULT | Amber | On = Module has detected one or more faulty outputs <br> Off = All output signals are good |

### 8.9.3.1 DS1 Output Module Specifications

The DS1 Output module specifications are provided in Table 8-25.

Table 8-25. DS1 Output Module Performance Specifications

| Performance <br> Characteristic | Specification |
| :--- | :--- |
| Signal | Alternate Mark Inversion (AMI) |
| Waveshape | Per (ANSI) T1.102 and ITU Rec. G.703 |
| Risetime | $<100 \mathrm{~ns}$ |
| Pulse Width | 324 ns, nominal into $100 \Omega$ |
| Pulse Interval | 648 ns, nominal |
| Duty Cycle | $50 \%$ |

Table 8-25. DS1 Output Module Performance Specifications (Continued)

| Performance <br> Characteristic | Specification |
| :--- | :--- |
| Pulse Amplitude | 2.4 to 3.6 Vpp |
| Jitter | $<0.01$ UI |
| Number of Outputs | 20 |

### 8.10 Composite Clock Output Module

This section provides user-reference data for the Composite Clock Output module used in both the SSU-2000 main chassis and in the optional SDU-2000 expansion shelf.

### 8.10.1 Composite Clock Output Module Overview

The Composite Clock Output module is one of several Output module types that may be installed in an SSU-2000 main shelf or expansion shelf to generate 20 signal pairs (TTIP and TRING signal pairs). Each output is a transformer-coupled symmetrical pair. Each output pair can be turned off independently of other channels; relays on each output allow for disconnecting the driver output from the output pins. These outputs are independently configurable for duty cycle (50/50 or 62.5/ 37.5) and phase delay from 0 to $3.4 \mu \mathrm{sec}$ in 8 or more steps. Refer to Section 5.6.2, Changing Factory Defaults, for more information on duty cycle settings.

The outputs are byte and polarity phase aligned with the selected 4 kHz clock. Each output signal is monitored for a failed output on an independent basis. An output is said to be failed when either the polarity pulse falls below 2.1 volts base to peak, when polarity reversal can no longer be detected, or when return to zero cannot be detected.

The outputs of the Composite Clock Output module meet the criteria set forth in Bellcore GR-378-CORE and TR-TSY-000458 for signal type, amplitude, and waveshape. ITU-T Rec. G. 703 Centralized Clock is partially supported (50/50 duty cycle) except only the Bellcore signal levels are generated.

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### 8.10.2 Composite Clock Output Module Functional Block Diagram

A simplified block diagram of the Composite Clock Output module is shown in Figure 8-5.


Figure 8-19. Composite Clock Output Module Block Diagram

### 8.10.3 Composite Clock Output Module Status LED Indicators

The Composite Clock Output module status LED indicators are shown in Figure 8-20 and described in Table 8-26.


Figure 8-20. Composite Clock Output Module Status LED Indicators

Table 8-26. Composite Clock Output Module Status LED Indicators

| Indicator | Color | Description |
| :--- | :--- | :--- |
| POWER | Green | On = +5 vDC power available on the Output module <br> Off $=+5$ vDC not present on the module |
| STATUS | Green/Amber | On (Green) = Module functioning correctly <br> Blinking Amber = Output module is downloading firmware <br> On (Amber) = Output module failure |
| SOURCE A | Green/Amber | On (Green) = Source A is the selected source clock <br> On (Amber) = Faulty or missing A source clock <br> Off = Source A is ignored or good and not selected |
| SOURCE B | Green/Amber | On (Green) = Source B is the selected source clock <br> On (Amber) = Faulty or missing B source clock <br> Off = Source B is ignored or good and not selected |
| SOURCE C | Green/Amber | On (Green) = Source C is the selected source clock <br> On (Amber) = Faulty or missing source C clock <br> Off = Source C is ignored or good and not selected |
| SOURCE D | Green/Amber | On (Green) = Source D is the selected source clock <br> On (Amber) = Faulty or missing source D clock <br> Off = Source D is ignored or good and not selected |
| OUTPUT <br> FAULT | Amber | On = Module has detected one or more faulty outputs <br> Off = All output signals are good |

### 8.10.4 Composite Clock Output Module Specifications

The functional specifications for the Composite Clock output module are provided in Table 8-27.

Table 8-27. Composite Clock Output Module Specifications

| Performance <br> Characteristic | Specification |
| :--- | :--- |
| Signal | Bipolar, Return to Zero, Alternate Mark Inversion (AMI) |
| Waveshape | Per Bellcore GR-378-CORE Table 6-2 \& Figure 6-1 |
| Rise/Fall time | $<500 \mathrm{~ns}$ |
| Pulse Width | $9.8 \mu \mathrm{~s} \pm 2 \%$ for $62.5 / 37.5$ duty cycle |
|  | $7.8 \mu \mathrm{~s} \pm 2 \%$ for $50 / 50$ duty cycle |
| Pulse Interval | $15.6 \mu \mathrm{~s}$, nominal |
| Duty Cycle | $62.5 / 37.5$ or $50 / 50$ selectable |
| Pulse Amplitude | 2.7 to 5.5 Vpk, 3.5 Vpk nominal into $133 \Omega$ |
| Number of Outputs | 20 Independent Channels |

### 8.10.5 Buffer Module Indicators

The Buffer module indicators (LEDs) are shown in Figure 8-21 and described in Table 8-28.

sdu00023
Figure 8-21. Buffer Module Indicators

Table 8-28. Buffer Module LED Indicators

| Indicator | Color | Description |
| :--- | :--- | :--- |
| POWER | Green | On = Receiving +5 vDC power <br> Off = Loss of +5 vDC power |
| STATUS | Green/Amber | On (Green) = Normal mode of operation; no faults <br> Blinking Amber = Downloading firmware <br> On (Amber) = Unknown status, or a fault has been <br> detected |
| -48V Power A | Green/Amber | On (Green) = Receiving input power from Power A <br> On (Amber) = Power connections reversed <br> Off = Loss of input Power A |
| -48 V Power B | Green/Amber | On (Green) = Receiving input power from Power B <br> On (Amber) = Power connections reversed <br> Off = Loss of input Power B |

### 8.11 I/O Adapter for 1-Port Input Module

The Input I/O adapter used with the 1-Port Input module is shown in Figure 8-22. One adapter can accommodate up to four 1-Port Input modules. Each port section on the I/O adapter can be configured for DS1 terminated ( $100 \Omega$ ), E1 terminated ( $120 \Omega$ ) and can accept either BNC or DE9 input cable connection (switch selectable).

The rear of the I/O adapter contains four SCSI-II type connectors, one for each Input module connection (via a one-meter input cable).


Figure 8-22. Input I/O Adapter for One-Port Input Modules

### 8.12 I/O Adapter for 3-Port Input Module

The input I/O adapter used with the 3-Port Input module is shown in Figure 8-23. One adapter is required for each Input module. The I/O adapter can be configured for DS1 terminated ( $100 \Omega$ ), E1 terminated ( $120 \Omega$ ) and can accept either BNC or DE9 input cable connection (switch selectable). A one meter cable is supplied with the I/O adapter that connects from the back of the SSU-2000 to the connector on the back of the I/O adapter.

Three different input sections are provided on the adapter, corresponding to the three ports on the Input module.

ss200018
Figure 8-23. I/O Adapter for 3-Port Input Modules

### 8.13 Balun Output I/O Adapter for Output Module

The Balun Output I/O Adapter panel for use with DS1 or E1 Output modules is shown in Figure 8-24. One adapter panel is required for each Output module in the system.

ss200020
Figure 8-24. Balun Output I/O Adapter Panel for Output Module

### 8.14 DE9 Output I/O Adapter Panel for Output Module

The DE9 Output I/O Adapter Panel for the DS1 and E1 Output module is shown in Figure 8-25. One adapter panel accommodates the 20 output signals generated by one Output module.

ss200021
Figure 8-25. Output I/O Adapter Panel, D9 Outputs

## In this Chapter ...

- Configuring a Conventional SSU/ TSG System
- Configuring a Primary Reference Source (PRS) System
- Configuring a Monitor Only System
- SSU-2000 Configuration Chart


## Chapter 9 Hardware Configuration Guide

The SSU-2000's modular construction and powerful plug and play features allow the system to be configured into a variety of telecommunications configurations, depending on which modules are installed. Some of the more common configurations include:

- SSU/TSG system
- Primary Reference Source (PRS) system
- Monitor-only system


### 9.1 Configuring a Conventional SSU/TSG System

The SSU/TSG configuration allows for input of external references to which the Clock modules are phase locked. This configuration allows for monitoring of several inputs and for synchronization of output signals. Figure 9-1 shows a TSG configuration.


Figure 9-1. Time Sync Generator (TSG) System Configuration

The TSG configuration consists of the following:

- SSU-2000 main chassis
- Communications Module
- One or more E1/DS1 input modules
- Corresponding number of Input I/O adapter panels and input I/O cables
- One or two Clock Module(s) (2E/3E)
- One or more E1 and/or DS1 Output Module(s)
- Corresponding number of Output I/O adapter panels and SCSI output cables
- Seven 1.0 -inch wide filler panels and one $3-1 / 2$ " wide filler panel


### 9.2 Configuring a Primary Reference Source (PRS) System

In a Primary Reference Source (PRS) configuration, the SSU-2000 meets the specifications defined in American National Standards Institute (ANSI) T1.101-1994. ANSI defines a Primary Reference Source as "equipment that provides a timing signal whose long-term accuracy is maintained at $1 \times 10^{-11}$ or better, with verification to Universal Coordinated Time (UTC), and whose timing signal is used as the basis of reference for the control of other clocks within a network". If standard Input modules are installed in the remaining input slots, this configuration also allows for monitoring of other external signals, such as DS1, E1, composite clock, and various clock frequencies. Time-of-day functionality is available via the Ethernet port employing NTP. Figure 9-2 shows a PRS configuration.

ssu00007
Figure 9-2. SSU-2000 Configured as PRS System

The SSU-2000 PRS configuration consists of the following:

- SSU-2000 main chassis
- Communications Module
- One or two GPS Input Modules
- One Clock Module (2E or 3E)
- One or more E1 and/or DS1 Output Modules
- One Input Adapter Panel and I/O cable
- One Output Adapter Panel and SCSI Output cable
- Seven 1.0-inch wide filler panels and one 3-1/2" wide filler panel


### 9.3 Configuring a Monitor Only System

In a monitor-only configuration, no output signals are required. One of the inputs is designated as the reference, and the SSU-2000 Clock module is locked directly to this signal. All remaining input signals are then compared to the phase-locked oscillators (and indirectly to the designated input reference). The SSU-2000 can support up to 27 inputs in this type of configuration. Figure 9-3 shows a monitor only configuration.


Figure 9-3. SSU-2000 Configured as Monitor Only System

A monitor only configuration consists of the following:

- SSU-2000 main chassis with SDU Termination Plug
- Communications Module
- One or more Input Modules (one-port or three port DS1 or E1)
- Stratum 2E Clock Module
- Stratum 3E Clock Module
- One (or more) input adapter panel(s) and I/O cable; one three port input adapter required for each three-port input module in the system; one four-port input adapter required for each set of four One-Port Input Modules


### 9.4 SSU-2000 Configuration Chart

A fully-populated SSU-2000 main shelf is shown in Figure 9-4. Figure 9-5 shows the I/O adapter panels used with the SSU-2000 input and output modules. Figure 9-6 shows the SDU-2000 Synchronization Distribution Unit (output expansion chassis) used with the SSU-2000. Table 9-1 contains a listing of all SSU-2000 components, provides the associated Datum part numbers and provides other configuration data required to procure a custom system.


Figure 9-4. SSU-2000 Main Shelf Front View

ss200020
75 Ohm Balun I/O Adapter for DS1 or E1 Output Module

ss200021
DE9 I/O Adapter for DS1 or E1 Output Module
Figure 9-5. SSU-2000 I/O Adapter Panels

ss200027
Figure 9-6. SDU-2000 Synchronization Distribution Unit

Table 9-1. SSU-2000 System Components

| Item | Description | Datum Part No. | Notes |
| :---: | :---: | :---: | :---: |
| SSU-2000 Main Shelf and Associated Hardware |  |  |  |
| 1 | SSU-2000 Main Shelf (Chassis) with SDU termination plug and SSU-2000 <br> Synchronization Supply Unit User Guide | 25413020-000-0 | 1. Required for all systems. <br> 2. If an Expansion chassis (SDU-2000) is not attached to J8, an SSU Expansion Terminator, P/N 12013049-000-0 must be installed on the SSU-2000 chassis, connector J8. Otherwise, the terminator must be installed on the last expansion chassis in the system. <br> 3. Requires minimum of one Comms module, one Clock module, one Input module, one Output module, one Input Adapter panel and one Output adapter panel and 8 Filler panels (including one wide panel). <br> 4. Supplied with User Guide. |
| 2 | Bracket, rack ear, 19" | 00413102-000-1 | Two each provided with the main shelf. |
| 3 | Bracket, rack ear, 23", 2 each required | 00413020-001-1 | Two each required per main shelf (must specify 23 " rack). |
| Clock Modules |  |  |  |
| 4 | Stratum 2E Rb Clock Module | 23413016-000-0 | 1. Minimum of one clock module per system (item 4 or item 5). <br> 2. Redundant configuration with automatic switching in case of clock failure requires two clock modules. <br> 3. The system will operate with $2 \mathrm{E} / 3 \mathrm{E}$ clocks combined. 2E clock must be installed in chassis slot A1. |
| 5 | Stratum 3E Clock Module | 23413015-000-0 | 1. Minimum of one clock module per system (item 4 or item 5). <br> 2. Redundant configuration with automatic switching in case of clock failure requires two clock modules. <br> 3. The system will operate with $2 \mathrm{E} / 3 \mathrm{E}$ clocks combined. 2E clock must be installed in chassis slot A1. |
| Communications Module |  |  |  |
| 6 | Communications Module | 23413012-000-0 | One required per SSU-2000 system. |

## Table 9-1. SSU-2000 System Components (Continued)

| Item | Description | Datum Part No. | Notes |
| :---: | :---: | :---: | :---: |
| Input Modules, I/O Adapter Panels and Input Cabling |  |  |  |
| 7 | 3-Port DS1 Input Module | 23413013-002-0 | 1. Accepts up to 3 DS1 or Clock signals. <br> 2. Requires use of three-port SSU I/O adapter (one per input module in system). |
| 8 | 1-Port DS1 Input Module | 23413013-001-0 | 1. Accepts one DS1 or Clock signal. <br> 2. Requires use of four-port SSU I/O Adapter (one adapter can handle up to four oneport DS1 or ES1 Input Modules). |
| 9 | 3-Port E1 Input Module | 23413014-002-0 | 1. Any combination of three G.703/9, G.703/ 13, or Clock inputs. <br> 2. Requires use of three-port SSU I/O adapter (one per input module in system. |
| 10 | 1-Port E1 Input Module | 23413014-001-0 | Requires use of four-port SSU I/O adapter (one adapter serves up to four input modules). |
| 11 | GPS Input Module | 23413019-000-0 | 1. Supports NTP provided by the Comms module. <br> 2. Time-of-day provided by the Radio. |
| 12 | Three port SSU I/O Input Adapter Panel | 22013066-001-0 | 1. Used with 3-port DS1 or E1 Input Module. <br> 2. For each port, has DE9 and BNC connectors (switch selectable) and selectable termination (50, $75,100,120$ or 3.3 kOhms). <br> 3. Typically, 100 Ohms termination for DS1 signals, 120 Ohms for E1 signals, 50 and 75 Ohm termination for $2,048 \mathrm{MHz}$ or sine wave signals. <br> 4. Comes with SCSI cable for connection to SSU-2000. |
| 13 | 4-Port SSU I/O Adapter Panel | 22013069-001-0 | 1. One adapter panel serves up to four 1 -port input modules. <br> 2. Supplied with SCSI input cable for attached panel to SSU-2000. |

Table 9-1. SSU-2000 System Components (Continued)

| Item | Description |  | Datum Part No. | Notes |
| :--- | :--- | :--- | :--- | :--- |$|$| Output Module, Output I/O Adapter Panels and Output Cables |  |
| :--- | :--- | :--- |

## Table 9-1. SSU-2000 System Components (Continued)

| Item | Description | Datum Part No. | Notes |
| :---: | :---: | :---: | :---: |
| 18 | SSU I/O Adapter Panel, DS1 100/75 Ohm Balun Outputs, 20 BNC connectors | 22013068-002-0 | 1. One adapter required per DS1 output module (or redundant pair Output modules). <br> 2. Requires separate I/O cable, 50 pin-SCSI - see below. <br> 3. Optional ears for 21 -inch or 23 -inch rack. |
| 19 | SSU I/O Adapter Panel, DS1 120/75 Ohm Balun Outputs, 20 BNC connectors | 22013068-001-0 | 1. One adapter required per DS1 output module (or redundant pair Output modules). <br> 2. Requires separate I/O cable, 50 pin-SCSI - see below. <br> 3. Optional ears for 21 -inch or 23 -inch rack. |
| 20 | I/O Adapter Assembly, 9 -pin D Outputs (DE9) | 22013067-001-0 | 1. One adapter required per DS1 output module (or redundant pair Output modules). <br> 2. Requires separate I/O cable, 50 pin-SCSI - see below. <br> 3. Optional ears for 21 -inch or 23 -inch rack. |
| 21 | Adapter, 9-pin to wirewrap | 22013085-000-0 | One DE9 I/O connector to wire wrap adapter for each DE9 I/O connector (optional). |
| 22 | I/O Cable, 50 pin (SCSI) <br> 1 Meter long | 805SCSI-0050 | 1. One cable ( 1 to 2 meters in length) required for each Output module or redundant pair of Output modules in the system. <br> 2. Same cables used for main chassis and expansion chassis. |
| 23 | Output Cable, 50 pin (SCSI) 1.1 Meters long | 805SCSI-0150 | 1. One cable ( 1 to 2 meters in length) required for each Output module or redundant pair of Output modules in the system. <br> 2. Same cables used for main chassis and expansion chassis. |
| 24 | Output Cable, 50 pin (SCSI) 1.2 Meters long | 805SCSI-0250 | 1. One cable ( 1 to 2 meters in length) required for each output module or redundant pair of output modules in the system. <br> 2. Same cables used for main chassis and expansion chassis. |
| 25 | Output Cable, 50 pin (SCSI) 1.3 Meters long | 805SCSI-0350 | 1. One cable ( 1 to 2 meters in length) required for each output module or redundant pair of output modules in the system. <br> 2. Same cables used for main chassis and expansion chassis. |

Table 9-1. SSU-2000 System Components (Continued)

| Item | Description | Datum Part No. | Notes |
| :--- | :--- | :--- | :--- |$|$| 26 | Output Cable, 50 pin <br> (SCSI) 1.4 Meters long | 805 SCSI-0450 |
| :--- | :--- | :--- |
| 27 | Output Cable, 50 pin <br> (SCSI) 1.5 Meters long cable (1 to 2 meters in length) required <br> for each output module or redundant pair of <br> output modules in the system. <br> 2. <br> Same cables used for main chassis and <br> expansion chassis. |  |
| 28 | Output Cable, 50 pin <br> (SCSI) 1.6 Meters long | 805 SCSI-0550 |
| 29 | 1. One cable (1 to 2 meters in length) required <br> for each output module or redundant pair of <br> output modules in the system. <br> (SCSI) 1.7 Meters long |  |
| 2ame cables used for main chassis and |  |  |
| expansion chassis. |  |  |

## Table 9-1. SSU-2000 System Components (Continued)

| Item | Description | Datum Part No. | Notes |
| :---: | :---: | :---: | :---: |
| SDU-2000 Expansion Chassis |  |  |  |
| 33 | SDU-2000 <br> Synchronization <br> Distribution Unit <br> Expansion Shelf, comes with D-clock cable | 25413023-000-0 | 1. Supplied with User Guide. <br> 2. Up to 4 expansion chassis can be attached to one SSU-2000 main shelf. <br> 3. Requires minimum of one buffer module ( 2 recommended) and up to 14 output modules (no input modules). <br> 4. Output modules interchangeable between expansion shelf and main shelf. <br> 5. Last expansion shelf requires SDU termination plug (shipped with main shelf). |
| 34 | Buffer Module | 25413022-000-0 | One to two required per SDU-2000 expansion chassis (install in chassis slots A15 and A16). |
| Blank Filler Panels |  |  |  |
| 35 | Clock Module Filler Panel (3.2 inches wide) | 10913022-000-0 | Panels are required in all unused clock slots. |
| 36 | Standard Module Filler Panel (1-inch wide) | 10913021-000-0 | Panels are required in all unused SSU-2000 and SDU-2000 chassis slots. The 1 -inch panel fits all unused slots in Expansion Chassis and all except A1 and A12 (two end slots) in the Main chassis. |
| RS-232 Cabling |  |  |  |
| 37 | Cable, RS-232 Shielded, DB9P to DB9S, 5 ft . ( 1.5 m ) | 551026-0038 | Used for communication with the SSU-2000. |

## In this Appendix ...

- Alarm Messages
- Event Messages


## Appendix A Alarms and Events

This appendix describes the alarms and events that the SSU-2000 generates, and provides some troubleshooting information for dealing with these alarms and events. After an SSU-2000 Communications module is installed and functioning properly, it monitors the SSU-2000 and logs unit events into non-volatile memory for inspection at a later date. Events are conditions within the unit or at the interfaces of the unit which may indicate abnormal operation or a change in the unit's operational status. Recurring events may be escalated to alarm status and may require action by the user. Conversely, alarms may be de-escalated and corrected automatically.

Although every alarm is considered to be an event, not every event is an alarm. For example, a login is recorded as an event but is not considered to be an alarm. In this case, no action is required by the user.

The following sections list all alarm and event messages by their designated numbers, a description of each, and any corrective action to clear the alarm or condition, if necessary.

## 픞 <br> Note

Datum offers a 24 -hour technical support line and a 2 -hour response time for each trouble call. For Customer Service, Call: (512) 721-4032 or (866) 638-7962 (866 NET-SYNC) during our normal business hours (8 a.m. to 5 p.m. CST), or (512) 721-4000 after hours and on weekends, Fax: (512) 251-9685, or E-mail: austinsupport@datum.com

Figure $\mathrm{A}-1$ shows the structure of a typical Alarm and Event report status messages.


Figure A-1. Alarm and Event Message Breakdown

## A. 1 Alarm Messages

With the exception of loss of power alarms (on main chassis and expansion unit) all alarms are module alarms. Table A-1 below lists each module with corresponding alarm descriptions, alarm levels, status messages, and corrective action. Since a "no fault" alarm requires no action, the "Description/Corrective Action" category applies only to fault messages requiring user intervention.

Table A-1. Module Alarm Messages

| Alarm Description | Alarm Number | Default Alarm Level | Status Messages | Description/Corrective Action |
| :---: | :---: | :---: | :---: | :---: |
| Clock Module Alarms |  |  |  |  |
| Status of module-to- module communication | 0 | Minor | - Communication Ok <br> - Communication Bad | Unable to communicate with other modules. <br> Re-seat modules. |
| Input reference available status | 1 | Minor | - Ok <br> - Invalid | Input reference is not available Perform the following: <br> - Check the Input reference settings <br> - Check the Input port's status <br> - Check that the phase value is valid <br> - Ensure that the Input port priority is set <br> - Verify that the PQL value is equal to or greater than the clock PQL value <br> When the Input reference is recovered, the alarm is cleared |
| Frequency mode degradation | 2 | Minor | - Ok <br> - Holdover | Invalid reference input will cause holdover. Verify input setup. |
| Frequency control parameters within specification | 3 | Major | - Ok <br> - Out of Range | The reference input frequency is over the clock pull-in range. |
| Output frequency status within specification | 4 | Minor | - Ok <br> - Degraded | Output exceeded pull-in range of oscillator. Select new input reference. |
| Clock module usable as the output reference | 5 | Minor | - Ok <br> - Invalid | Clock mode has warmed up. |
| Status of the numerically controlled oscillator phase lock loop | 6 | Minor | - Ok <br> - Not Locked | Alarm will clear within one minute after module is installed. If alarm persists, re-seat modules. |
| Status of the local oscillator phase lock loop | 7 | Minor | - Ok <br> - Not Locked | Alarm will clear within one minute after module is installed. If alarm persists, re-seat module. |
| Status of the rubidium's internal phase lock loop (ST2E clock only) | 8 | Minor | - Ok <br> - Not Locked | Only available with Stratum 2E Rubidium module. If alarm persists, re-seat module. |
| Status of the hardware configuration | 9 | Minor | - Ok <br> - Failed | Call Datum Customer Service. Return to factory. |

Table A-1. Module Alarm Messages (Continued)

| Alarm Description | Alarm Number | Default Alarm Level | Status Messages | Description/Corrective Action |
| :---: | :---: | :---: | :---: | :---: |
| Communications Module Alarms |  |  |  |  |
| Module-to-module communication | 0 | Minor | - Ok <br> - Bad | Unable to communicate with other modules. Re-seat modules. |
| Indication of output controller mastership | 1 | Minor | - Ok <br> - Bad | Identifies master output controller. No action necessary. |
| Status of Power A | 2 | Minor | - Ok <br> - Lost | - Verify that the fuse for Power A is properly installed and not OPEN. <br> - Verify that Power Bus A is providing -48 vDC to the unit. If no power is connected to the Power A input and there is no plan to connect power, enter the command AL 10-1 IG at the prompt. |
| Status of Power B | 3 | Minor | - Ok <br> - Lost | - Verify that the fuse for Power B is properly installed and not OPEN. <br> - Verify that Power Bus B is providing -48 vDC to the unit. If no power is connected to the Power B input and there is no plan to connect power, enter the command AL 10-1 IG at the prompt. |
| Status of module's serial peripheral interface hardware (SPI watchdog timeout) | 4 | Minor | - Ok <br> - Timeout | Unable to communicate with other modules. Re-seat module. |
| DS1/E1 Input Module Alarms |  |  |  |  |
| Loss of signal fault status | 0 | Minor | - Ok <br> - Active | Verify signal is connected. May be extinguished by disabling port. |
| Alarm indication signal fault status | 1 | Minor | - Ok <br> - Active | Verify input signal is good. Port can be disabled. |
| Out of frame signal fault status | 2 | Minor | - Ok <br> - Active | Change frame type: <br> - DS1-ESF or D4 <br> - E1-CAS or CCS |
| Bipolar violation signal fault status | 3 | Minor | - Ok <br> - Active | Verify port ZS is on. Verify signal is good. |
| Cyclic redundancy code error fault status | 4 | Minor | - Ok <br> - Active | Verify port CRC is off. Verify signal is good. |

## Table A-1. Module Alarm Messages (Continued)

| Alarm Description | Alarm Number | Default Alarm Level | Status Messages | Description/Corrective Action |
| :---: | :---: | :---: | :---: | :---: |
| Maximum time interval error fault status limit 1 | 5 | Minor | - Ok <br> - Exceeded | MTIE limit 1 has been exceeded. |
| Maximum time interval error fault status limit 2 | 6 | Minor | - Ok <br> - Exceeded | MTIE limit 2 has been exceeded. |
| Received PQL below provisioned PQL status | 7 | Minor | - Ok <br> - Below Prov | Received SSM (PQL) is below provisioned PQL. |
| No SSM status | 8 | Minor | - Ok <br> - Lost | Set port SSM to off to clear. |
| Module boot problem | 9 | Minor | - Ok <br> - Failed | Re-seat module. |
| Clock PLL not locked | 10 | Minor | - Ok <br> - Not Locked | Re-seat module. |
| Input PLL not locked | 11 | Minor | - Ok <br> - Not Locked | Verify input frequency setting. Re-seat module. |
| Phase measurement hardware fault | 12 | Minor | - Ok <br> - Bad | Re-seat module. |
| Frequency measurement range exceeded | 13 | Minor | - Ok <br> - Exceeded | Input frequency is greater than threshold. Monitor frequency and if persistent, check source. |
| Hardware configuration fault | 14 | Major | - Ok <br> - Failed | Call Datum Customer Service. Return to factory. |
| GPS Input Module Alarms |  |  |  |  |
| Hardware configuration fault | 0 | Major | - Ok <br> - Failed | Call Datum Customer Service Return to factory. |
| GPS Engine tracking status | 1 | Minor | - Ok <br> - Not Tracking | No visible satellites seen at startup. |
| Antenna connection status | 2 | Minor | - Ok <br> - Not Connected | Verify that: <br> - The antenna is connected <br> - The cable and connectors are not damaged <br> - The antenna placement is correct |

Table A-1. Module Alarm Messages (Continued)

| Alarm Description | Alarm <br> Number | Default Alarm Level | Status Messages | Description/Corrective Action |
| :---: | :---: | :---: | :---: | :---: |
| Antenna condition fault | 3 | Minor | - Ok <br> - Shorted | Ring out the cable to ensure that the center conductor is not shorted to the sleeve, then verify that: <br> - The antenna cable is connected properly <br> - The cable and connectors are not damaged |
| GPS Engine hardware fault | 4 | Minor | - Ok <br> - Bad | Reseat module. If problem persists, call Datum Customer Service. |
| Engine system fault | 5 | Minor | - Ok <br> - Bad | If alarm doesn't clear after 30 minutes, call Datum Customer Service. |
| Position unknown fault | 6 | Minor | - Ok <br> - Unknown | If alarm doesn't clear after 1 hour, call Datum Customer Service. |
| Clock PLL status fault | 7 | Minor | - Ok <br> - Not Locked | Reseat module. Ensure that the GPS priority level is set to 1 . If problem persists, call Datum Customer Service. |
| Manufacturing item number fault | 8 | Minor | - Ok <br> - Unknown | Call Datum Customer Service. Return to factory. |
| System software fault | 9 | Minor | - Ok <br> - Failed | Reseat module. If problem persists, call Datum Customer Service. |
| Phase hardware fault | 10 | Minor | - Ok <br> - Bad | Reseat module. If problem persists, call Datum Customer Service. |
| DS1/E1 Output Module |  |  |  |  |
| Redundant module status | 0 | Major | - Ok <br> - Failed | Output alignment problem. Disable module, then re-enable. |
| Mismatched DS1/ E1 modules in redundant configuration | 1 | Major | - Ok <br> - Invalid | A redundant pair has one DSI module and one E1 module. Replace module. |
| Loss of clock source A | 2 | Major | - Ok <br> - Lost | Clock module in slot A1 is in warm-up mode or has other problems. |
| Loss of clock source B | 3 | Major | - Ok <br> - Lost | Clock module in slot A12 is in warm-up mode or has other problems. |

## Table A-1. Module Alarm Messages (Continued)

| Alarm Description | Alarm Number | Default Alarm Level | Status Messages | Description/Corrective Action |
| :---: | :---: | :---: | :---: | :---: |
| Loss of clock source C | 4 | Major | - Ok <br> - Lost | Reference signal is in LOS and both clocks have been removed or are in warm-up. |
| Clock below minimum clock level | 5 | Major | - Ok <br> - Below | Clock A or B is below output module setting. |
| Clock not selected for output | 6 | Major | - Selected <br> - Not Selected | No clocks, no output. |
| Output port fault (displayed as hex value) | 7 | Major | - Ok <br> - Active | Indicates which output port is in fault (typically shorted). Remove short and re-enable port. |
| VCXO status | 8 | Major | - Ok <br> - Lost | VCXO problems, re-seat or replace module. |
| Output PLL status | 9 | Major | - Ok <br> - Lost | No clocks or VCXO. Re-seat and check clocks. |
| Configuration status | 10 | Major | - Ok <br> - Failed | Redundant configuration mismatch. Re-seat or replace module. |
| Hardware configuration fault | 11 | Major | - Ok <br> - Failed | Call Datum Customer Service. Return to factory. |
| Loss of clock source D | 12 | Major | - Ok <br> - Lost | Only in SDU. Loss of backup clock. Check cable. |
| Composite Clock Output Module |  |  |  |  |
| Redundant module status | 0 | Major | - Ok <br> - Failed | Output alignment problem. Disable module, then re-enable. |
| Mismatched DS1/E1 modules in redundant configuration | 1 | Major | - Ok <br> - Invalid | A redundant pair has one DSI module and one E1 module. Replace module. |
| Loss of clock source A | 2 | Major | - Ok <br> - Lost | Clock module in slot A1 is in warm-up mode or has other problems. |
| Loss of clock source B | 3 | Major | - Ok <br> - Lost | Clock module in slot A12 is in warm-up mode or has other problems. |
| Loss of clock source C | 4 | Major | - Ok <br> - Lost | Reference signal is in LOS and both clocks have been removed or are in warm-up. |

Table A-1. Module Alarm Messages (Continued)

| Alarm <br> Description | Alarm <br> Number | Default <br> Alarm <br> Level | Status Messages | Description/Corrective Action |
| :--- | :---: | :---: | :--- | :--- |
| Loss of clock <br> source D | 5 | Major | - | Ok <br> Lost |
| Clock below minimum <br> clock level | 6 | Major | - | Ok <br> - Below |

Table A-1. Module Alarm Messages (Continued)

| Alarm Description | Alarm Number | Default Alarm Level | Status Messages | Description/Corrective Action |
| :---: | :---: | :---: | :---: | :---: |
| Clock below minimum clock level | 6 | Major | - Ok <br> - Below | Clock A or B is below output module setting. |
| Clock not selected for output | 7 | Major | - Selected <br> - Not Selected | No clocks, no output. |
| VCXO status | 8 | Major | - Ok <br> - Lost | VCXO problems, re-seat or replace module. |
| Output PLL status | 9 | Major | - Ok <br> - Lost | No clocks or VCXO. Re-seat and check clocks. |
| Configuration status | 10 | Major | - Ok <br> - Failed | Redundant configuration mismatch. Re-seat or replace module. |
| Internal port fault, Active 4000 | 11 | Major | - Ok <br> - Active | Driver chip indicated a port fault on port 2 ( 4000 Hex ). |
| Hardware configuration fault | 13 | Major | - Ok <br> - Failed | Call Datum Customer Service. Return to factory. |

## A. 2 Event Messages

Table A-2 lists event messages categorized by module. Each section lists status messages associated with each module and an event description of each message.

Table A-2. Module Event Messages

| Event Message | Event \# | Event Description |
| :---: | :---: | :---: |
| Clock Module Events |  |  |
| Install, Clock Module | 129 | Module installation |
| Remove, Clock Module | 130 | Module removal |
| Enable, Clock Module, COML | 131 | Module enabled |
| Disable, Clock Module, COML | 132 | Module disabled |
| Restart, in 5 seconds, COML | 133 | User requesting for a module to reboot |
| Cannot Enable, Clock Module, COML\} | 134 | Inability to enable module |
| Clk Select | 144 | Which clock module is selected to generate output |
| Software phase lock loop (Soft PLL, Acquire/Lock/Hold) | 145 | Software Phase Lock Loop in Acquire, Lock, or Holdover status |
| Inp Select, 1404-02\ | 146 | An Input has been selected as Reference |
| Output Pql, 2 <br> (PQL value 1 to 5 ST2, or 8 ST3) | 147 | The Output PQL has been set to the value shown |
| CLK C Sel, 1A04-02\ | 148 | A reference Input has been selected as an output source |
| Warmup Chg, 1800 sec , COML | 194 | The user has changed the Oscillator warmup time setting |
| Start tc, 240, COML | 195 | The user has changed the Starting Time Constant (TAU) of the Oscillator |
| Dflt tc, 10000, COML | 196 | The user has changed the Default Time Constant (TAU) of the Oscillator |
| Clk AR< On, COML | 199 | The user has changed the Clock Auto-Return (ON \| OFF) |
| Inp Switch, AR On, COML\} | 200 | The user has changed Input Auto-Return (ON \| OFF) |
| LO, Dis, COML | 201 | The user has changed the Local Oscillator Output (ON \| OFF) on the LO Output connector |
| Inp Sel Mode, PQL, COML\} | 202 | Reference selection mode (Priority Quality Level - PQL) |
| Err Delay, (1), $300 \mathrm{sec}, \mathrm{COML}$ | 251 | The user has changed Alarm Delay time |
| Alm Level, (2), Maj, COML\} | 252 | The user has changed Alarm level (IGNORE, REPORT, MINOR, MAJOR, CRITICAL) |

## Table A-2. Module Event Messages (Continued)

| Event Message | Event \# | Event Description |
| :---: | :---: | :---: |
| Elevate Time, $7200 \mathrm{sec}, \mathrm{COML}$ | 253 | The user has changed alarm elevation time change |
| Setup, User Default, COML | 254 | The user has set the module's configuration |
| Communications Module Events |  |  |
| KeepAlive, SSU2000 | 105 | The Keep Alive function has been enabled/disabled |
| Install, Comms Module\} | 129 | Module Installation |
| Remove, Comms Module\} | 130 | Module Removal |
| Enable, Comms Module, COML | 131 | The Comms Module has been Enabled |
| Disable, Comms Module, COML | 132 | The Comms Module has been Disabled |
| Restart, in 5 seconds, COML | 133 | Module reboot (Warm boot) |
| Log In, JAY, COML, level: $2 \backslash$ | 144 | User at indicated level has logged in on indicated port |
| Log Out, JOHN, COML, level: $2 \backslash$ | 145 | User at indicated level has logged out from indicated port |
| Auto Out, SMITH, COML, level: 3:\} | 146 | System automatically logging out a user |
| Msg, <HELLO USER>, COML | 147 | Message sent from a user |
| Not Acknowledged, 1A01\} | 148 | Module configuration could not be obtained |
| Module Status, Bad, 1A04 | 150 | Module did not boot properly |
| UTC TIME, Valid/Invalid | 151 | Time of startup, when NTP is enabled but GPS time is not being used |
| TODSYNC, TIMEOUT | 152 | Time of day (TOD) was requested by the Comms module, no response from the GPS module |
| Upgrade Image, Start/Complete | 153 | System firmware upgrade was started or completed |
| Upgrade, 1A01 | 154 | Module's firmware upgrade has started |
| Upgrade ACK, 1A01 | 155 | Module's firmware upgrade was completed |
| Upgrade NAK, 1A01 | 156 | Module's firmware upgrade was not completed |
| Hdw Config Err, 1A06 | 157 | Call Datum Customer Service. Return to factory. |
| NTP Mode, Client/Broadcast/BClient/ Local | 158 | The SSU is configured with NTP running in a NTP Client, Broadcast, or Broadcast Client server mode; Local is displayed when NTP server is initialized. If GPS is not installed or setup, or NTP has not been configured NTP remains in Local mode and uses Comms module time |
| Reset, CIk-B, COML | 159 | The clock listed was reset by the user |
| InitUserTable, TOM, COML | 192 | Administrator initialized user database |

## Table A-2. Module Event Messages (Continued)

| Event Message | Event \# | Event Description |
| :---: | :---: | :---: |
| Communications Module Events (Continued) |  |  |
| Add User, Andy, COML\} | 193 | Administrator added a user to user database |
| Mod User, DON, COMLI | 194 | User/Administrator modified user database |
| Del User, TESTUSER, COML | 195 | Administrator deleted user from user database |
| Pql Table, DS1, pql (5)=ST2, COML | 196 | PQL database has been modified |
| Pql Table Dflt, COMLI | 197 | PQL database has been set to factory defaults |
| Unit Name, AUSTIN, COMLI | 198 | The SSU name has been changed |
| NTP Peer Add, 192.5.41.40, Client, COML\} | 199 | A NTP client was added at the IP address shown |
| NTP Peer Del, 192.5.41.40, Client, COMLI | 200 | A NTP client was deleted at the IP address shown |
| NTP Brd Timer, 64 seconds, COML\} | 201 | The NTP broadcast server timer has been set to the interval shown |
| SNMP User, ADD, id=1, COML | 202 | A SNMP user has been added in the position of the user table shown |
| SNMP Mode, Ena, COML | 203 | A SNMP Mode has been enabled |
| SNMP Manager, Init, 192.5.41.3, COML | 204 | A SNMP Manager has been initialized at the IP address shown |
| Evt Blocked, SET, 2A02, COML | 205 | SNMP events (Traps) will not be generated from the module shown |
| SNMP Trap, ALM, COML | 206 | The SNMP Trap Port has been set to send traps on alarms only by the user |
| Chg KeepAlive, ALL, 15 minute, COMLI | 207 | The Keep Alive timer has been set to the interval shown |
| Err Delay, (1), $300 \mathrm{sec}, \mathrm{COML}$ | 251 | An alarm delay time change |
| Alm Level, (2), Rep, COMLI | 252 | An alarm level change |
| Elevate Time, 3600 sec , COML | 253 | An alarm elevation time change |
| Setup, Save, COML | 254 | User defaults change or save |
| DS1/E1 Input Module Events |  |  |
| Install, Input Module\} | 129 | Module Installation |
| Remove, Input Module\} | 130 | Module Removal |
| Enable, Input Module, COML | 131 | The Input module has been enabled |
| Disable, Input Module, COML\} | 132 | The Input module has been disabled |
| Restart, in 5 seconds, COML | 133 | Module re-boot |
| Cannot Enable, Input Module, COML | 134 | Internal firmware conflict. Restart module, if the problem persists, Call Datum Customer Service |

## Table A-2. Module Event Messages (Continued)

| Event Message | Event \# | Event Description |
| :---: | :---: | :---: |
| Zero Phase, B, COML | 144 | User has forced the phase to be cleared |
| Rcv Pql Chg, 3 | 145 | Input has received a different PQL |
| Pha Buildout, 334000, 335000 | 146 | Input performed phase buildout and difference in Phase that cause PBO |
| DS1 Framer, ESF, COML | 193 | An Input framer setup change |
| E1 Framer, CCS, COML | 194 | An Input framer setup change |
| Freq, 10 MHz , COML | 195 | User changed input framer setup |
| ZS, On, COML | 196 | User changed input framer setup |
| SSM, Off, COMLI | 197 | User changed input SSM capability |
| CRC, On, COMI\} | 198 | User changed input framer setup |
| Port, Dis, COML | 199 | User Enabled \| Disabled input port |
| SSM, Auto, COML | 200 | User changed SSM setup |
| Priority, 5, COML | 201 | User changed input priority level |
| SSM Bit, 4, COML | 202 | User changed SSM Bit location (E1 only) |
| Prov PQL, 5, COMLI | 203 | User changed input provisioned PQL |
| MTIE, T100, L1, 550, COML | 204 | User changed input MTIE limits (L1 \| L2) |
| Gain, On, COMLI | 205 | User changed the input gain control |
| CSFlt, Off, COML | 206 | User changed input Cesium Fault control |
| Err Cnt, BPV, 16, COML | 207 | Signal Alarm Error Count (LOS, AIS, OOF, BPV, or CRC) |
| Clr Cnt, OOF, 5, COML | 208 | Current Signal Alarm Clear Count (LOS, AIS, OOF, BPV, or CRC) |
| Freq Err Limit, Clk-A, 100 | 209 | The frequency error limit settings have been changed |
| Freq Clr Limit, Clk-A, 800 | 210 | The frequency clear limit settings have been changed |
| MTIE CIr Limit, T100, L1, 500, COML | 211 | The MTIE error limit settings have been changed |
| MTIE Limit, DS1, COML, Setting | 212 | The MTIE clear limit settings have been changed |
| PBO, Report, COMLI (Disable\|Event|Report|None) | 213 | Phase Build-out system response has been changed to the indicated setting |
| Freq Tau, CIk-A, 400, COML\} | 214 | The frequency TAU limits have been set |
| Err Delay, (0), $10 \mathrm{sec}, \mathrm{COML}$ | 251 | An alarm delay time change |
| Alm Level, (2), Maj, COML | 252 | An alarm level change |
| Elevate Time, $86400 \mathrm{sec}, \mathrm{COML}$ | 253 | An alarm elevation time change |
| Setup, Save, COML | 254 | User defaults have been set and saved |

## Table A-2. Module Event Messages (Continued)

| Event Message | Event \# | Event Description |
| :---: | :---: | :---: |
| GPS Input Module Events |  |  |
| Install, GPS/CDMA Module\} | 129 | Module Installation |
| Remove, GPS/CDMA Module\} | 130 | Module Removal |
| Enable, GPS/CDMA Module\} | 131 | The input module has been enabled |
| Disable, GPS/CDMA Module\} | 132 | The input module has been disabled |
| Restart, in 5 seconds, COMLI | 133 | Module re-boot |
| Cannot Enable, GPS/CDMA Module, COMLI | 134 | Inability to enable module |
| Zero Phase, B, COMLI | 144 | User has forced the phase to be cleared |
| Priority, 3, COML (0 to 10) | 193 | User has changed the Priority level on the GPS input module to the level shown |
| Prov PQL, 2, COML | 194 | User has changed the Priority quality level to the level shown |
| ElMask, Pos 10, COMLI | 195 | User has changed the elevation mask on the input module to the level shown |
| Satellite Ignore, 3, COML | 197 | User has set the GPS engine to ignore the satellite number indicated |
| Position, 300 Avg, COML Position, 300 AvgCnt, COML | 198 | The position has been calculated, AvgCnt=10 to 1000 |
| Tracking Mode, On, COML\} | 199 | User specified GPS positioning mode has been set |
| Pos Set by Rec, Information Locked, COMLI | 200 | User specified GPS positioning mode has been set to Calc and the position has been recalculated and locked in |
| Engine Set Time, GPS | 201 | System time has been set to UTC by the GPS module |
| PDOP, 2, COMLI | 203 | User has changed the PDOP on the GPS input module to the setting shown |
| CDMA FREQ, 882.750 MHz , COML | 204 | User has changed the CDMA frequency being used |
| Err Delay, (0), $10 \mathrm{sec}, \mathrm{COML}$ | 251 | An alarm delay time change |
| Alm Level, (2), Maj, COMLI | 252 | An alarm level change |
| Elevate Time, 86400 sec , COML | 253 | An alarm elevation time change |
| Setup, Save, COML | 254 | User defaults have been set and saved |

## Table A-2. Module Event Messages (Continued)

| Event Message | Event \# | Event Description |
| :---: | :---: | :---: |
| Output Module Events |  |  |
| Install, Output Module\ | 129 | Module Installation |
| Remove, Output Module\} | 130 | Module Removal |
| Enable, Output Module, COML\} | 131 | Output module has been enabled |
| Disable, Output Module, COML | 132 | Output module has been disabled |
| Restart, in 5 seconds, COMLI | 133 | Module re-boot |
| Cannot Enable, Output Module, COMLI | 144 | Output module cannot be enabled |
| Frame Mode, ESF, COML | 193 | Output framing type change |
| ZS, On, COML | 194 | User changed output framing type |
| DS1 LEN, [0-5], len=133 ft., COML\} | 195 | User changed output line length (DS1 only) |
| CRC, On, COML | 199 | User has changed output framing type |
| SSM Bit, 8, COML | 201 | User has changed output SSM bit position (E1 only) |
| Min Clk Level, ACQ, COML | 202 | User has changed Minimum Clock Level to turn on outputs |
| Bypass, On, COMLI | 203 | User has changed Bypass mode of operation |
| DutyCycle, Port= [0-1], 50/50, COML | 204 | CC signal duty cycle settings have been changed for the port shown |
| Delay, Port= [0-3], 4000ft, COML | 205 | CC signal phase offset settings have been changed for the port shown |
| FltMode, ON, COML | 206 | Fault recovery strategy has been changed |
| Alm Level, (0), Maj, COMLI | 252 | An alarm level change |
| Elevate Time, 86400 sec , COML | 253 | An alarm elevation time change |
| Setup, User Default, COML | 254 | User defaults have been set and saved |

## In this Section ...

. SSU-2000 Control Languages

- TL1 Command Interface
- Interactive Command Set
- NTP Support
- SNMP Protocol


## Appendix B Communications Protocol

This appendix provides information about the Transaction Language One (TL1), Interactive Command Set (ICS), and Simple Network Management Protocol (SNMP) control languages that are used to communicate with the SSU-2000.

## B. 1 SSU-2000 Control Languages

Software embedded in the SSU-2000 hardware allows operators to query and manage an SSU-2000 unit from a local or remote management terminal using one of three control interfaces. These management agents allow operators to change factory default settings, set or restore stored configuration settings, configure and provision the SSU-2000 system to meet the requirements of a unique environment, and perform maintenance and troubleshooting.

The SSU-2000 unit supports three control interfaces. Each grants access to command functions according to the security levels assigned to users. The control interfaces are:

- TL1 - The Transaction Language One (TL1) control language, perhaps the dominant telecommunications industry ASCII command line interface, provides a standard manmachine language. The TL1 language is defined in Bellcore document TR-NWT000831, Issue 3, Revision 1, December 1993.
- ICS - The Interactive Command Set (ICS) control language also called the ASCII command set, can be used to control the SSU-2000 from a terminal connected to one of the SSU-2000 RS-232 serial ports.
- SNMP - The Simple Network Management Protocol (SNMP) protocol is based on a client server query-response mode and is supported by Ethernet only.

There are four main executables (software versions) available for the SSU-2000 as shown in Table B-2. They are the Basic System Load, Basic with NTP Support, Basic with SNMP Support, and Basic with SNMP and NTP Support. This section provides information about the TL1 and ICS control languages for all four versions of software.

- Section B.2, TL1 Command Interface defines the TL1 command and response specifications.
- Table B-5 defines the TL1 retrieve commands, access identifier (AID) code, description and use of the command function, and the response message format for each.
- Table B-6 defines the TL1 set commands, access identifier (AID) code, description and use of the command function, and the response message format for each.
- Table B-7 defines other TL1 commands for logging onto and off the SSU-2000 system, and for activating, disconnecting, and removing modules from the SSU-2000 unit.
- Section B.3, Interactive Command Set defines the ICS commands, responses, and events.
- Section B.4, NTP Support gives a description of NTP support functionality.
- Section B.5, SNMP Protocol identifies SNMP command functions, as well as features supported in this software version.


## Recommendation ...

To ensure optimal system performance using the Communications module main executable software shown in Table B-2, Datum recommends that the module hardware and software used be at the minimum revision levels as shown in Table B-1.

Table B-1. Module and Software Revision Levels

| Module Part \# | Module Name | Software <br> Revision Level | Hardware <br> Revision level |
| :--- | :--- | :---: | :---: |
| $23413013-001-0$ | DS1 1 Port Input Module | B | B |
| $23413014-001-0$ | E1 1 Port Input Module | B | B |
| $23413013-002-0$ | DS1 3 Port Input Module | B | B |
| $23413014-002-0$ | E1 3 Port Input Module | B | B |
| $23413019-000-0$ | GPS Input Module | A | A |
| $23413016-000-0$ | Clock Module (STR 2E) | B | A |
| $23413015-000-0$ | Clock Module (STR 3E) | B | A |
| $23413017-000-0$ | DS1 Output Module | A | C |
| $23413018-000-0$ | E1 Output Module | A | C |

Table B-1. Module and Software Revision Levels (Continued)

| Module Part \# | Module Name | Software <br> Revision Level | Hardware <br> Revision level |
| :--- | :--- | :---: | :---: |
| $23413159-000-0$ | 2048 kHz Output Module | A | A |
| $23413158-000-0$ | CC Output Module | A | A |
| $23413012-000-0$ | Communications Module | A | E |
| $23413012-001-0$ | Communications Module | A | E |

Table B-2. Communications Module Software

| Part Number | Software Version |
| :--- | :--- |
| $24113012-000-0$ | Basic System Load |
| $24113012-001-0$ | Basic + NTP Support |
| $24113012-002-0$ | Basic + SNMP Support |
| $24113012-003-0$ | Basic + NTP and SNMP Support |

## B. 2 TL1 Command Interface

Telcordia Technologies (formerly Bellcore) specified the TL1 command interface to be used as a standard man-machine language for controlling telecommunications network elements. TL1 provides command sets to support all operation, administration, maintenance, and provisioning tasks required to maintain and control an SSU-2000 system. These tasks include configuring and provisioning security, monitoring system performance, configuring hardware, locating and handling faults, and performing equipment diagnosis and testing.

## 巨 <br> Note ..

To communicate with the SSU-2000 unit, you must first connect a terminal to one of the three SSU-2000 EIA-232-C serial communication ports. After setting up the Ethernet port, you can also communicate with the SSU-2000 using an Ethernet Telnet session.

## To set up an SSU-2000 port for TL1 communications:

1. Log on to one of the SSU-2000 EIA-232 serial ports using a Supervisor-level (or higher) user name and password.
2. Set port A, B, or L to TL1 mode. For example, to set the local port (COML) to TL1 mode, at the system prompt, type:

COMM L MODE TL1

- The communications mode settings for the COMM A and COMM B ports (located on the rear of the unit) are stored in non-volatile RAM, and remain in effect even after restarting the SSU-2000 unit.
- The communications mode settings for the COMM L (local) port (located on the front of the unit) always default to ASCII mode on startup.
- When connecting via Ethernet, a Telnet session to port 2000 (decimal) will open in TL1 mode and remain until the session is terminated. Once connected in TL1 mode, the user must log in using the ACT-USER command with a user name and password (if security is active on the unit).


## To close the serial port for TL1 communications:

- Type EXIT, then press Enter, or command or send three ESCape characters from the management terminal. This logs you out and returns the port to the default communications mode.


## To log off the user and exit from an Ethernet connection:

- Type EXIT, then press Enter, or disconnect the Telnet session or.
- Type CANC-USER, then press Enter to $\log$ out and return the port communication setting to security level 0 . This command does not change the communications mode.

Note ...

The automatic time-out is disabled for the port when you are communicating in TL1 mode using one of the serial communications ports or the Ethernet port.

## B.2.1 TL1 Command and Response Conventions

This section describes general and specific conventions for expressing TL1 command and response parameters for the four types of operations application messages:

- Input Command Message - This message determines the action that the SSU-2000 will take. For a detailed description of input command messages and conventions, see Section B.2.1.1, Input Command Message Conventions.
- In-Process Acknowledgment - The in-process acknowledgment (IP) response message is sent in response to a command that the SSU-2000 is unable to respond to within two seconds. For a detailed description of in-process acknowledgment response messages and conventions, see Section B.2.1.2, In-Process Acknowledgment Response Message Conventions.
- Output response message - The output response message indicates whether the command was complied with (COMPLD) or denied (DENY). For a detailed description of output response messages and conventions, see Section B.2.1.3, Output Response Message Conventions.
- Autonomous response or report message - The autonomous response or report message is an output generated by the SSU-200 due to an event, such as an alarm, or a change in status in the system. For a detailed description of autonomous response or report messages and conventions, see Section B.2.1.4, Autonomous Report Conventions.

TL1 General Conventions - TL1 uses English-like acronyms and shorthand or abbreviations in a format that can be read and composed by humans.

Follow these general conventions for entering all TL1 parameters:

- Enter all command characters in upper-case. In the command syntax, lower-case characters indicate parameters that you must supply.
- All commands must contain the cmd, tid, and ctag fields.
- You may omit trailing commas in the parameters field.
- Terminate command lines with a terminating semicolon (;) and an end-of-line designator (<cr><lf> or <cr lf>). The SSU-2000 executes the command when it receives the terminating semicolon in the command entry.
- $\wedge$ is a blank that must appear in a command or response.
- : is a block separator character.
- :: indicates a null field for a block.
- ; indicates the end of the message.
- <cr> and <lf> or <cr lf> indicate the ASCII carriage return (CR) and line feed (LF) codes used as a line terminator and may be used separately or combined.
- The ASCII cancel code character (hex 18) can be used to cancel a partially sent command and clear the input buffer.


## B.2.1.1 Input Command Message Conventions

Command messages entered and sent by the user determine the action that the SSU-2000 will take. Command messages are input messages, and are always followed by an acknowledgment or output response message.

The format for the input command message is:

```
cmd:tid:[aid]:ctag[:[gb]:<other>;<cr lf>
```

where:

- cmd (Command) is a descriptive string of letters that represents the input command (Table B-5 through Table B-7). The command string consists of a standard TL1 command verb, followed by one or two command modifiers. The modifiers identify the subject of the command verb and each may be as many as five characters. If two modifiers are used, they must be separated by dashes: verb- mod1- mod2.
- tid (Target Identifier) represents the name assigned to the SSU-2000. The assigned name must be either null or match the name assigned to the SSU-2000. If the tid is not null, it may must begin with a letter and may contain as many as 20 alpha-numeric characters. See the SET-NAME command in Table B-6.

```
EN NOTE ..
The system does not generate a response for entries without a valid tid.
```

- aid (Access Identifier) is an optional field that represents the shelf, module, and port within the $\mathrm{SSU}-2000$ to which the command is addressed or to which the response applies. The aid must be null (::, indicating ALL or not used), ALL (indicating all modules and ports related to the command type), or the aid assigned to an entity in the SSU-2000. The aid allows aliases for clock and buffer modules.

Follow these conventions for entering the aid field:

|  | SxAy-z |
| :--- | :--- |
| or | ALL |
| or | SxBUF-w |
| or | SxCLK-w |

where:
$\mathbf{x} \quad$ SSU-2000 main (1) or expansion unit (shelf) number (2-5)
A placeholder used to separate the shelf number form the slot position
y $\quad$ SSU-2000 slot position (1-16)
$\mathbf{z}$ port number (1-20)
ALL all modules or ports to which the command applies
w buffer module A or B or clock module A or B

Specify multiple aids using the ampersand (\&)
Use a single ampersand (\&) to indicate aid 1 and aid2
Use a double ampersand $(\boldsymbol{\&} \boldsymbol{\&})$ to indicate a range from aid1 to aid2
The $\mathbf{y}$ or $\mathbf{z}$ part of the aid also uses the ampersand $(\boldsymbol{\&})$

- ctag (Correlation Tag) field is a six-digit alpha-numeric message identifier code that is received with the command and returned in the response, for correlation of message and response within the operating system. The ctag can be any combination of six alphanumeric characters randomly generated by the user.
- gb (General Block) is an field that is not used by the SSU-2000 but that you must indicate by a double colon, that is, by preceding any parameters following the ctag field with double colons (::).
- other is a field that is used for commands that require other information. The format for this field is specified in the individual command descriptions.


## B.2.1.2 In-Process Acknowledgment Response Message Conventions

Each command received by the SSU-2000 with a valid tid generates a response when the terminating semicolon is received, followed by an output response message or the output response.

The SSU-2000 sends the in-process acknowledgment (IP) only if it is unable to respond to the command within two seconds. The requested response is then sent in full when the SSU-2000 data is available.

The in-process acknowledgment response always begins with a carriage return and two line feed characters, and ends with the header line containing the source identifier (sid), defined below, and the date ${ }^{\wedge}$ time stamp.

The format for the IP acknowledgment message is:

```
<cr lf lf>
^^^sid^date^time <cr lf>
IP^ctag <cr lf>
<
```

where:

- sid (Source Identifier) is the returned ID, and is the same as the tid in the input command message to which the IP acknowledgment is responding.
- date is the current year, month, and day date in the SSU-2000 system in the format: YY-MM-DD.
- time is the current hours, minutes, and seconds timestamp information in the SSU-2000 system in the 24-hour format: HH-MM-SS.
- IP is the in-process response message that the $\mathrm{SSU}-2000$ sends in response to a command only if the SSU is unable to respond to the command within two seconds. The SSU sends the requested response in full when the data is available.
- ctag (Correlation Tag) field is a six-digit alpha-numeric message identifier code that is received with the command and returned in the response, for correlation of message and response within the operating system.
- The IP acknowledgment response always terminates with the less-than character (<). The semicolon appears after the requested output response message is sent.


## B.2.1.3 Output Response Message Conventions

The output response indicates whether the SSU-2000 complied with (COMPLD) or denied (DENY) the input command.

The COMPLD Output Response Message Conventions - If the message is received correctly and can be processed by the SSU-2000 within two seconds, the complied message is sent with data that was requested in the input command message. The requested data is included in the response message lines and is always enclosed in quotation marks.

The format for a complied (COMPLD) output response message is:

```
<cr lf lf>
^^^sid^date^time <cr lf>
M^^ctag^COMPLD <cr lf>
[^^^"(response message" <cr lf>]
[...]
;
```

where:

- sid (Source Identifier) is the returned ID, and is the same as the tid in the input command message to which the IP acknowledgment is responding
- date is the current year, month, and day date in the SSU-2000 system in the format: YY-MM-DD
- time is the current hours, minutes, and seconds timestamp information in the SSU-2000 system in the 24 -hour format: HH-MM-SS
- ctag (Correlation Tag) field is a six-digit alpha-numeric message identifier code that is received with the command and returned in the response, for correlation of message and response within the operating system
- COMPLD is the complied message
"response message" is the response message. The response message line for complied messages always begins with 3 spaces ( $\wedge \wedge \wedge)$ followed by the response message enclosed in quotation marks, and terminated by <cr lf>. Multiple lines of response messages are allowed. Each command response is terminated by a semicolon following the last <cr lf>.

The DENY Output Response Message Conventions - The DENY response contains a fourcharacter error code (ercd) that describes the reason for the denied response. For example, the error code ICNV indicates Input Command Not Valid. See error codes in Table B-3.

The SSU-2000 sends the DENY response if:

- the cmd is not valid
- the aid is not valid
- the ctag is not valid, indicated by a response containing the ctag set to a single zero character (0)
- the unit is unable to comply with the request for the reason indicated by the ercd

The format for a denied (DENY) output response message is:

```
<cr lf lf>
^^^sid^date^time <cr lf>
M^^ctag^DENY <cr lf>
```

^^^ercd <cr lf>
where:

- $\quad$ sid (Source Identifier) is the returned ID, and is the same as the tid in the input command message to which the IP acknowledgment is responding
- date is the current year, month, and day date in the SSU-2000 system in the format: YY-MM-DD.
- time is the current hours, minutes, and seconds timestamp information in the SSU-2000 system in the 24-hour format: HH-MM-SS

■ ctag (Correlation Tag) field is a six-digit alpha-numeric message identifier code that is received with the command and returned in the response, for correlation of message and response within the operating system

- DENY is the deny message
- ercd (Error Code) is a four-character error code that explains the reason for the deny, and is one of the following defined codes (other error codes may be defined and used, if required).

Table B-3. Denied Response Error Codes

| Error Code | Definition |
| :---: | :--- |
| ICNV | Command Not Valid |
| IIAC | Invalid aid Code |
| IICT | Invalid ctag |
| IITA | Invalid Target Identifier |
| IPEX | Extra Parameter |
| IPMS | Parameter Missing |
| IPNV | Parameter Not Valid |
| SDNR | Data Not Ready |

## B.2.1.4 Autonomous Report Conventions

The SSU-2000 unit sends autonomous reports in response to a detected alarm condition or status change. These reports are similar to the RTRV-ALARM command responses, but contain an alarm code rather than the complied line.

The format for an autonomous report is:

```
<cr lf lf>
^^^sid^date^time <cr lf>
almcde^atag^REPT^mod1[^mod2] <cr lf>
^^^"(response message" <cr lf>
```

where:

- sid (Source Identifier) is the returned ID, and is the same as the tid in the input command message to which the IP acknowledgment is responding
- date is the current year, month, and day date in the SSU-2000 system in the format: YY-MM-DD
- time is the current hours, minutes, and seconds timestamp information in the SSU-2000 system in the 24-hour format: HH-MM-SS
- almcde (Alarm Code) is sent with autonomous reports to indicate the severity level of the reported alarm or event. The alarm code is one of these four two-character codes:
* $\mathrm{C}=$ critical alarm
**= major alarm
*^ $=$ minor alarm
$\mathrm{A}^{\wedge}=$ non-alarm event
- atag (Alarm Correlation Tag) is a six-digit correlation tag that is incremented each time a message is sent
- REPT (Report) indicates an autonomous report
- mod1 (Modifier 1) indicates whether the report is for an alarm (ALRM) or an event (EVNT)
- mod2 (Modifier 2) indicates the cause for the report, such as input signal fault (INP) or hardware module faults (EQPT)
- "response message" is the response message. The format for the response message line is:

```
^^^" [aid]:ntfcncde,condtype,srveff,ocrdat,ocrtm[:condscr]" <cr lf>
```

where:

- ntfencde (Notification Code) is an optional field that further describes the alarm or event in an output response or autonomous report, if required. The notification code is one of these two-character codes:

CR Critical alarm;
MJ Major alarm;
MN Minor alarm:
CL Cleared alarm;
NA Event (not an alarm)

- condtype (Condition Type) indicates the type of alarm or event that the message is reporting
- srveff (Service Affecting or Not Service Affecting) indicates whether the response message affects service: SA (Service Affecting response) or NSA (Not Service Affecting response)
- ocrdat (Occurrence Date) indicates the date of occurrence in the format YY-MM-DD (year, month, day)
- ocrtm (Occurrence Time) indicates the time of the occurrence in the format HH-MMSS (hours, minutes, seconds)
- condscr (Condition Description) is an optional text string which is sent with the alarm or event and which indicates the alarm or event condition


## B.2.2 User Access Levels

The SSU-2000 security system software allows management of operating limits and functions according to user security level. Your security level determines the options available to you.

Each security level accessing the system has a different set of options available, for instance, a user does not have as many options available as a technician.

The password security level determines the options available. Each incremental security level incorporates all of the options from the lower numbered security levels and additional options at that level. For instance, a User does not have as many options available as a Technician. To determine your security level, contact your Administrator.

Table B-4 summarizes each security access level, ID number, and the operator privileges for each level. To determine your security level, contact your Administrator.

Table B-4. User Access (Security) Levels

| Level | ID | Description |
| :--- | :--- | :--- |
| Idle | 0 | Security level 0 is available when no user is logged in. This level allows Idle <br> users to view a list of available commands (HELP), syntax, software version <br> number, unit id, or to login. |
| User | 1 | Security level 1 allows User users perform level 0 functions and to view <br> information about the current configuration and operation, and change <br> communication settings such as line termination and echo. Changes made by <br> the user remain in effect only until the user logs out. |
| Technician | 2 | Security level 2 allows Technician users (CRAFT persons) to perform levels 0 <br> through 1 functions, and to read or set all installation functions. |
| Supervisor | 3 | Security level 3 allows Supervisor users to perform levels 0 through 2 <br> functions, and to read or set all functions. |
| Administrator | 4 | Security level 4 allows Administrator users to perform levels 0 through 3 <br> functions, view and set software configurations, add, delete, or modify the user <br> table, or log off any user from any port. |

## B.2.3 Retrieve Commands and Responses

This section contains a table which provides an alphabetical listing of TL1 retrieve commands, a description of the command which provides the valid aid codes to use in the command, and an example and description of the components of message lines. Table B-5 provides a listing of the TL1 retrieve commands.

Table B-5. TL1 Retrieve Commands

| Command | Description |
| :---: | :---: |
| RTRV-ALARM:[tid]:[aid]:ctag; or RTRV-ALM:[tid]:[aid]:ctag; | Valid aid code: ALL, SxAy[-z] <br> This command reports all active alarms from the SSU-2000 unit or designated modules with an aid indicating which module or port is generating the alarm. The response is the complied message followed by the alarm report message(s). <br> There may be none or multiple lines in the report, one for each active alarm. There is no report message for modules or ports that have no alarm condition. The format for each response message line, using the definitions above, is: ```^^^"aid:ntfoncde,condtype, srveff,\"condstr\"" <cr lf> where: ntfcncde = Notification Code (CR, MJ, MN, CL) condtype = Condition Type (event number) srveff = service affecting flag (SA, NSA) condstr = condition description string.``` |

Table B-5. TL1 Retrieve Commands (Continued)

| Command | Description |
| :---: | :---: |
| RTRV-CONF:[tid]:[aid]:ctag; | Valid aid code: ALL, SxAy <br> This command returns the configuration (inventory management) information for the addressed module(s). The response is the complied message followed by the response message(s). For an aid of ALL a one line summary for each module is returned in the following format: <br> ヘ^^"aid:status[,desc,item,rev,serial]" <cr lf> where: <br> - status = configuration status \{OK\|BAD|RMVD|EMPTY $\}$ <br> - The additional fields are present only if status = OK <br> - desc = text name of the module <br> - item = Datum Item Number <br> - rev = hardware revision level <br> - serial = item serial number <br> If an aid is used in the command and the status is OK, then two or more additional message lines are returned with the following format: <br> ^^^"aid:svcdat,svctim,mandat,"\userdat\"" <cr lf> ^^^"aid:cnt,\"revstr\" " <cr lf> <br> where: <br> - svcdat = in-service date for the module, in the format YY -MM-DD (year, month, day) <br> - svctim = in-service time, as determined from when the module was installed in the system, in the format HH-MM-SS (hours, minutes, seconds) <br> - mandat $=$ manufacture date of YY-MM-DD reported by the module <br> - userdat = any additional information entered for the module in a text string <br> Successive lines contain these fields: <br> - cnt = software version count (from 0 to 5) <br> - revstr = revision string returned by the module, generally as X.yy [YY-MM-DD], where $\mathbf{X}=$ major revision number, $\mathbf{y} \mathbf{y}=$ minor revision, and the optional date $=$ the date the version was created, if available. <br> If no additional software is registered on the module, there are no software revision lines present. |

## Table B-5. TL1 Retrieve Commands (Continued)

| Command | Description |
| :---: | :---: |
| RTRV-DATACDMA:[tid]:[aid]:ctag; | Valid aid code: S1A3 or S1A5 (for a CDMA module). <br> This command returns the current tracking data for the specified CDMA input. If the input specified is not a CDMA module, a DENY error message is returned. <br> The format for the valid response message is: <br> ^^^"aid:freq, snr,status"<cr lf> <br> where: <br> - freq indicates the number of the frequency table that is displayed with RTRV-CDMA-FREQ; <br> - $\mathbf{s n r}=$ signal-to-ratio or signal strength measurement; <br> - status = tracking status of CDMA engine, where: $\mathbf{O K}=$ tracking, SRC = searching for base frequency, and ACQ = acquiring signal. |
| RTRV-DATA-GPS:[tid]:[aid]: ctag; | Valid aid code: S1A3 or S1A5 (for a GPS module) <br> This command returns the current tracking data for the specified GPS input. If the input specified is not a GPS module a DENY error message is returned. <br> The format for the valid response message is as many as eight lines in this format: <br> ^^^"aid:chan, prn,snr,status"<cr lf> <br> Each line displays information for one of the satellites currently being tracked: <br> - chan indicates the channel number used to track the corresponding sv <br> - $\quad$ prn = satellite vehicle number <br> - $\mathbf{s n r}=$ signal-to-noise ratio or signal strength <br> - status = the currently tracking status, where: SRC = searching, COD = code locking, FRQ = frequency locking, TIM = setting time, EPH = retrieving Ephemeris data. and OK = satellite being used in the timing solution. |

Table B-5. TL1 Retrieve Commands (Continued)

| Command | Description |
| :---: | :---: |
| RTRV-DATA-GPSAVAIL:[tid]: [aid]:ctag; | Valid aid code: S1A3 or S1A5 (for units with GPS module) <br> This command returns the current tracking data for the specified GPS input. If the input specified is not a GPS module a DENY error message is returned. <br> The format for the valid response message is as many as 12 lines in the format: <br> ^^^"aid:prn, health, asimuth, elevation"<cr lf> where: <br> Each line displays information for one of the satellites currently being tracked; <br> - prn = satellite vehicle number <br> - health = current health of the satellite: $\mathbf{H}$ (healthy) or $\mathbf{U}$ (unhealthy) <br> - azimuth and elevation = calculated orientation of the satellite |
| RTRV-DATA-FREQ:[tid]:[aid]: ctag; | Valid aid code: ALL, S1Ay[-z] <br> This command returns the current frequency measurements for the specified input(s). <br> The format of the response message is: <br> ヘ^^"aid:freqa, freqb">cr lf> <br> where: <br> - freqa = frequency of the port versus clock A <br> - freqb = frequency of the port versus clock B |
| RTRV-DATAINPUT:[tid]:[aid]: ctag; | Valid aid code: ALL, S1Ay[-z] <br> This command returns the current LOS, AIS, OOF, BPV, CRC Error and Clear counts for the specified inputs. <br> The format of the response message is: ^^^"aid:loserr, losclr, aiserr, aisclr, ooferr, oofclr,bpverr,bpvclr,crcerr,crcclr"<cr lf> where: <br> - ???err and ???cIr are the erred second count and cleared second counts for each of the signal faults as listed above. |

Table B-5. TL1 Retrieve Commands (Continued)

| Command | Description |
| :---: | :---: |
| RTRV-DATA-MTIE:[tid]:aid: ctag[::[clksrc][,start][,stop]; | Valid aid code: S1Ay-z <br> This command returns the MTIE data for an input port. The command requires an aid to identify the input port to report data from. It then has the ctag and a null field followed by optional parameters which contain a clock identifier and the start and stop times for the measurement. <br> If no clock source [CLK-A\|CLK-B] is specified, the current output clock is used. <br> The response is the complied message followed by the requested data. The format for each response message line is: <br> "aid: ocrdat, ocrtm, MTIE, clksrc, temper, monval" <cr lf> <br> where: <br> - ocrdat and ocrtm = the beginning date and time the data was collected. <br> - clksrc = clock A or B used for the measurements. <br> - tmper = time period for the measurement data, given in seconds. The maximum tmper values for MTIE are $\mathbf{0 . 0 5}, \mathbf{0 . 1}$, 1, 10, 100, 1000, 10000, and 100000. <br> - monval = data value for the time period, given in nanoseconds. <br> - start = start time specifies the start date and time for data in the format MM-DD,HH-MM. If the date is null but followed by a time, the command defaults to the current date. If the start time is null, but preceded by a date, the command defaults to the current time. If the start date and time are null, the command defaults to the start of the data. The comma must be present to indicate a null start time. <br> - stop = stop time specifies the stop date and time for data in the format MM-DD,HH-MM. If the date is null but followed by a time, the command defaults to the current date. If the stop time is null but preceded by a date, the command defaults to the current time. If the stop date and time is null, the command defaults to the end of the data. <br> Only the values available in the interval between the start and stop times are output. |

Table B-5. TL1 Retrieve Commands (Continued)

| Command | Description |
| :---: | :---: |
| RTRV-DATA-MTIE- <br> HIST:[tid]:aid:ctag[::[clksrc] [,count]; | Valid aid code: S1Ay-z <br> This command returns the Historical MTIE data for an input port. The Historical MTIE data is the 24 -hour MTIE data stored every day at midnight. There are 99 Historical MTIE records stored. The command requires an aid to identify the input port to report data from. The optional parameters are the clock identifier and the number of day(s) of MTIE history to be retrieved from the current day (day 0 ). If no clock source <br> [CLK-A\|CLK-B] is specified, the current output clock will be used. The response will be the complied message followed by the requested data. The format for each response message line is: <br> ^^^"aid:ocrdat, ocrtm, MTIE, clksrc, monvall, monval <br> 2,... monval8"<cr lf> <br> The ocrdat and ocrtm will be the beginning date and time the data was collected. The clksrc is the clock A or B used for the measurements. The monval are the data value for the time period, given in nanoseconds. There are eight of monvals in sequence, and the time periods in sequence are $0.05,0.1,1,10$, $100,1000,10000$, and 100000. |

Table B-5. TL1 Retrieve Commands (Continued)

| Command | Description |
| :---: | :---: |
| RTRV-DATA-PHASE:[tid]:aid: ctag[::tmper[,clksrc[,start] [,stop]]]; | Valid aid code: S1Ay-z <br> Returns phase data from phase history buffers. The command requires an aid to identify the input to report data from. <br> - ctag is followed by a null field <br> - tmper = optional parameter containing the averaging time period for data to be returned: [100\|1000|10000] with the default of $\mathbf{1 0 0}$ if not specified <br> - clksrc = [CLK-A\|CLK-B] or both (on separate message lines) if not specified <br> The format for each response message line is: <br> ヘ^^"aid:ocrdat, ocrtm, PHA, clksrc, tmper, (monval)" <cr lf> <br> where: <br> - ocrdat and ocrtm are the actual date and time the data was collected <br> - clksrc is [CLK-A\|CLK-B] indicating the clock used for the measurements <br> - tmper = time period of the measurement data, given as xSEC where $\mathbf{x}=$ time in seconds <br> - monval = +/- phase values versus clock for the specified input given in nanoseconds enclosed in () <br> - $\quad$ start $=$ start time specifies the start date and time for data in the format MM-DD,HH-MM. If the date is null but followed by a time, the command defaults to the current date. If the start time is null, but preceded by a date, the command defaults to the current time. If the start date and time are null, the command defaults to the start of the data. The comma must be present to indicate a null start time. <br> - stop = stop time specifies the stop date and time for data in the format MM-DD,HH-MM. If the date is null but followed by a time, the command defaults to the current date. If the stop time is null but preceded by a date, the command defaults to the current time. If the stop date and time is null, the command defaults to the end of the data. There is one line for each data point in the specified time between start and stop times. Only the number of values currently available is returned. The maximum stored points for 100 second time period is 7000 ; the maximum stored points for 1000 second time period is 700; the maximum stored points for 10000 second time period is 70 . If a start and stop time is not specified, the default is current value. |

Table B-5. TL1 Retrieve Commands (Continued)

| Command | Description |
| :---: | :---: |
| RTRV-DATA-TDEV:[tid]:aid: ctag[::[clksrc][,start][,stop]; | Valid aid code: S1Ay-z <br> This command returns TDEV data for an input port. This command requires an aid to identify the input port to report data from. It then has the ctag and a null field followed by optional parameters which contain a clock identifier clksrc [CLK-A\|CLKB] and the start and stop times for the measurement. If no clock source is specified, the current output clock is used. The response is the complied message followed by the requested data. The format for each response message line is: <br> ^^^"aid:ocrdat,ocrtm, TDEV, clksrc, temper, monval" <cr lf> <br> where: <br> - ocrdat and ocrtm = the beginning date and time the data was collected. <br> - clksrc = clock used for the measurements. <br> - tmper = time period for the measurement data, given in seconds. <br> - monval = data value for the time period, given in nanoseconds. The maximum tmper values for TDEV are 0.1, $0.3,0.6,1.0,3.0,6.0,10.0,30.0,60.0,100.0,300.0,600.0$, $1000.0,3000.0,6000.0$, and 10000.0 <br> - start = start time specifies the start date and time for data in the format MM-DD,HH-MM. If the date is null but followed by a time, the command defaults to the current date. If the start time is null, but preceded by a date, the command defaults to the current time. If the start date and time are null, the command defaults to the start of the data. The comma must be present to indicate a null start time. <br> - stop = stop time specifies the stop date and time for data in the format MM-DD,HH-MM. If the date is null but followed by a time, the command defaults to the current date. If the stop time is null but preceded by a date, the command defaults to the current time. If the stop date and time is null, the command defaults to the end of the data. <br> Only the values available in the interval between the start and stop times is output. |

Table B-5. TL1 Retrieve Commands (Continued)

| Command | Description |
| :---: | :---: |
| RTRV-DATA-TDEVHIST:[tid]:aid:ctag [::[clksrc][,count]; | Valid aid code: S1Ay-z <br> This command returns the Historical TDEV data for an input port. The Historical TDEV data is the 24 -hour TDEV data stored every day at midnight. There are 99 Historical TDEV records stored. The command requires an aid to identify the input port to report data from. The optional parameters are the clock identifier and the number of day(s) of MTIE history to be retrieved from the current day (day 0). <br> If no clock source [CLK-A\|CLK-B] is specified, the current output clock will be used. The response will be the complied message followed by the requested data. The format for each response message line is: <br> ^^^"aid:ocrdat,ocrtm, TDEV, clksrc, monvall, . ., mon vall6"<cr lf> <br> The ocrdat and ocrtm will be the beginning date and time the data was collected. The clksrc is the clock used for the measurements. The monval are the data value for the time period, given in nanoseconds. There are 16 of monvals in sequence, and the time periods in sequence are $0.1,0.3,0.6$, $1.0,3.0,6.0,10.0,30.0,60.0,100.0,300.0,600.0,1000.0$, 3000.0, 6000.0, and 10000.0. |

Table B-5. TL1 Retrieve Commands (Continued)

| Command | Description |
| :---: | :---: |
| RTRV- <br> EVENT:[tid]:[aid]:ctag:: <br> [count],[start],[stop]; | Valid aid code: ALL, SxAy <br> This command returns stored event data. <br> - aid (or aid range) is optional and may be used to limit the report to specified modules. With an aid of ALL or null, all event data between start and stop time is returned. <br> - count specifies the number of previous events to display [1 to 500]. <br> - start and stop = an optional time interval for events to be retrieved. The start and stop times are specified in the format MM-DD,HH-MM (month. day. time in hours and minutes). One line containing the time stamp and event message is returned for each event in the log. <br> The format for event log report is: <br> "aid:ntfencde, condtype, srveff,ocrdat,ocrtm:c ondscr" <cr lf> <br> where: <br> - ntfencde = Notification Code (CR, MJ, MN, CL, NA) <br> - condtype = Condition Type (event number) <br> - srveff = service affecting flag: SA = service affecting, NSA = non-service affecting <br> - ocrdat = occurrence date <br> - ocrtm = occurrence time <br> - condstr = condition description string <br> - start = start time specifies the start date and time for data in the format MM-DD,HH-MM. If the date is null but followed by a time, the command defaults to the current date. If the start time is null, but preceded by a date, the command defaults to the current time. If the start date and time are null, the command defaults to the start of the data. The comma must be present to indicate a null start time. <br> - stop = stop time specifies the stop date and time for data in the format MM-DD,HH-MM. If the date is null but followed by a time, the command defaults to the current date. If the stop time is null but preceded by a date, the command defaults to the current time. If the stop date and time is null, the command defaults to the end of the data. |

Table B-5. TL1 Retrieve Commands (Continued)

| Command | Description |
| :---: | :---: |
| RTRV-EVENT-ALARM:[tid]: <br> [aid]:ctag::[count],[start], [stop]; | Valid aid code: ALL, SxAy <br> This command returns only alarm information from the stored event data. <br> The format for event log reports is: <br> ヘ^^"aid:ntfencde, condtype, srveff,ocrdat,ocrtm: <br> condscr" <cr lf> <br> where: <br> - ntfencde = Notification Code (CR, MJ, MN, CL) <br> - condtype = Condition Type (event number) <br> - srveff = service affecting flag (SA, NSA) <br> - ocrdat occurrence date <br> - ocrtm = occurrence time <br> - condstr = condition description string <br> - start = start time specifies the start date and time for data in the format MM-DD,HH-MM. If the date is null but followed by a time, the command defaults to the current date. If the start time is null, but preceded by a date, the command defaults to the current time. If the start date and time are null, the command defaults to the start of the data. The comma must be present to indicate a null start time. <br> - stop = stop time specifies the stop date and time for data in the format MM-DD,HH-MM. If the date is null but followed by a time, the command defaults to the current date. If the stop time is null but preceded by a date, the command defaults to the current time. If the stop date and time is null, the command defaults to the end of the data. |
| RTRV-EVENT-REPORT:[tid]: <br> [aid]:ctag::[count],[start], [stop]; | Valid aid code: ALL, SxAy <br> This command returns only reports (non-alarm) information from the stored event data. These have a ntfencde of NA. <br> The format for event log reports is: ```^^^"aid:ntfcncde,condtype,srveff,ocrdat,ocrtm: condscr" <cr lf> where: - ntfencde = Notification Code (NA) - condtype = Condition Type (event number) - srveff = service affecting flag (SA, NSA) - ocrdat = occurrence date - ocrtm = occurrence time - condstr = condition description string - start = the start time - stop = the stop time``` |

Table B-5. TL1 Retrieve Commands (Continued)

| Command | Description |
| :---: | :---: |
| RTRV-GPS-POS:[tid]:[aid]: ctag; | Valid aid code: S1A3 or S1A5 (must be a GPS module) <br> This command returns the settings position mask for the GPS module designated by the aid. <br> The format for each response message line is: <br> ^^^"aid:lat,lon, hgt, pdop, mode, avg, posel, timel" <br> <cr lf> <br> where: <br> - lat = current latitude of the receiver in the format (DD)-MMSS:SS <br> - Ion = current longitude of the receiver in the format (DD)-MMSS.SS <br> - hgt = current height of the receiver in meters <br> - pdop = current Position Dilution of Precision or pdop mask [1 through 10]. Pdop is a measurement that indicates the geometry of the GPS satellites that the SSU-2000 unit is tracking. Lower values indicate better geometry. <br> - mode = GPS positioning mode is user-specified or calculated: [User\|Calc]. If the positioning mode is set to User, the configuration setting is sent to the GPS engine and the mode is set to a fixed position. When the positioning mode is set to Calc, the elevation mask setting for positioning is sent to the engine, the engine is set to positioning mode, and 10 positions are averaged and compared to the configuration setting. If there is a greater than 300 meter error, the unit recalculates the position based on the averaging count. If there is not such an error, the unit uses the stored position. The SSU-2000 generates an event when the GPS module calculates a new position, and stores the new position in NVRAM as the current position and changes the engine mode to fixed position. <br> - avg = current GPS position averaging count. Setting the averaging count generates an event and starts a new position fix automatically. <br> - posel $=$ minimum satellite elevation to use for positioning <br> - timel = the minimum satellite elevation to use for timing |
| RTRV-HDR:[tid]::ctag; | Valid aid code: none. <br> This command is used to verify system connectivity. It may also be used to retrieve the unit name (sid) and date and time. The only action taken by the SSU-2000 is to respond with the complied message. |

Table B-5. TL1 Retrieve Commands (Continued)

| Command | Description |
| :---: | :---: |
| RTRV-INPUT-REF:[tid]::ctag; | Valid aid code: None <br> This command returns the current input reference, reference switch mode, and reference selection mode. <br> The format of the response message is: <br> "port,swtmode,selmode<cr lf> <br> where: <br> - $\quad$ swtmode $=$ auto return (revertive) selection, auto switch (but not revertive), or no auto switching [AR\|AS|OFF] <br> - selmode = reference selection: [PRI\|PQL] for priority quality level or status message selection of inputs. <br> If the input port is not a valid reference the DENY response is returned. |
| RTRV-INV:[tid]::ctag; | See RTRV-INVENTORY command. |
| RTRV- <br> INVENTORY:[tid]::ctag; | Valid aid code: None <br> This command returns the inventory management information for the addressed module(s). The response will be the complied message followed by the response message(s). A summary for each module and shelf are returned in the following format: <br> ^^^"aid:desc,hw_part,hw_rev,hw_serial,sw_part,sw_rev" <cr If> <br> Where desc is the text name of the module, hw_part is the Datum hardware part number, hw_rev is the hardware revision level, hw_serial is the hardware serial number, sw_part field reports the software part number (i.e. 141xxxxx-xxx-x), and the sw_rev field reports the software revision level. <br> The aid reported is the shelf address. The desc and hw_part are per the following table: |
| RTRV-NAME:[tid]:[aid]:ctag; | Valid AID codes: S1A2 or any I/O module or port. <br> This command returns the name assigned to Input or Output ports. One name of as many as 20 characters is returned for each port designated by the aid. The format for each response message line is: <br> "aid:"name" " <cr lf> <br> When the aid is S1A2, the name is that of the unit. <br> When the aid is an I/O module or port, the name is the assigned port name. |

Table B-5. TL1 Retrieve Commands (Continued)

| Command | Description |
| :---: | :---: |
| RTRV-NETYPE:[tid]::ctag; | Valid aid code: none. <br> This command serves the same purposes as RTRV-HDR with an element type message added. The response message for retrieve network element type is: <br> ^^^"SSU2000" <cr If> |
| RTRV-PING:: :ctag::ip; | Valid aid code: none. <br> This command allows for a remote host to be pinged via TCP/IP. The ip parameter shall be given in the \#\#\#.\#\#\#.\#\#\#.\#\#\# format, where \#\#\# is a number between 0 and 255 . The response message for retrieve ping is COMPLD if the ping was successful or DENY (SDNR) if unsuccessful. |
| RTRV-PRMTR-AIS:tid:[aid]: <br> ctag; <br> RTRV-PRMTR-BPV:tid:[aid]: <br> ctag; <br> RTRV-PRMTR-CRC:tid:[aid]: <br> ctag; <br> RTRV-PRMTR-LOS:tid:[aid]: <br> ctag; <br> RTRV-PRMTR-OOF:tid:[aid]: <br> ctag; | Valid AID codes: SxAy[-z] <br> This command returns the erred and cleared second thresholds for the signal faults. <br> The format for each response message line is: ^^^"aid:prmtr, errent,clent"<cr lf> where: <br> - prmtr = signal fault LOS, AIS, OOF, BPV, or CRC; <br> - errcnt = setting for the error threshold; <br> - clent = setting for the clear threshold. |
| RTRV-PRMTR-ALARM:[tid]: [aid]:ctag; | Valid AID codes: SxAy[-z] <br> This command returns the alarm settings for the specified module, or ALL alarms if no aid is specified. <br> The format for each response message line is: <br> ^^^"aid:almnum, level, startdelay, cleardelay"<cr lf> where: <br> - aid = module or input port <br> - almnum = alarm number <br> - level = Ignore, Report, Minor, Major, or Critical: <br> [IGN\|RPT|MIN|MAJ|CRT] <br> - startdelay = delay time or errored seconds count for start of the alarm <br> - cleardelay = cleared seconds count for clearing of the alarm. Delay numbers are reported only if they are settable for the alarm; otherwise they are reported as IMMED (immediate). |

## Table B-5. TL1 Retrieve Commands (Continued)

| Command | Description |
| :---: | :---: |
| RTRV-PRMTR-CCOUT:[tid]: [aid]:ctag; | Valid aid code: ALL, SxAy[-z] <br> This command returns the settings for the composite clock port designated by the aid. If a port is specified in the request, the format for each response message line is: <br> ^^^"aid:mode,level,bypass,pstate,duty,pcomp"<cr If> where: <br> - aid = port access identifier <br> - mode = CC (composite clock) <br> - level = minimum clock level to enable outputs on the module [WARM \| ACQ | LOCK] <br> - bypass = allows Clock C selection: [ON \| OFF] <br> - pstate = port state [ON \| OFF] <br> - duty = duty cycle of the modules outputs $[1 \mid 0]$ where $1=5 / 8$ and $\mathbf{0}=50 / 50$ <br> - pcomp = phase compensation [1 through 7] <br> When no port is specified by the aid, then the response is four lines as follows: <br> ^^^"aid: mode,level,bypass"<cr lf> <br> ^^^"aid:pstate1,pstate2,pstate3,...pstate20"<cr 1f> <br> ^^^"aid:duty1,duty2,duty3,...duty20"<cr lf> <br> ヘ^^"aid:pcomp1,pcomp2,pcomp3,..., pcomp20"<cr lf> <br> Line1 contains: <br> - aid = module access identifier <br> - mode = CC <br> - level = minimum clock level to enable outputs on the module [WARM \| ACQ | LOCK] <br> - bypass = allow Clock C selection: [ON \| OFF] <br> Line 2 contains: <br> - aid = module access identifier <br> - pstate\# port state [1\| 0] (1 = ON, $0=0 \mathrm{OFF}$ ), where \# = port number 1 through 20 <br> Line 3 contains: <br> - aid = module access identifier <br> - duty\# = duty cycle of the module outputs [1\|0], where: <br> - $1=5 / 8$ <br> - $0=50 / 50$ <br> - \# = port number 1 through 20 <br> Line 4 contains: <br> - aid = module access identifier <br> - pcomp\# = phase compensation 1 through 7 <br> - \# = port number 1 through 20 |

Table B-5. TL1 Retrieve Commands (Continued)

| Command | Description |
| :---: | :---: |
| RTRV-PRMTR-CDMA:[tid]: [aid]:ctag; | Valid aid code: S1A3 or S1A5 (must be a CDMA module) This command returns the settings for the CDMA module designated by the aid. The format for each response message line is: <br> ^^^"aid:pri,pql,sigma" <cr lf> <br> where: <br> - pri $=$ priority setting for the input [0 through $\mathbf{1 0}$, with $\mathbf{0}=\mathbf{M O N}]$, <br> - pqI = priority quality level $[2,3,4,5,8]$ <br> - sigma $=$ limit of the noise measurement [ $\mathbf{1 0}$ to $\mathbf{1 0 0 0} \mu \mathrm{s}$ ]. |
| RTRV-PRMTR-CDMA-FREQ: [tid]:[aid]:ctag; | Valid aid code: S1A3 or S1A5 (only CDMA modules) <br> This command returns as many as 32 CDMA pilot frequency settings (in MHz) used to select the frequency being tracked by the CDMA module. The output is returned in the following format: <br> ^^^"aid:freqval"<cr lf> <br> ヘ^^"aid:freqval"<cr lf> <br> ヘ^^"aid:freqval"<cr lf> <br> where: <br> - freqval = a floating-point value representing the frequency in MHz . Only the set frequencies are displayed, and a maximum of 32 frequencies can be set. |
| RTRV-PRMTR-CLK:[tid]:[aid]: ctag; | Valid aid code: ALL or S1A1 or S1A12 <br> This command returns the settings for the clock designated by the aid, or both clocks for ALL. <br> The format for each response message line is: ^^^"aid:warmup, mintau, maxtau, clkar" <cr lf> where: <br> - warmup = warmup delay time <br> - mintau = starting time constant <br> - $\quad$ maxtau $=$ final time constant value in seconds for the clock <br> - clkar = current setting for the clock Auto-Return mode [OFF \| ON]. |

## Table B-5. TL1 Retrieve Commands (Continued)

| Command | Description |
| :---: | :---: |
| RTRV-PRMTR-CLKOUT:[tid]: [aid]:ctag; | Valid aid code: ALL, SxAy[-z] <br> This command returns the output port setting when a port aid is specified. <br> The format for the response message is: <br> ^^^"aid:mode, level,bypass,fltmode,pstate" <cr lf> where: <br> - aid = module access identifier <br> - mode = CLK <br> - level = [WARM\|ACQ|LOCK] for the clock level where outputs are turned on, <br> - bypass = allow Clock C selection: [ON\|OFF] <br> - fltmode = determines if outputs are set to fault [OFF \|ON | AUTO] when signal levels drop below the threshold output level <br> - pstate = port state [1\|0] (where $\mathbf{1}=\mathrm{ON}$ and $\mathbf{0}=\mathrm{OFF}$ ). <br> When no port is specified by the aid, then the response is two lines as follows: <br> ^^^"aid:mode, level,bypass,fltmode" <cr lf> <br> ^^^"aid:pstate1,pstate2,pstate3,..., pstate20" <cr lf> where: <br> Line 1 contains: <br> - mode = CLK <br> - level = [WARM\|ACQ|LOCK] for the clock level where outputs are turned on, <br> - bypass = [ON\|OFF] for allowing Clock C selection <br> - fltmode = determines if outputs are set to fault [OFF \| ON | AUTO] when signal levels drop below the threshold output level <br> Succeeding lines contain: <br> - aid = access identifier of module <br> - pstate\# = port state [1\|0], where: \# = port number 1 through 20 , and a result of $\mathbf{1}=\mathbf{O N}$ and $\mathbf{0}=\mathbf{O F F}$. |

Table B-5. TL1 Retrieve Commands (Continued)

| Command | Description |
| :---: | :---: |
| RTRV-PRMTR-COMM:[tid]: [aid]:ctag; | Valid aid code: ALL, COML, COMA, COMB, TELNET, or TL1 <br> This command returns the current internet protocol settings for the unit. <br> When a serial port is specified, the format of the response message is: <br> ^^^"aid:baud,echo,eol,mode,tout"<cr lf> <br> where: <br> - aid = communication port [COML \| COMA | COMB] <br> - baud = communications baud rate [19200 \| 9600 | 4800 | 2400 | 1200]. <br> - echo = whether the port operates in full-duplex or half-duplex [ON \| OFF] <br> - eol = end-of-line character to be used when the unit transmits ASCII data [CR \| LF | CRLF] <br> - mode $=$ mode of communication [ASCII \| TL1] <br> - tout = inactivity timeout period before the session is logged out [value \| NEVER]. <br> When a Telnet port is specified, some data fields are null, and the format of the response message is: <br> ^^^"aid:, , , ,tout"<cr lf> |
| RTRV-PRMTR-ELTIME:[tid]: [aid]:ctag; | Valid aid code: SxAy <br> This command returns the time for alarm elevation, from 60 seconds to 500,000 seconds. A setting of 0 (zero) means no elevation for the alarm. When an alarm has been at MINOR or MAJOR level continuously for elevtime seconds, then it is elevated to the next level. Delay may be set for each module or ALL modules, and applies to all alarms created by the module. <br> ^^^"aid:elevtime" <cr lf> <br> where: <br> - Elevtime = alarm elevation time for the specified module. |
| RTRV-PRMTR- <br> FREQ:[tid]:[aid]:ctag; | Valid aid code: ALL, S1Ay-z <br> This command returns the MTIE threshold settings for the input port designated by the aid. <br> The format for the response message is: <br> ^^^"aid:freq,fae,fac,fbe,fbc" <cr lf> <br> where: <br> - aid = access identifier of the port <br> - fae = frequency error threshold for A <br> - fac = clear threshold for $A$ <br> - $\quad$ fbe = error threshold for $B$ <br> - $\mathbf{f b c}=$ clear threshold for $B$ |

## Table B－5．TL1 Retrieve Commands（Continued）

| Command | Description |
| :---: | :---: |
| RTRV－PRMTR－ GPS：［tid］：［aid］：ctag； | Valid aid code：S1A3 or S1A5（must be a GPS module） <br> This command returns the settings for the GPS module designated by the aid． <br> The format for each response message line is： <br> ヘ＾＾＂aid：pri，pql，sigma＂＜cr lf＞ <br> where： <br> －pri $=$ priority setting of［0 through 10 ，with $0=M O N$ ］ <br> －pql＝priority quality level［1 through 16］ <br> －sigma＝limit of the noise measurement［10 to $\mathbf{1 0 0 0} \mu \mathrm{s}$ ］． |
| RTRV－PRMTR－ INPUT：［tid］：［aid］：ctag； | Valid aid code：ALL，S1Ay［－z］ <br> This command returns the settings for the input designated by the aid．This reports the input module settings． <br> The format for the response message is： <br> ヘ＾＾＂aid：pstate，pri，pql，mode，ssm，zs，crc，gain，csf <br> lt，bit＂＜cr lf＞ <br> where： <br> －aid＝port aid <br> －pstate＝port enabled state［ON｜OFF］ <br> －pri＝priority 1 （highest）through 10 （lowest）or MON for monitor <br> －pqI＝provisioned priority quality level of 1 through 16 <br> －mode＝framing type or clock frequency in MHz ： <br> ［ESF｜D4｜CCS｜CAS｜1｜1．544｜2．048｜5｜10］ <br> －ssm，zs，cre，and gain＝［ON｜OFF］ <br> －csflt＝［HI｜LO｜OFF｜NA］ <br> －bit＝bit number $\mathbf{4}$ through 8 of the Time Slot 0 word used for the E1 sync status message． |
| RTRV－PRMTR－IP：［tid］：：ctag； | Valid aid code：None <br> This command returns the current Internet protocol settings for the unit． <br> The format of the response message is： <br> ヘ＾＾＂aaa．aaa．aaa．aaa，mmm．mmm．mmm．mmm， <br> ggg．ggg．ggg．ggg＂＜cr lf＞ <br> where： <br> －aaa．aaa．aaa．aaa＝IP address of unit <br> －mmm．mmm．mmm．mmm＝IP mask of unit <br> －ggg．ggg．ggg．ggg $=I P$ gateway of unit |

Table B-5. TL1 Retrieve Commands (Continued)

| Command | Description |
| :---: | :---: |
| RTRV-PRMTRKEEPALIVE:[tid]::ctag; | Valid aid code: None <br> The Keep-alive function causes autonomous messages to be transmitted at a user selectable interval. This command returns the current TL1 and SNMP keep alive settings for the unit. The format of the response message is: <br> ヘ^^"tll_time,snmp_time "<cr lf> <br> where tl1_time is the TL1 session timer in minutes, snmp_time is the SNMP session timer in minutes. <br> Times set to zero indicate keep alive is disabled. |
| RTRV-PRMTR-MTIE:[tid]:[aid] :ctag; | Valid aid code: ALL, S1Ay-z <br> This command returns the MTIE threshold settings for the input port designated by the aid. The format for the response message is: $\begin{aligned} & \text { ^^^"aid:MTIE, EL1,t10,t100,t1000,t10000,t100000" <cr lf> } \\ & \text { ^^^"aid:MTIE, EL2,t10,t100,t1000,t10000,t100000" <cr lf> } \\ & \text { ^^^"aid:MTIE, CL1,t10,t100,t1000,t10000,t100000" <cr lf> } \\ & \text { ^^^"aid:MTIE, CL2,t10,t100,t1000,t10000,t100000" <cr lf> } \end{aligned}$ <br> The first line contains the aid of the port and the error threshold settings for EL1 <br> The second line contains the aid of the port and the error threshold settings for EL2. <br> The third line contains the aid of the port and the clear threshold settings for CL1 <br> The fourth line contains the aid of the port and the clear threshold settings for CL2. <br> There are always four lines returned for each input port, one for each limit. |
| RTRV-PRMTRNTP:[tid]::ctag; | Valid aid code: None <br> This command returns the current network timing protocol settings for the unit. The format of the response message is: $\begin{aligned} & \text { ^^^ip1,mode, interval"<CR LF> } \\ & \text { ^^^ip2,mode, interval"<CR LF> } \\ & \text { ^^^ip3,mode, interval"<CR LF> } \end{aligned}$ <br> Where ip is the server ip used by the client or broadcast client or broadcast server. Mode is the operating mode for the given ip, the mode can be CLIENT meaning that the SSU will automatically request the time from the server, BCLIENT which means that the server designated by the ip is a broadcast server, and BROADCAST which means the SSU is set up as a broadcast server. The interval is used when the SSU is setup as a broadcast server, the broadcast interval is defined to be either $32 / 64 / 128 / 512 / 1024$ seconds. The SSU is automatically configured as an NTP server with the address specified in the SET-PRMTR-IP command. There can be up to three NTP ip's listed. |

## Table B-5. TL1 Retrieve Commands (Continued)

| Command | Description |
| :---: | :---: |
| RTRV-PRMTR-OUTPUT:[tid]: [aid]:ctag; | Valid aid code: ALL, SxA[y[-z]] <br> Returns the output port setting when a port aid is specified. <br> The format for the response message is: <br> ^^^"aid: mode, level,bypass,zs,crc,bit,pstate,len" <cr lf> <br> The first line contains these fields: <br> - aid of the port <br> - mode = output signal mode, [ESF\|D4|CCS|CAS] <br> - level = [WARM\|ACQ|LOCK] for the clock level where outputs are turned on <br> - bypass = allow Clock C selection: [ON\|OFF] <br> - zs = zero suppression <br> - cre = error checking crc are [ON\|OFF] <br> - bit = SSM bit [4 through 8] for E1 sync status messages <br> - pstate = port enabled state [ON \|OFF] <br> - len = line length setting of [133\|266|399|533|655] for DS1 outputs <br> When no port is specified by the aid, the response is: <br> ^^^"aid:mode,level,bypass, zs,crc,bit" <cr lf> <br> ^^^"aid:pstate1,pstate2, pstate3,...pstate20" <cr lf> <br> ^^^"aid:len1,len2,len3,...,len20" <cr lf> <br> Line 1 contains: <br> - aid = module access identifier <br> - mode = outputs signal mode: [ESF\|D4|CCS|CAS] <br> - level = clock level: [WARM\|ACQ|LOCK] when outputs are turned on <br> - bypass = allow Clock C selection: [ON\|OFF] <br> - zs = zero suppression: [ON\|OFF] <br> - $\quad$ crc = error checking: [ON\|OFF] <br> - bit = SSM bit [4 through 8] for E1 sync status messages. <br> Line 2 contains: <br> - aid = port access identifier <br> - pstate\# = port enabled state [1\|0] ( $\mathbf{1}=\mathbf{O N}$ and $\mathbf{0}=\mathbf{O F F}$ ) for all 20 output ports. <br> The third line contains: <br> - aid = access identifier of the port <br> - len\# = line length setting of [133\|266|399|533|655] for all 20 DS1 output ports. |

Table B-5. TL1 Retrieve Commands (Continued)

| Command | Description |
| :---: | :---: |
| RTRV-PRMTRPBO:[tid]::ctag; | Valid aid code: none <br> This command returns the Phase Build-Out (PBO) settings for the system. All input modules will use this setting. The format for each response message line is: <br> ^^^"aid:pbo_mode" <cr lf> <br> where this aid is specified as ALL (i.e. all DS1/E1 input modules). The pbo_mode is [DIS\| EVT| REP| NONE]. <br> - DIS indicates the PBO function has been disabled. <br> - EVT indicates the PBO function is enabled. PBO events are displayed and stored in the COMM module event buffer. <br> - REP indicates the PBO function is enabled. <br> - PBO events are displayed, but the event is not stored in the COMM module event buffer. <br> - NONE indicates the PBO function is enabled. The PBO event is neither displayed nor stored in the COMM module event buffer. |
| RTRV-PRMTR-SNMPMODE:[tid]::ctag; | Valid aid code: none <br> This command returns the current SNMP mode. The format for each response message line is: <br> ^^^"mode,trap_filter" <cr lf> <br> Values for mode are as follows: <br> - ENA Enables SNMP operation in the system <br> - DIS Disables SNMP operation in the system <br> Values for trap_filter are as follows: <br> - ALM Only alarms cause Traps to be transmitted <br> - ALL All events and alarms cause the transmission of Traps |
| RTRV-PRMTR-SNMPUSER:[tid]::ctag; | Valid aid code: none <br> This command returns the current SNMP user list. The format for each response message line is: <br> ヘ^^"read_community,level" <cr lf> <br> Where read_community is the assigned Read Community String used by SNMP and level is the access level assigned to that user. No Write Community String will be displayed. This is only accessible by Level 4 user. |
| RTRV-PRMTR-SNMPMANAGER:[tid]::ctag; | Valid aid code: none <br> This command returns the SNMP Manager list. The format for each response message line is: <br> "ip_address" <cr lf> <br> Where ip_address is the assigned SNMP Manager IP address. |

## Table B-5. TL1 Retrieve Commands (Continued)

| Command | Description |
| :---: | :---: |
| RTRV-REF:[tid]::ctag; | Valid aid code: None <br> This command returns the current input reference port and output clock source. <br> The format of the response message is: <br> ^^^"port,clksrc" <cr lf> <br> where: <br> - port = input reference port designated by aid <br> - clksrc = selected clock source [CLK-A\|CLK-B|NA] for outputs |
| RTRV-STATUS-ALARM:[tid]: [aid]:ctag; | Valid aid code: SxAy <br> This command returns the current status of all alarms. The format for the response message is: <br> ^^^"aid:almnum,stat" <cr lf> where: <br> - aid = module or input port <br> - almnum = alarm number for that aid <br> - status = current state of each alarm condition [OK\|BAD] |
| RTRV-STATUSCLK:[tid]:[aid]:ctag; | Valid aid code: ALL or S1A1 or S1A12 <br> This command returns the clock status, loop mode, current time constant value and current priority quality level (pql). Two message lines are returned if aid = ALL, one for each clock module (if both installed). <br> The format for each response line is: <br> ヘ^^"aid:mstat,mode,tau,pql" <cr lf> where: <br> - aid = which clock module status is being displayed <br> - mstat = module status \{OK\|SEL|DIS|FLT $\}$ <br> - clock mode = [WARM\|ACQ|LOCK|HOLD] <br> - tau = current time constant in seconds for the clock control loop <br> - pql = Stratum Level of the clock |

Table B-5. TL1 Retrieve Commands (Continued)

| Command | Description |
| :---: | :---: |
| RTRV-STATUS-INPUT:[tid]: [aid]:ctag; | Valid aid code: ALL, S1Ay[-z] <br> This command returns the condition (current operating mode and readings) of the input ports. <br> The format of each response line is: <br> ^^^"aid:mstat,pstate, (pha), (phb), pql" <cr lf> where: <br> - mstat = module status \{OK \| DIS | FLT $\}$ <br> - pstate = the port state $\{\mathbf{O K} \mid$ DIS $\mid$ FLT $\}$ <br> - pha and phb = current 1 second phase values in nanoseconds, or NA if not available <br> - pql = current pql level (read or provisioned) being reported by the port, if available. <br> One line is returned for each port designated by the aid. |
| RTRV-STATUSNTP:[tid]::ctag; | Valid aid code: None <br> This command returns the current network timing protocol status for the unit. The format of the response message is: <br> ^^^ip1,offset, delay, dispersion"<CR LF> <br> ^^^ip2,offset, delay, dispersion"<CR LF> <br> ^^^ip3,offset, delay, dispersion"<CR LF> <br> Where ip is the server IP address used by the client or broadcast client or broadcast server. Offset is the number of seconds (partial seconds) that the local time was adjusted by. Delay is the calculated delay in the communication path. Dispersion is a value that indicates the accuracy of the offset/delay settings. There can up to three NPT IP addresses listed. |

## Table B－5．TL1 Retrieve Commands（Continued）

| Command | Description |
| :---: | :---: |
| RTRV－STATUS－OUTPUT：［tid］： ［aid］：ctag； | Valid aid code：ALL，SxAy［－z］ <br> This command returns the condition（current operating mode and status）of an output module or port． <br> The format of each port response line is： <br> ヘ＾＾＂aid：mstat，red，clksrc，pql，pstate＂＜cr lf＞ where： <br> The first line contains the port aid． <br> －mstat＝module status［OK｜DIS｜FLT］：where OK indicates normal operation，and DIS or FLT indicate all outputs are turned off <br> －red＝redundant［NA｜SxAy］：where NA＝non－redundant， and the aid＝the redundant module identifier <br> －clksrc＝clock which is generating the output：［CLK－A｜CLK－ B｜CLK－C｜CLK－D］ <br> －pqI＝possible Priority Quality Level（SSM）being generated <br> －pstate $=$ port status $[\mathbf{1}\|\mathbf{0}\| \mathrm{F}]$ ，where $1=$ enabled， $0=$ disabled， and $\mathrm{F}=$ faulted <br> Multiple message lines are returned if aid specifies one or more output modules as follows： <br> ヘヘ＾＂aid：mstat，red，clksrc，pql＂＜cr lf＞ <br> ヘ＾＾＂aid：p1，p2，p3，．．．p20＂＜cr lf＞ <br> where： <br> The first line contains the module aid． <br> － mstat $=$ module status is［OK｜DIS｜FLT］，where $\mathbf{O K}=$ normal operation，and DIS or FLT＝all outputs are turned off <br> －red $=[\mathbf{N A} \mid \mathbf{S x A y}]$ ，where： $\mathbf{N A}=$ non－redundant，and $\mathbf{S x A y}=$ redundant module aid <br> －clksrc＝clock generating the output：［CLK－A｜CLK－B｜CLK－C ｜CLK－D］ <br> －pqI＝Priority Quality Level（SSM）being generated <br> The second line contains： <br> －aid＝module identifier <br> －pstate＝port status：［1｜0｜F］，where 1 ＝enabled， $2=$ disabled， F＝faulted for all 20 outputs |
| RTRV－USER：［tid］：：ctag； | Valid aid code：None <br> This command returns the current user list．The format of the response message is： <br> ヘ＾＾＂username，level＂＜cr lf＞ <br> where： <br> －username＝assigned user <br> －level＝access level assigned to that user． <br> No password information is displayed．This command is only accessible by Level 4 users． |

## B.2.4 TL1 Set Commands

This section contains a table which provides an alphabetical listing of TL1 set commands, a description of the command which provides the valid aid codes to use in the command, and an example and description of the components of message lines.

The TL1 set commands allow operators to set data and time or parameters for the SSU-2000 unit. The unit responds to set commands with a complied message or a deny message that indicates the cause for the failure. There is no response message line for the set commands. Table B-6 provides a listing of the TL1 set commands.

Table B-6. TL1 Set Commands

| Command | Description |
| :--- | :--- |
| SET-CLK:[tid]:[aid]:ctag; | Valid aid code: None or Any clock <br> This command changes the current output clock to the one <br> designated in the aid. If the aid is invalid or the clock is not <br> available for use or clock A/R is on, the DENY response is <br> returned. <br> Empty fields leave parameters unchanged. |
| SET-CLK-AR:[tid]::ctag::ar; | Valid aid code: none <br> The command sets the clock mode of returning or not returning <br> after faults are cleared. The ar parameter changes the current <br> clock selection mode to [ON \| OFF] for revertive or non-revertive <br> operation. <br> Empty fields leave parameters unchanged. |
| SET-CLK-MODE:[tid]:[aid]: <br> ctag::mode; | Valid aid code: ALL, Clock <br> This command is used to change the clock loop mode to ACQ \| <br> LOCK \| HOLD. <br> If no aid is specified then both clocks are changed. |
| SET-DAT:[tid]::ctag::date^time; | Valid aid code: none. <br> This command always has a null aid and the <other> field <br> contains the date and time. |
| The format of the date and time is YY-MM-DD^HH:MM:SS |  |
| where the $\wedge$ may be a space character or a comma separating |  |
| the date and time, and the colons in the time may be dashes. |  |
| The SSU-2000 system clock is set to the received date and time |  |
| and a complied message is returned, with the new date/time in |  |
| the header. |  |$|$

Table B-6. TL1 Set Commands (Continued)

| Command | Description |
| :---: | :---: |
| SET-GPS-POS:[tid]:[aid]:ctag:: [(lat)],[(lon)],[(hgt)],[pdop],[avg], [posel],[timel]; | Valid aid code: S1A3 or S1A5 (must be a GPS module) <br> This command sets the position mask for the GPS module designated by the aid. <br> The settings for this command include: <br> lat $=$ set the latitude [+/- 90deg], formatted (DD)-MM-SS.SS where: <br> - + = North <br> - - = South <br> Ion = set longitude [+/-180 deg] formatted as (DD)-MM-SS.SS where: <br> - + = East <br> - - = West <br> - hgt $=$ set height [ $+/-10000.0$ meters $]$ <br> - pdop = set the pdop [1 to 10] <br> - $\mathbf{a v g}=$ set position averaging value [10 to 3600] <br> - posel = set the minimum satellite elevation to use for positioning [ 0 to 50 deg ] <br> - timel = set the minimum satellite elevation to use for timing [ 0 to 50 deg ]. |
| SET-INPUT-REF:[tid]::ctag::port [,swtmode][,selmode]; | Valid aid code: None <br> This command sets the current input reference to the designated input port. <br> - $\mathbf{s w t m o d e}=[\mathbf{A R}\|\mathbf{A S}\|$ OFF $]$ for auto return (revertive) selection, auto switch (but not revertive), or no auto switching <br> - selmode = reference selection: [PRI\|PQL] for priority or status message selection of inputs <br> If the input port is not a valid reference the DENY response is returned. |
| SET-MTIE- <br> MASK:[tid]:[aid]:ctag::mask; | Valid aid code: ALL, SxAy-[z]. <br> This command will set the MTIE mask for the given input to predefined settings, such that mask can be set to PRS \| DS1 | G811 | G823. The MTIE mask settings include both Limit 1 and Limit 2 and set and clear thresholds. For user defined thresholds use the SET-PRMTR-MTIE command. |
| SET-NAME:[tid]:[aid]:ctag:: name; | Valid aid code: none, S1A2, or I/O port aid. <br> This command with no aid or S1A2 (Communications Module) assigns a new name to the unit. The tid (if used) must match the original name, which is returned in the response sid. The new unit name must be used as the tid (and sid) for all commands following. <br> For an aid designating an Input or Output port the name is assigned to the port. The name for unit or port may be null or as many as 20 characters beginning with a letter. |

## Table B-6. TL1 Set Commands (Continued)

| Command | Description |
| :---: | :---: |
| SET-PHASE-ZERO:[tid]:[aid]: ctag[::clksrc]; | Valid aid code: none or Input port aid. <br> This command sets the input phase to zero for the designated port(s) or all input ports with an aid of null or ALL. If clksrc is specified [CLK-A\|CLK-B] only the one phase value is set to zero; otherwise both values are set to zero. |
| SET-PRMTR-ALARM:[tid]:aid: ctag::almnum,level [,errent],[cIrcnt]; | Valid aid code: ALL, SxAy <br> This command assigns the alarm number specified. <br> - almnum = alarm level [IGN\|RPT|MIN|MAJ|CRT] <br> - start delay time or erred seconds count <br> - errent and clear delay time for the indicated alarm number <br> - clrent on the modules specified by the aid. |
| SET-PRMTR-AIS:tid:[aid]:ctag ::[errent],[clrcnt]; <br> SET-PRMTR-BPV:tid:[aid]:ctag ::[errent],[clrcnt]; <br> SET-PRMTR-CRC:tid:[aid]:ctag ::[errent],[clrent]; <br> SET-PRMTR-LOS:tid:[aid]:ctag ::[errent],[clrent]; <br> SET-PRMTR-OOF:tid:[aid]:ctag ::[errent],[clrent]; | Valid aid code: ALL, SxAy-[z] <br> This command sets the input error and clear parameters of [AIS\|BPV|CRC|LOS|OOF] for the designated input. <br> - errent and clrent = number of seconds to delay [0\|...|100] before reporting the condition for LOS and AIS input errors <br> - errent and clrent = number of seconds to delay [0\|...|100000] before reporting the condition for OOF, BPV, and CRC input errors <br> With the aid of ALL the specified parameters are set for all inputs. |
| SET-PRMTR-CCOUT:[tid]:[aid] :ctag::[pstate],[mode],[level], [bypass],[duty],[pcomp]; | Valid aid code: ALL, SxA[y[-z]] <br> pstate sets the output port [ON\|OFF] <br> - mode = ignored <br> - level = the condition where outputs are turned on [WARM \|ACQ | LOCK] <br> - bypass = allow Clock C selection: [ON\|OFF] <br> - duty= set duty cycle to use $5 / 8$ or $50 / 50$ [1\|0] <br> - pcomp = set phase compensation delay to [0 through 8], where $\mathbf{0}=$ No compensation and $\mathbf{8}=4000 \mathrm{ft}$. The resolution of pcomp values is 500 ft . Setting the status for a module (no port $-z$ ) sets all ports [ON\|OFF]. <br> Empty fields leave parameters unchanged. |
| SET-PRMTR-CDMA:[tid]:[aid]: ctag::[pri],[pql],[sigma],[freq]; | Valid aid code: S1A3 or S1A5 (must be a CDMA module) <br> - pri = priority setting for the input [0 through $\mathbf{1 0}$, with $\mathbf{0}=\mathbf{M O N}]$ <br> - pqI = priority quality level [1 through 16] <br> - sigma = limit of the noise measurement [10 to $\mathbf{1 0 0 0} \mu \mathrm{s}$ ] <br> - $\quad$ freq = selected base station frequency [1 through 32] <br> Empty fields leave parameters unchanged. |

Table B-6. TL1 Set Commands (Continued)

| Command | Description |
| :---: | :---: |
| SET-PRMTR-CDMA-FREQ:[tid]: <br> [aid]:ctag::mode,freqval; | Valid aid code: S1A3 or S1A5 (must be a CDMA module) <br> - mode = allow adding or deleting a pilot frequency value [ADD \| DEL] <br> - freqval = pilot frequency in MHz (decimal based, for example $3.4328=3.4328 \mathrm{MHz}$ ) |
| SET-PRMTR-CLK:[tid]:[aid]: ctag::[warmup],[mintau], [maxtau]; | Valid aid code: S1A1, S1A12, CLK-A, CLK-B <br> This command sets the designated clock warmup time. <br> - warmup = warmup time constant <br> Set to 1200 seconds <br> - mintau = starting time constant <br> Stratum 2E and $3 E=300$ seconds <br> - maxtau = final time constant value <br> Stratum 2E $=10000$ seconds <br> Stratum 2E $=500$ seconds <br> The aid may be specified to indicate which clock, or left null to set both clocks identically. <br> Empty fields leave parameters unchanged. |
| SET-PRMTR-CLKOUT:[tid]:[aid]: ctag::[pstate],[mode],[level], [bypass],[fltmode]; | Valid aid code: ALL, SxA[y[-z]] <br> - pstate = sets output port state: [ON\|OFF] <br> - mode = ignored <br> - level = set the clock mode: [WARM\|ACQ|LOCK] <br> - bypass = allow Clock C selection [ON\|OFF] when outputs are turned on <br> - fltmode = allow output level to be monitored for fault thresholds: [OFF \| ON | AUTO]. Setting the status for a module (no port $-z$ ) sets all ports [ON\|OFF]. <br> Empty fields leave parameters unchanged. |
| SET-PRMTR-COMM:[tid]:[aid]: ctag::[baud],[echo],[eol], [mode],[tout]; | Valid aid code: ALL, COML, COMA, COMB, TELNET, or TL1 where: <br> - aid = set the communication port [ALL \| COML | COMA | COMB] <br> - baud = set the communications baud rate [19200 \| 9600 | 4800 | 2400 | 1200] <br> - echo = set unit to use full or half duplex [ON \| OFF] <br> - eol = set end-of-line character(s) sent by the unit [CR \| LF | CRLF] <br> - mode $=$ set the mode of communication to [ASCII \| TL1] <br> - tout = set the inactivity timeout period [5 to $\mathbf{4 3 2 0 0}$ \| NEVER] |

Table B-6. TL1 Set Commands (Continued)

| Command | Description |
| :---: | :---: |
| SET-PRMTR-ELTIME:[tid]:[aid]: ctag::elevtime; | Valid aid code: SxAy <br> This command sets the time for alarm elevation, from 60 seconds to 500,000 seconds. A setting of 0 (zero) means no elevation for the alarm. When an alarm has been at MINOR or MAJOR level continuously for ELTIME seconds, then it is elevated to the next level. <br> This may be set for each module or ALL modules, and applies to all alarms created by the module. |
| SET-PRMTR-FREQ:[tid]:[aid]: ctag::[fae],[fac],[fbe],[fbc]; | Valid aid code: ALL, S1Ay[-z] <br> This command sets the input Frequency alarm thresholds. <br> - fae = error threshold for input versus A clock <br> - fac = clear threshold for input versus Clock A <br> - fbe = error threshold for input versus B clock <br> - $\mathbf{f b c}=$ clear threshold for input versus Clock B, for the designated input. <br> The maximum settings for these limits is 10000000 in units of $\mathrm{ps} / \mathrm{s}$. Empty fields are unchanged. |
| SET-PRMTR-GPS:[tid]:[aid]: ctag::pri],[pql],[sigma]; | Valid aid code: S1A3 or S1A5 (for a unit with GPS module) <br> - pri $=$ set the priority setting of [0 through $\mathbf{1 0}$, with $\mathbf{0}=\mathbf{M O N}]$ <br> - pqI = set the priority quality level [1 through 16] <br> - sigma = set the limit of the noise measurement [10 to $1000 \mu \mathrm{~s}$ ]. |

Table B-6. TL1 Set Commands (Continued)

| Command | Description |
| :---: | :---: |
| SET-PRMTR-INPUT: <br> [tid]:[aid]:ctag::[pstate],[pri], [pql],[mode],[ssm],[zs],[crc], [gain],[csflt],[bit]; | Valid aid code: ALL, S1Ay[-z] <br> This command sets: <br> - pstate = port state [ON\|OFF] (port enable/disable) <br> - pri = port priority [1\|2|...|0|MON] where MON is monitor only mode, and 1 through 10 are priorities from 1 (highest) to 10 (lowest) <br> - pqI = provisioned priority quality level of $[\mathbf{1 \|}\|\ldots\| 16\}$. <br> - $\quad$ mode $=[$ ESF\|D4|CCS|CAS|1|1.544|2.048|5|10] for framing mode or clock frequency. DENY with ICNV returned if mode setting does not match module type (DS1 or E1). <br> - $\mathbf{s s m}=$ reading or ignoring incoming sync status messages [ON\|OFF] <br> - zs = zero suppression <br> - crc = error checking <br> - gain $=$ input gain $=$ [ON\|OFF] <br> ssm, zs, crc, and gain are ignored for clock modes. <br> - Csflt = external cesium fault alarm input [HI\|LO|OFF] <br> - bit = bit number $4-8$ of the Time Slot 0 word used for the E1 sync status message. For DS1 input, the bit value is ignored. With an aid of ALL (or null) the specified parameters are set for all inputs. <br> Empty fields leave parameters unchanged. If mode is set to a framed type then frequency is set to correct frequency for type DS1 (1.544) or E1 (2.048) |
| SET-PRMTR-IP:[tid]::ctag:: [addr],[mask],[gate]; | Valid aid code: None where: <br> - addr = IP address of SSU-2000 unit <br> - mask = IP mask of SSU-2000 unit <br> - gate = IP gateway of SSU-2000 unit. <br> All IP numbers shall be in the \#\#\#.\#\#\#.\#\#\#.\#\#\# format. |
| SET-PRMTRKEEPALIVE:[tid]::ctag:: [tt1_time],[snmp_time]; | Valid aid code: None <br> This command will support a "keep alive" mode whereby based upon a user settable time an event will be generated by the SSU2000 to alert the upstream support system that the SSU2000 and associated communication path is functional. <br> Where t11_time is the TL1 session keep alive in minutes, snmp time is the SNMP session keep alive in minutes. The minimum settable time is one minute, and the maximum is 60 minutes. If zero minute is specified, the keep alive is disabled. |

Table B-6. TL1 Set Commands (Continued)

| Command | $\quad$ Description |
| :--- | :--- |
| SET-PRMTR-MTIE:[tid]:[aid]: <br> ctag::\{EL1\|EL2|CL1|CL2\},[t10], <br> [t100],[t1k],[t10k],[t100k]; | Valid aid code: ALL, S1Ay[-z] <br> This command sets the input MTIE alarm thresholds EL1or EL2 <br> and the clear thresholds CL1 or CL2 for the designated input. <br> Threshold settings t10 through t100k are the error limits in <br> nanoseconds for the measurement time period. <br> With the aid of ALL (or null) the specified parameters are set for <br> all inputs. |
| SET-PRMTR-NTP:[tid]::ctag:: <br> mode,ip,interval; | Valid aid code: none <br> This command sets the NTP client and NTP broadcast mode of <br> operation. <br> Mode can be set to client \| bclient | broadcast | del | clrall. |
| Client mode will request the time from the time server (as |  |
| defined by the ip, internet protocol address), this time will be |  |
| used to set the time in the SSU. |  |
| Bclient mode will accept time from a broadcast server that is |  |
| specified by the ip parameter. |  |

Table B-6. TL1 Set Commands (Continued)

| Command | Description |
| :---: | :---: |
| SET-PRMTR-PBO:[tid]::ctag:: pbo_mode; | Valid aid code: none <br> The pbo_mode is [DIS\| EVT| REP| NONE]. <br> DIS shall disable the phase buildout (PBO) function. <br> EVT shall enable the PBO function. The PBO event is displayed and stored in the COMM module event buffer. <br> REP shall enable the PBO function. The PBO event is displayed, but the event is not stored in the COMM module event buffer. NONE shall enable the PBO function. The PBO event is neither displayed nor stored in the COMM module event buffer. |
| SET-PRMTR-SETUP: <br> [tid]:[aid]:ctag::[factory \| user | save]; | Valid aid code: ALL, SxA[y[-z]] <br> This command sets or saves the configuration of the specified module. <br> Factory will restore the module configuration to factory defaults. Any time the configuration has changed from the factory configuration, these configurations become the current configurations. <br> Save will store the current configuration. If changes are then made to the current configuration and the user would like to return to the previously stored configuration. <br> The user parameter will reload the previously saved configuration. |
| SET- PRMTR -SNMPMODE:[tid]::ctag:: [mode],[trap_filter]; | Valid aid code: None <br> This command sets the SNMP mode and trap filter parameters. Values for mode are as follows: <br> - ENA Enables SNMP operation in the system <br> - DIS Disables SNMP operation in the system Values for trap_filter are as follows: <br> - ALM Only alarms cause Traps to be transmitted <br> - ALL All events and alarms cause the transmission of Traps Empty fields leave parameters unchanged. |
| SET-PRMTR-SNMP-USER: <br> [tid]::ctag::mode,[rd_community], [wr_community],[level]; | Valid aid code: none <br> This command allows changes to the SNMP security of the system. $\text { mode }=\{\text { ADD\| DEL\| MOD\| INIT }\}$ <br> where: <br> ADD requires a rd_community and wr_community. Level defaults to 1 if not entered. <br> DEL only requires a username to delete the user from the table. MOD requires a username, a new password, and new user level. <br> INIT requires no additional parms and clears all entries in the table. |

Table B-6. TL1 Set Commands (Continued)

| Command | Description |
| :---: | :---: |
| SET- PRMTR -SNMP- <br> MANAGER:[tid]::ctag::mode,[ip]; | Valid aid code: none <br> This command allows changes to the SNMP manager table entries. <br> mode $=\{$ ADD \| DEL | INIT $\}$ <br> where: <br> - ADD requires an IP address. <br> - DEL only requires an IP address to delete the entry from the table. <br> - INIT requires no additional parms and clears all entries in the table. |
| SET-USER:[tid]::ctag::mode, [username],[password], [userlevel]; | Valid aid code: none <br> This command allows changes to the security of the system. <br> mode $=\{$ ADD $\mid$ DEL $\mid$ INIT $\}$ <br> where: <br> - ADD requires a username and password. <br> - DEL only requires a user name to delete the user from the table. <br> - INIT requires no additional parameters and clears all entries in the table except for the default Guest and Admin entries. <br> - userlevel ( 1 through 4 ), defaults to 1 if not entered. |

## B.2.5 Other TL1 Commands

Table B-7 summarizes the TL1 commands for activating (enabling), disconnecting (disabling), removing or restarting modules, and for logging in or out of the SSU-2000 system.,

Table B-7. Other TL1 Commands

| Commands | Descriptions |
| :--- | :--- |
| ACT-MODULE:[tid]:aid:ctag; | Valid aid codes: ScAy <br> This command activates (enables) a module (not a <br> specific port. |
| ACT-USER:[tid]:uid:ctag::pwd; | Valid aid codes: none, requires user name instead. <br> This command logs in the username uid with <br> password pwd. |
| CANC-USER:[tid]::ctag; | Valid aid codes: None. <br> This command logs off the TL1 user and returns to <br> security level 0. |
| DISC-MODULE:[tid]:aid:ctag; | Valid aid codes; SxAy. <br> This command disconnects (disables) a module (not a <br> specific port). |
| EXIT:[tid]::ctag; | Valid aid codes: None. <br> This command logs off the user and returns an RS-232 <br> port to ASCII mode or disconnects an Ethernet session <br> to end TL1 communication. |
| RMV-MODULE:[tid]:aid"ctag; | Valid aid codes: SxAy. <br> This command removes module configuration <br> information from the database of the SSU-2000 unit. |
| RST-MODULE:[tid]:aid:ctag; | Valid aid codes: SxAy. <br> This command restarts (reboots) the specified module. |
| RST-CLOCK:[tid]:aid:ctag; | Valid aid codes: S1A1, S1A12 <br> This command resets the specified clock module via <br> hardware. This reset is more drastic than the restart in <br> that it does not give the clock time to switch to the <br> secondary clock if it was the primary clock. |

## B. 3 Interactive Command Set

The Interactive Command Set (ICS), also called the ASCII command set, can be used to control the SSU-2000 from a terminal connected to one of the SSU-2000 RS-232 serial ports.

This section describes ICS command conventions, the prompts, line editing functions, and command syntax for ICS commands. The ICS command functions and features are organized by user security access levels and are listed alphabetically, see Section B.3, Interactive Command Set.

## EL Note..

If you are unable to access command features using your current security access level, contact your SSU-2000 administrator user for assistance.

## B.3.1 General Conventions

The following are ICS command general conventions:

- Braces \{ \} indicate multiple options. When entering options in the ICS command, enter one option from the options listed in the braces. Options within braces \{ \} are separated by a pipe ( $\mid$ ).
- Brackets [ ] indicate that the enclosed information is optional.
- Italics indicate variable options.
- The variable xAy-z indicates the aid, or access identifier. This variable specifies the shelf and slot location for hardware components, in this format:
xAy-z
where:
$\mathbf{x} \quad$ Slot number of the unit:
$1=$ the slot position for the main shelf or unit
$2-5=$ slot positions for expansion shelves, numbering from left to right
APlace holder or slot separator
ySlot number, beginning with one, and numbering from left to right for each shelf
zPort number for a module


## B.3.2 ICS Prompts

ICS uses the SSU-2000 unit name followed by command prompt. The prompt is either $+>$ or $->$ :

- The +> prompt indicates that the last output string is an event.
- The -> prompt indicates that the last output string is a response to a command or end-of-line.


## B.3.3 Line Editing

The ICS interface supports these line-editing functions:

- Press ESC (Escape) to clear the ICS command buffer.
- Press Backspace to delete the last character entered.
- Press $\mathbf{C t r l}+\mathbf{C}$ to stop all output and flush the transmit buffers.
- Input and output end-of-line (EOL) characters function independently. The ICS interface automatically adjusts to changes in incoming EOLs.


## B.3.4 Logon Requirements

The ICS interface features an optional logon requirement:

- If the user list is empty and no passwords have been set for default users, logon is not required and the software defaults to the Administrator user.
- After a user name has been added or a password has been entered for the Administrator user, a user name and logon password is required.
- While communicating with the SSU-2000 using an EIA-232-C connection, if the communications port requires a user name and logon password, only these commands are available until an operator logs on: ID, INFO, LOGIN, HELP, and DOY. In this state, the port displays autonomous events but does not allow a query of event history until the operator logs on.
- While communicating with the SSU-2000 using Telnet, if the communications port requires a user name and password to log on, the interface does not allow commands to be performed or events to be displayed until the operator logs on. For example, events are stored in the event history but are not displayed on ports to which no user is logged on.


## B.3.5 Command Syntax

The ICS interface follows these conventions for expressing command syntax:
All lowercase letters are converted to uppercase.

- Command is any valid command consisting of only uppercase letters, excluding the <Data Separator> and <Command Separator> codes, in this format:

Command [<Data Separator> <data>...] [<Command Separator>] or EOL
where:
<Data Separator> is any of the following:
> (hex 20) space character. Multiple spaces are converted to a single space character.
<data> The data input for the command. This can be any combination of printable ASCII codes and is specified in the command description section. Use double quotes ( " ") to imply literal input. All data within the quotes is accepted as a single data entry, allowing you to enter complex input strings. The ICS interface does not convert uppercase characters in quotes to uppercase.
<Command Separator> is a semicolon (;).

- The interface responds to any input line terminator. Possible terminators are CR, LF, or CRLF. When the interface receives any of these terminators, the input is terminated and the entered command line is processed.
- The ICS interface uses the following single-character commands:
/ executes the previous command if it is used as the first character on a line.
? $\quad$ alias of the HELP command.
- Command descriptions follow this format:

Command The command name as it appears in the system.
Description Brief description of the command functionality.
Operation Level 1: Gives the options and operations for Level 1 (Operator)
Level 2: Gives the options and operations for Level 2 (Technician)
Level 3: Gives the options and operations for Level 3 (Supervisor)
Level 4: Gives the options and operations for Level 4 (Administrator)
Remarks Includes comments on the command operation.

Related Shows any commands related to this command. This command may affect other commands or be affected by other commands.

Restrictions Special restrictions on the use or operation of this command.

- Command syntax follows these conventions:
\{ \} Signifies more than one parameters choice; one must be entered. Options are separated by vertical bars.
| Pipe or vertical bar, used to separate multiple parameters or options.
[] Signifies optional parameters.
italics $\quad$ Signifies variable data.
c Signifies character data (any printable ASCII character).
- Terminology:
shelf The actual shelf number of the unit in the system: 1 indicates the main shelf; 2 through 5 indicate expansion shelves.
slot The actual slot number in the shelf. Slot numbers begin at 1 and number from left to right in the shelf.
port The actual port number in the slot. The port number begins at 1 .
Comm port An EIA-232-C, Telnet, or Ethernet TL1 communications port.
- Module selection follows these conventions. Each module selection in a unit is defined as: $\mathbf{x A y}$.
where:
$\mathbf{x}$
Shelf number (starting from 1);
A Place holder indicating the slot separator;
$\mathbf{y} \quad$ Slot number (starting from 1, left to right, defined by each shelf).
- Port selection follows these conventions. Each port of a module is addressed as: xAy-z.
where:
$\mathbf{x A y} \quad$ same as defined for module selection.
$\mathbf{z} \quad$ Indicates the port number, starting from 1, left to right
- Legal module and port names follow the conventions illustrated by these examples:
- 1A5-3 indicates shelf 1 , slot 5 , port 3 .
- $\quad 1 \mathrm{~A} 5$ indicates a module in shelf 1 , slot 5 .
- The ICS interface allows aliases for modules. Aliases follow the conventions shown in these examples. For example, assuming a 19 inch chassis, these aliases apply:

> CLK-A = Clock A, 1A1

CLK-B = Clock B, 1A12
2BUF-A = Shelf 2, Buffer A, 2A15
2BUF-B $=$ Shelf 2, Buffer B, 2A16
3BUF-A = Shelf 3, Buffer A, 3A15
3BUF-B $=$ Shelf 3, Buffer B, 3A16
4BUF-A = Shelf 4, Buffer A, 4A15
4BUF-B = Shelf 4, Buffer B, 4A16
5BUF-A = Shelf 5, Buffer A, 5A15
5BUF-B = Shelf 5, Buffer B, 5A16

- Communications port names follow these conventions:
- For the EIA-232C serial port
$\mathrm{L}=$ Local RS232 port (i.e., COML = local EIA-232 port)
A = Serial Port A (i.e., COMA is Serial Port A)
B $=$ Serial Port B (i.e, COMB is Serial Port B)
- For the Telnet port:

TELA = Telnet session one
TELB $=$ Telnet session two
TELC $=$ Telnet session three
TELD $=$ Telnet session four

- For the Ethernet TL1 port:

TL1A = Ethernet TL1 session one
TL1B $=$ Ethernet TL1 session two

- The interface uses ISO 8601 Date and Time Format:

Date and Time format: yyyy-mm-ddThh:mm:ss
(example: 1998-02-19T11:03:03)
Date format: yyyy-mm-dd
Time format Thh:mm:ss+

## B.3.6 ICS Commands

This section provides an alphabetical listing of all ICS commands. For each command, the section provides the following information:

- Command name as it appears in the system
- Description of command function
- Operation of this command at security levels 0 through 4, with descriptions of syntax and command functions for each level
- Remarks and comments about the command operation
- Related Commands lists other commands that may affect or be affected by the command.
- Restrictions describes any special restrictions on the use or operation of the command.


## ALARM

Use this command to provide the current alarm status and access to the alarm settings.
Level $0 \quad$ Not applicable
Level $1 \quad$ ALARM [\{ALL $\mid \mathbf{x A y}[-\mathbf{z}]\}]$
Use this command to view the current alarm status for the module that you specify. Only active alarms display, unless an option is passed.

If you do not specify a parameter, each active alarm status stored in the Communications Module is displayed. If you type ALL, the current status of all alarms for all modules through the SPI command displays.

Output from the command includes the alarm number (internal number used for alarm identification), a text description of the alarm, the current status, the current alarm level (elevated alarms are indicated with an asterisk*), and the delay time for the alarm.

Example:
SSU_2000->alarm 1A2
2001-05-24T18:23:38Z ID: SSU2000 Name: SSU_2000
Input \# Alarm Status Level(*=Elev) Delay

1A02 (00) Communication Ok Minor 5 sec
1A02 (01) Mastership Ok Minor 30 sec
1 A 02 (02) Power-A Ok Minor Immed
Level 2 Same as Level 1 operation, with the following additions:

## ALARM TEST \{MINOR|MAJOR| CRITICAL\}

Options are:
TEST Use this option to test and activate alarm relay/ LED for one

MINOR Use this option to set the MINOR alarm relay/ LED.
MAJOR Use this option to set the MAJOR alarm relay/ LED.
CRITICAL Use this option to set the CRITICAL alarm relay/ LED.

## Level 3 Same as Level 2 operation, with the following additions:

## ALARM xAy[-z] \# DELAY time

## ALARM xAy[-z] \# \{IGNORE| REPORT| MINOR| MAJOR| CRITICAL\}

Use this command to set up the expected operation for the specified alarm number. Only one alarm number can be passed if you enter additional information.

The additional parameters that you can use are:
\# Alarm number

DELAY A supervisor can use this parameter to enter the amount of time that an alarm condition must be active before an actual alarm condition is generated. If an alarm is specified to be Immediate, no delay time can be entered. (Delay times are in seconds).

Valid delays to use are: 0 to 86,400 seconds (1 day). If the original value is set to -1 (Immediate) for this command, delay time cannot be set by the user.

IGNORE Use this option to set the alarm status level to IGNORE. This means that no action is taken for an alarm condition.

REPORT Use this option to set the alarm status level to REPORT. This means that a report-only message occurs for an alarm condition.

MINOR Use this option to set the alarm status level to MINOR.
MAJOR Use this option to set the alarm status level to MAJOR.

CRITICAL Use this option to set the alarm status level to CRITICAL.

Level $4 \quad$ Same as Level 3 operation.
Remarks Use of this command implies that the operator is querying the state of the unit. All information is presented as concisely and completely as possible. Each alarm is listed on a separate line.

Related ELEVTIME, STATUS
Restrictions None

## BYE

Use this command to $\log$ off.
Level $0 \quad$ Not applicable

## Level 1 BYE

Use this command to log off the system. If passwords are enabled, the logon header displays and you are prompted for a user name.

Level 2 Same as Level 1 operation
Level 3 Same as Level 1 operation
Level 4 Same as Level 1 operation
Remarks This command implies that the operator has completed the session and wants to
return the SSU-2000 to an Idle state.

Related LOGIN

Restrictions None

## CLK

Use this command to view the clock status and access the clock operating parameters.
Level $0 \quad$ Not applicable
Level 1 CLK [xAy]
If you do not specify a parameter, the status for both CLOCK A and CLOCK B in the unit displays. If you specify a particular clock address, the clock status and setup information for that clock display.

Concise status information: Status (Fail/ Disable/ Selected/ OK), Software Phase Locked Loop Mode, Current Tau, PQL Value, Freq Offset, Sigma.

Detailed status information: Same as concise status information, with the addition of Current Max Tau.

Concise setup information: Minimum tau, maximum tau, Clk Freq, clock switching method (such as, AutoReturn or Not), input switching method (AutoReturn On, AutoSwitch On, or AutoSwitch Off), input selection mode (Priority or PQL), and Local Oscillator output is On or Off.

Detailed setup information: Same as concise setup information, with the following additions: Freq.Offset limit, warm-up time, minimum tau limit, and maximum tau limit. The alarm level and delay time are handled by the ALARM command. The alarm elevation time is handled by the ELEVTIME command.

Example:

```
SSU_2000->clk
```

```
2001-05-24T18:24:21Z ID: SSU2000 Name: SSU_2000
CLOCK STATUS
Loc# Status Mode Tau Pql Freq off Sigma
---- ------ ---- ----- --- -------------------
1A01 Sel LOCK 3330 5 9.22E-11 2.49E-10
1A12 Ok LOCK 333 5 -7.55E-09 2.75E-10
```

Level 2 Same as Level 1 operation
CLK xAy MODE \{ACQUIRE | LOCKED | HOLD\}

## CLK xAy SELECT

Options are:
MODE \{ACQUIRE | LOCKED| HOLD\}
Use this option to set the current PLL operation parameters.
ACQUIRE Use this option to force re-acquisition of the software PLL loop.
LOCKED Use this option to put the software PLL mode into the lock state.
HOLD Use this option to put the software PLL mode into the manual holdover state.
SELECT Use this option to allow the operator to specify the clock reference.
Level 3 Same as Level 2 operation, with the following additions:
CLK $\{A R|O N| O F F\}$CLK [xAy] WARMUP value
CLK [xAy] \{MINTAU | MAXTAU\} value
Options are:
AR \{ON | OFF \} Use this option to enable or disable the clock AutoReturnmode.
WARMUP Use this option to set the clock warm up time in seconds.
MINTAU Use this option to set the minimum tau value.
MAXTAU Use this option to set the maximum tau value.
Level 4 Same as Level 3 operation
Remarks None
Related SETUP, STATUS
Restrictions None

Use this command to view and change the current communication port settings.

## Level $0 \quad$ Not applicable <br> Level $1 \quad$ COMM [\{L $|\mathbf{A}| \mathbf{B}\}]$

Use this command to view the current settings for the specified communications port. If you do not specify a communications port, all communications ports are assumed. The communications port settings include baud rate, character echo, current output line termination, current session mode, and time-out value.

COMM BAUD $\{\mathbf{1 2 0 0 |} \mathbf{2 4 0 0 |} \mathbf{4 8 0 0 |} \mathbf{9 6 0 0 |} \mid \mathbf{1 9 2 0 0}\}$
COMM ECHO \{ON | OFF $\}$

## COMM EOL \{CR| LF| CRLF $\}$

Use this option to change the setting for the port over which you are communicating. If your security access level is Level 1 , the setup changes are not stored in non-volatile RAM.

Options are:
BAUD Use this option to set the current baud rate setting. Only the baud rates shown are valid.

ECHO Use this option to enable or disable character echo on the terminal.

EOL $\{\mathbf{C R}|\mathbf{L F}| \mathbf{C R L F}\}$ Use this option to set the current End-Of-Line termination for output line.

CR Use this option to set the line termination to carriage return (0xD).

LF Use this option to set line termination to line feed (0xA).
CRLF Use this option to set the line termination to carriage return, followed by a line feed.

Level 2 Same as Level 1 operation, with the following additions:
COMM \{L |A | B $\}$ BAUD $\{\mathbf{1 2 0 0 |} \mathbf{2 4 0 0 |} \mathbf{4 8 0 0 |}|\mathbf{9 6 0 0 |}| \mathbf{1 9 2 0 0}\}$
COMM $\{\mathrm{L}|\mathrm{A}| \mathrm{B}\}$ ECHO $\{\mathrm{ON} \mid \mathrm{OFF}\}$
COMM $\{\mathrm{L}|\mathrm{A}| \mathrm{B}\}$ EOL $\{\mathrm{CR}|\mathrm{LF}|$ CRLF $\}$

## COMM $\{\mathrm{L}|\mathrm{A}| \mathrm{B}\}$ MODE $\{\mathbf{A S C I I} \mid$ TL1 $\}$

## COMM \{L| A | B | TELNET | TL1\} TIMEOUT \{[5-43200] | NEVER\}

Use this option to change the setting for a specified communications port. The setup changes are stored in non-volatile RAM.

Options are:
MODE \{ASCII| TL1\}Use this option to set the current mode to either ASCII (interactive) or TL1.

## TIMEOUT Use this option to set a communications port automatic logout-time-out value. Values are in seconds. NEVER disables automatic logout.

Level 3 Same as Level 2 operation
Level 4 Same as Level 3 operation
Remarks None
Related None
Restrictions BAUD, ECHO, AND EOL are only applicable to RS-232-C. The communications port must be specified to set any parameter.

## CONFIG

Use this command to view the current hardware configuration of the unit.
Level $0 \quad$ Not applicable
Level 1 CONFIG [xAy]
If you do not provide parameters, the current hardware inventory displays with each slot on one line (concise information). If you provide parameters, more detailed hardware and software inventory management information displays in multiple lines (detailed information).

Concise information: Concise Information includes slot location, module name, item number, hardware revision number, manufacture date, and serial number. If shelf address, $1-5$, it will display shelf description and shelf part number ( 254 xxxxx-xxx-x).

Detailed information: Includes all the concise information described in the above. It also includes configured revisions (if supported by module), in-service time (if supported by module), and the feature list (if supported by module, for example: the COMM Module returns NTP and SNMP features).

If the $x A y$ is $1-5$, the shelf information is displayed. The description and shelf_part are per Table B-8.

Table B-8. Shelf Configuration Information

| Shelf | Description | Shelf Part |
| :---: | :--- | :--- |
| 1 | SSU-2000 | $25413020-000-0$ |
| $2-5$ | SSU-2000 | $25413140-000-0,25413140-001-0$ |
| 1 | SDU-2000 | $25413023-000-0$ |
| $2-5$ | SDU-2000e | $25413141-000-0,25413141-001-0$ |

## CONFIG SW

This command will display software part number (141xxxxx-xxx-x) and revision number.

Level 2 Same as Level 1 operation, with the following additions:

## CONFIG xAy \{REMOVE| DISABLE| ENABLE $\}$

Options are:

REMOVE Use this option to remove module entries from the registry. A module is removable only if it is physically absent.

DISABLE Use this option to mark a module inactive to be removed from the system.

ENABLE Use this option to restore a previously disabled module to be active in the system.

Level 3 Same as Level 2 operation
Level 4 Same as Level 3 operation
Remarks None

Related None
Restrictions None
The following are examples of the CONFIG command message format:

## SSU_2000->CONFIG

| $\begin{aligned} & \text { 2001-06-21T15:10:34Z } \\ & \text { Loc\# Name } \end{aligned}$ | SSU2000 Name: JWANG <br> HW Part \# HW Rev | Date | Serial \# |
| :---: | :---: | :---: | :---: |
| 1 SSU-2000 | 25413020-000-0 |  |  |
| 1A01 Clock Stratum 2E | 23413016-000-0 A | 30NOV99 | 990705398000615020 |
| 1A02 Communication | 23413012-000-0 A | 03NOV99 | 990705398000614573 |
| 1A03 Input GPS | 23413019-000-0 A | 18DEC99 | 1234567890005 |
| 1A05 Input GPS | 23413019-000-0 A | 29FEB00 | 990705398000728324 |
| 1A06 Input E1 3Port | 23413014-002-0 B | 03DEC99 | 990705398000661713 |
| 1A07 Input DS1 3Port | 23413013-002-0 B | 26JANoo | 1234567890 |
| 1A08 Input DS1 1Port | 23413013-001-0 B. 02 | 21APR00 | 990705398000736077 |
| 1A09 Input DS1 3Port | 23413013-002-0 B. 02 | 27MAR00 | 990705398000736527 |
| 1A10 Output DS1 | 23413017-000-0 D | $30 \mathrm{NOV99}$ | 990705398000613606 |
| 1A11 Output DS1 | 23413017-000-0 B | 02MAR00 | 990705398000613453 |
| 1A12 Clock Stratum 3E | 23413015-000-0 A | 09MAR00 | 990705398000734493 |
| 2 SDU-2000 | 25413023-000-0 |  |  |
| 2A01 Output E1 | 23413018-000-0 D | 05JANOO | 990705398000650816 |
| 2A02 Output E1 | 23413018-000-0 D | 13JANOO | 990705398000650793 |
| 2A03 Output DS1 | 23413017-000-0 D | 15JAN99 | 1234567890 |
| 2A04 Output DS1 | 23413017-000-0 D | 15JAN99 | 1234567890 |

## SSU_2000->CONFIG SW

| Loc\# Name | SW Part \# SW Rev | Date |
| :---: | :---: | :---: |
| 1A01 Clock Stratum 2E | 14113015-000-0 B.06 | 20JUNO1 |
| 1A02 Communication | 14113012-003-0 A.00 | 21JUNO1 |
| 1A03 Input GPS | 14113019-000-0 A. 04 | 21JUNO1 |
| 1A05 Input GPS | 14113019-000-0 A.04 | 21JUN01 |
| 1A06 Input E1 3Port | 14113013-000-0 B.04 | 200CT00 |
| 1A07 Input DS1 3Port | 14113013-000-0 B.04 | 200CT00 |
| 1A08 Input DS1 1Port | 14113013-000-0 B.04 | 200CT00 |
| 1A09 Input DS1 3Port | 14113013-000-0 B. 04 | 200CT00 |
| 1A10 Output DS1 | 14113017-000-0 A.06 | 19APR01 |
| 1A11 Output DS1 | 14113017-000-0 A.06 | 19APR01 |
| 1A12 Clock Stratum 3E | 14113015-000-0 B. 06 | 20JUNO1 |
| 2A01 Output E1 | 14113017-000-0 A.06 | 19APR01 |
| 2A02 Output E1 | 14113017-000-0 A.06 | 19APR01 |
| 2A03 Output DS1 | 14113017-000-0 A.06 | 19APR01 |
| 2A04 Output DS1 | 14113017-000-0 A.06 | 19APR01 |
| 2A05 Output E1 | 14113017-000-0 A.06 | 19APR01 |
| 2A08 Output Comp Clock | 14113158-000-0 A.02 | 090CT00 |
| 2A09 Output Comp Clock | 14113158-000-0 A.02 | 090Сто0 |

## DATE

Use this command to view and set the current date.
Level $0 \quad$ Not applicable

## Level 1 DATE

Use this command to view the current date set within the unit. The date format that displays is:

## yyyy-mm-dd

Level 2 Same as Level 1 operation
Level 3 Same as Level 2 operation, with the following additions:
DATE yyyy-mm-dd

Use this option to set the current date.
Level 4 Same as Level 3 operation
Remarks None
Related TIME, DOY

Restrictions None

## DOY

Use this command to view the Julian date and the year in the unit.

Level $0 \quad$ This command returns the day of the year and the current year.
Level 1 Same as level 0 operation
Level 2 Same as level 0 operation
Level 3 Same as level 0 operation
Level 4 Same as level 0 operation
Remarks This command is used to display the current day of the year and the year in the unit. This command is used for the generation of backdoor passwords and, for this reason, is always a hidden command.

Related LOGIN

Restrictions This command is always hidden and does not display in the online Help.

## ELEVTIME

Use this command to read and set the current time-outs for alarm elevation.

Level $0 \quad$ Not applicable
Level 1 ELEVTIME [xAy]
If you do not specify a parameter, all module elevation times within the unit display.

Level 2 Same as Level 1 operation.
Level 3 Same as Level 2 operation, with the following additions:

## ELEVTIME [xAy] time

Supervisors use this command to read and set the current time-out length for alarm elevation. The unit is required to elevate MINOR and MAJOR alarms to the next level after a user settable time period. Time is in seconds and can be from 60 seconds ( 1 minute) to 500,000 seconds.

Level 4 Same as Level 3 operation
Remarks The default value for the elevation time is 86,400 seconds ( 24 hours).
Related ALARM, SETUP
Restrictions None

The following is an example of the ELEVTIME command message format:

## SSU_2000->ELEVTIME

```
SSU_2000->elevtime
2001-06-18T20:44:50Z ID: SSU2000 Name: SSU 2000
1A01 elevation time is 86400 seconds
1A02 elevation time is 86400 seconds
1A03 elevation time is 86400 seconds
1A04 elevation time is 86400 seconds
1A05 elevation time is 86400 seconds
1A08 elevation time is }86400\mathrm{ seconds
1A09 elevation time is }86400\mathrm{ seconds
```


## ENGINE

Use this command to read or set the current settings for the GPS engine.
Level $0 \quad$ Not applicable
Level $1 \quad$ ENGINE xAy [ELMASK| POS| AVAIL]
ELMASK Use this option to read current elevation masks for the GPS engine.

POS Use this option to read the current antenna position (latitude and longitude).

AVAIL Use this option to show current satellite availability.
Level 2 Same as Level 1 operation
Level 3 ENGINE xAy [PMASK mask] [TMASK mask]
ENGINE xAy POS [lat lon ht] [AVG n]
ENGINE xAy TDATA [ON| OFF| CLR]
ENGINE xAy PDOP \{1-10\}
ENGINE xAy FREQ [\{ADD| DEL\} freqval]
PMASK mask Use this option to read and set the current elevation masks for the GPS engine. The masks change to avoid attempting to track satellites that are below a portion of the sky that might be blocked by the terrain.

PMASK Use this option to set the positioning mask level. Lower mask levels provide the unit position with a better PDOP.

TMASK mask Use this option to set the mask level to be used when not in survey mode. This is usually set to a higher level than positioning because of timing degradation of the GPS signals at low elevations. Valid mask levels are from 0 to 60 degrees

POS Use this option to read and set the current antenna position. In addition, you can set the maximum number of averages to perform on the position calculations.

## POS [lat lon ht] [AVGn]

Same as Level 1 operation, with the addition of being able to set the current position and or the number of averages to use when calculating a position.

Options are:
lat Antenna latitude. The decimal point determines the input format. For example, the format is dd:mm:ss.ss for entering 30:27:49.8 seconds.
lon Antenna longitude. The format is dd:mm:ss.ss.
height Antenna height; +/- 10,000.0 meters.

AVG $n \quad$ Number (n) of averages for the calculated position fixes. Range is 10 to 1,000 . Setting this places the unit into survey mode. The frequency control is placed into holdover during survey mode.

AVAIL $\quad$ Shows the current satellite availability

A table is generated with the following information:

- SV Satellite PN code ID.
- Elev Current elevation above the horizon of the satellite, in degrees.
- Azmth Azimuth of the satellite, in degrees.
- Hlth Health of the satellite, either H or U. Unhealthy can also mean that the user has set the receiver to ignore the satellite.

NOTE ..

Only satellites that are above the current elevation mask are shown.

PDOP Sets the current Position Dilution of Precision or pdop mask (1 through 10). Pdop is a measurement that indicates the geometry of the GPS satellites that the SSU-2000 unit is tracking. Lower values indicate better geometry.

TDATA Provides tracking information for the engine.

Available options are:

ON Tracking data displays on that communications port.

OFF Tracking data does not display on that communications port.

CLR No tracking data displays on any communications port.

## FREQ \{ADD|DEL\} freq

Allows for adding or deleting a CDMA pilot frequency value and freqval $=$ pilot frequency in MHz (decimal based, for example: 3.4328).

## Level 4 Same as Level 3 operation

## Remarks

## ELMASK Default values for the masks are 5 degrees for the positioning mask and 10 degrees for time.

> POS Only set the position if you know the accurate position. The software automatically verifies the position on restart. The unit averages 10 position fixes and compares them to the fixed position.

> If the position is within 100 m RMS, no position updates are performed. If the position error is $>100 \mathrm{~m}$ RMS, an event is generated stating that the position is being recalculated, and the position is recalculated and updated in the NVRAM. Similarly, setting the AVG time puts the unit back into survey mode, which generates an event that the position is being recalculated.

> TDATA Engine reports are asynchronous outputs, which means they can occur at any time, not necessarily at the time the command is issued.

Related None

Restrictions None

The following is an example of the ENGINE command message format:

## SSU_2000->ENGINE

```
2001-06-18T20:46:20Z ID: SSU2000 Name: SSU_2000
GPS Module: 1A03
GPS MOT Engine: 2.2, APR 24 1998
Lat: +30:27:15.89, Lon: -097:39:45.88, Ht: 230.81 m (3D) PDOP: 2.7, 300
ave
GPS Module: 1A05
GPS MOT Engine: 2.2, APR 24 1998
Lat: +30:27:15.75, Lon: -097:39:45.85, Ht: 233.43 m (3D) PDOP: 2.8, 10 ave
```


## EVENTS

Use this command to read and control current event log information.
Level $0 \quad$ Not applicable
Level 1 EVENTS [ALARM| REPORT] [\#events_display | ALL]
EVENTS [ALARM| REPORT] [startdate [starttime]] [stopdate [stoptime]]
EVENTS [ALARM| REPORT] starttime [stopdate] [stoptime]
EVENTS If you do not specify any options, only the last event prints.
Other options are:
ALARM Use this option to show alarm events only. The alarm event is defined as any event ID less than 32 .

REPORT Use this option to show report events only. Any events excluding alarm events (for example: any event ID is greater 32).
\#event_displayUse this option to show the maximum number of events to display. Zero returns all events.

ALL Use this option to show all the events stored in the buffer.

## [startdate] [starttime]

Use this option to specify the start time and date for displaying events within a time period.
[stopdate] [stoptime]
Use this option to specify the stop time and date for displaying events within a time period
? Use this option to display the event count.

[^1]Example:
SSU_2000+>events alarm

| Time Stamp | Which Type Event | Description |
| :---: | :--- | :--- |
| 2001-05-24T18:27:00Z | 1A04-03 Maj LOS | Active |
| $2001-05--24 \mathrm{~T} 18: 27: 29 Z$ | 1A01 Rep Soft PLL, | HOLD |
| $2001-05-24 \mathrm{~T} 18: 27: 29$ Z | 1A01 Min Freq Mode, | Holdover |

Level 2 Same as Level 1 operation
Level 3 Same as Level 2 operation, with the following additions:
EVENTS CLR
This option clears the event list.
Level 4 Same as Level 3 operation
Remarks Events are stored in non-volatile memory. They are retained on startup.
Related ALARM
Restrictions None

## FREQUENCY

Use this command to display the input frequency data from a selected input port.
Level $0 \quad$ Not applicable

## Level $1 \quad$ FREQUENCY [xAy] [\{A| B\}]

Use this command to view the frequency measurement from a selected input module. If you do not provide a parameter, frequency measurement on the selected clock to all inputs displays.

Options are:

A| B Clock A or Clock B

Level 2 Same as Level 1 operation
Level 3 Same as Level 1 operation
Level 4 Same as Level 1 operation
Remarks None

Related INPUT, PHASE
Restrictions None

The following is an example of the FREQUENCY command message format:

## SSU_2000->FREQUENCY

```
1A04-01 FreqA:2001-06-18T20:54:19, 0
1A04-02 FreqA:2001-06-18T20:54:19, 1
1A04-03 FreqA:2001-06-18T20:54:19, 1
1A09-01 FreqA:2001-06-18T20:54:19, 3
1A09-02 FreqA:2001-06-18T20:54:19, 2
1A09-03 FreqA:2001-06-18T20:54:19, 1
```


## HELP

Use this command to access online Help.
Level $0 \quad$ HELP
Use this command to access the online Help menus. If you specify you want to view Help for a specific command, the Help menu for that command displays.

Remarks Only commands that are valid for the user level are displayed in the Help menu. The Help menu does not display any command that you cannot perform at your current logon level. If the first entered character is?, then ICS displays the main Help screen.

Related None
Restrictions None
The following is an example of the HELP command message format:

## SSU_2000->HELP

Level 4 commands:

| ALARM | BYE | CLK | COMM | CONFIG | DATE |
| :--- | :--- | :--- | :--- | :--- | :--- |
| ELEVTIME | ENGINE | EVENTS | FREQ | HELP | ID |
| INFO | INPUT | IONAME | IP | KEEPALIVE | MSG |
| MTIE | NAME | NTP | OUTPUT | PBO | PHASE |
| PING | PQLTABLE | REF | RESET | RESTART | SETUP |
| SNMP | STATUS | SYSTIME | TDEV | TIME | USERS |
| VER | WHO |  |  |  |  |

## ID

Use this command to display the fixed unit ID for the system.

Level $0 \quad$ Displays SSU2000e
Level 1 Same as Level 0 operation
Level 2 Same as Level 0 operation
Level 3 Same as Level 0 operation

Level 4 Same as Level 0 operation
Remarks This command is used by test systems to tell the type of instrument connected. This is different from the NAME command in that the NAME information is settable by the user. The unit ID is also returned on any status type command.

Related NAME

Restrictions None

The following is an example of the ID command message format:
SSU_2000->ID
Unit ID: SSU2000

## INFO

Use this command to view information necessary to return a product for service. This includes the unit ID, software version(s), shipping address, and phone number for Datum, Inc.

## Level $0 \quad$ INFO

Displays information as follows (assume COMMS Version A, Bootloader A):
Unit ID: SSU2000
Main Code: A.01, 10FEB99
Copyright 1997-99
Datum
15811 Vision Drive
Pflugerville, Texas 78660
Ph: (512) 721-4032
Fax: (512) 721-4033

Level 1 Same as Level 0 operation
Level 2 Same as Level 0 operation
Level 3 Same as Level 0 operation
Level 4 Same as Level 0 operation
Remarks This command provides a method for you to have all service information available for a unit.

Related ID, VER
Restrictions None

## INPUT

Use this command to access to the input status, hardware configuration, and alarm settings.
Level $0 \quad$ Not applicable

Level 1 INPUT [xAy[-z]] [STATUS| SETUP]
If you do not provide a parameter, all the input module status information in the unit displays. If a specified input address is provided, that input status and setup information displays.

Options are:
STATUS Use this command to display input status information.
SETUP Use this command to display input setup information.
Status information: status, phase A/B values, PQL, hardware alarm (LOS, AIS, OOF, BPV, CRC) statuses, MTIE status.

Setup information: port (Enable or Disable), framed signal (D4 or ESF if DS1, CAS or CCS if E1), unframed signal (if specified as CLK), zero suppression (ON or OFF), CRC (ON or OFF), SSM (ON or OFF), PQL provision value (116), priority ( $0-10$ ), high gain (ON or OFF), cesium fault indication level (High, Low, OFF), MTIE mask limits, hardware alarm (LOS, AIS, OOF, BPV, CRC) error count and clear error count setting.

If E1: SSM bit position (4 through 8)
The alarm level and delay time are handled by the ALARM command. The alarm elevation time is handled by the ELEVTIME command.

Example:
SSU_2000+>input


Level 2 Same as Level 1 operation
Level 3 Same as Level 2 operation, with the following additions:
INPUT xAy[-z] \{ESF | D4| CCS | CAS |1MHZ | 1.544MHZ | 2.048MHZ | 5MHZ|10MHZ\}

INPUT xAy[-z] \{ZS |SSM | CRC $\}$ \{ON | OFF $\}$
INPUT xAy[-z] PRIORITY $\{0-10\}$
INPUT xAy[-z] \{ENABLE| DISABLE\}
INPUT xAy[-z] SSM $\{4|5| 6|7| 8\}$
INPUT xAy[-z] PQL \{1-16\}
INPUT xAy[-z] MTIE [\{EL1| EL2| CL1| CL2\}] \{T10| T100| T1K| T10K|
T100K \} value
INPUT xAy[-z] MTIE \{PRS| DS1| G.811| G.823\}
INPUT xAy[-1] GAIN $\{\mathrm{ON} \mid \mathrm{OFF}\}$
INPUT xAy[-z] CSFLT \{HIGH| LOW| OFF \}
INPUT xAy[-z] \{LOS| AIS| OOF| BPV| CRC\} \{SET| CLR\} value
INPUT xAy[-z] FREQ $\{\mathrm{A} \mid \mathrm{B}\}\{\mathrm{SET} \mid \mathrm{CLR}\}$ value
Allows the user to change the setting of a specified input module.
Options are:
ESF/ D4 Set the T1 framing mode: ESF or D4.
CCS/ CAS Set the E1 framing mode: CCS or CAS.
1MHZ | 1.544MHZ | 2.048MHZ | 5MHZ | 10MHZ
Sets the basic input module clock frequency when input is not running in framing mode. Only the clock frequencies shown are valid. If the module is a T1 frame signal, the CLK rate is 1.544 MHZ ; if it is E1 frame signal, the CLK rate is 2.048 MHZ automatically.

ZS \{ON | OFF $\}$ Enables or disables Zero Suppression
For DS1:
B8ZS (zero suppression on) or AMI (zero suppression off)
For E1:
HDB3 (zero suppression on) or AMI (zero suppression off)
SSM \{ON | OFF $\}$
Enables or disables Sync Status Message reading
CRC $\{\mathrm{ON} \mid \mathrm{OFF}\}$
Enables or disables CRC checking

## PRIORITY \{0-10\}

Sets Input priority level, where: $0=$ monitor. 1 - highest priority, and $10=$ lowest priority

ENABLE Enables a specified input port

DISABLE Disables a specified input port. This clears all alarms associated with an input and disables setting of further alarms or use of the input measurements.
$\operatorname{SSM}\{4|5| 6|7| 8\}$
Sets the E1 SSM bit Position
$\operatorname{PQL}\{2|3| 4|5| 6 \mid 8\}$
Sets a Priority Quality Level (PQL) to a specified input port
MTIE [\{EL1| EL2| CL1| CL2\}] \{T10| T100| T1K| T10K| T100K \} value
Sets MTIE Limit 1 or Limit 2 for 10/100/1,000/ 10,000/100,000 seconds threshold. If L1 or L2 are not provided, both limits are implied. The Limit Range is [0.100,000].

EL1 MTIE Error Limit 1
EL2 MTIE Error Limit 2
CL1 MTIE Clear Limit 1
CL2 MTIE Clear Limit 2

T10 MTIE 10-second period
T100 MTIE 100-second period
T1K MTIE 1000-second period
T10K MTIE 10000-second period
T100K MTIE 100000-second period
MTIE $\{$ PRS| DS1| G.811| G.823\}
Sets MTIE Limit 1 or Limit 2 for predefined values
ANSI Specification- PRS, DS1
ITU Specification - G.811, G. 823
GAIN\{ON | OFF $\}$
Enables or disables input gain setting for port one

## CSFLT \{HIGH| LOW| OFF \}

Sets cesium fault logic level

> HIGH High. Alarm is active when the fault is a high logic level

LOW Low. Alarm is active when the fault is a low logic level
OFF Default. Cesium Fault is ignored (not the AIS).

# \{LOS| AIS| OOF| BPV| CRC\} \{SET| CLR\} value <br> Sets Error Count (SET) or sets Clear Count (CLR) of a given input hardware alarm signal. These signals are LOS/ AIS/ OOF/ BPV/ CRC. 

FREQ Sets Frequency limits on Clock A or Clock B
SET Sets Freq Error Count
CLR Sets Freq Clear Count
TAU Set frequency tau. (default is 400), range is $10-1000$
Level 4 Same as Level 3 operation
Remarks None
Related SETUP, STATUS
Restrictions None

## IONAME

Use this command to set an alias name for each input or output port.

## Level $0 \quad$ Not applicable <br> Level $1 \quad$ IONAME [xAy]

Use this command to display a previously specified name associated with each I/O port.

## Example:

## SSU_2000->ioname

```
2001-05-24T18:28:23Z ID: SSU2000 Name: SSU_2000
```

1A05-01 GPS Input

Level 2 Same as Level 1 operation
Level 3 Same as Level 2 operation, with the following additions:

## IONAME xAy-z[\&\&z] \{CLR| 'io_port_name"\}

Use this option to set a name associated with each I/O port. No control characters are allowed. Multiple spaces between words reduce to one blank character. The port alias can contain up to 20 characters.

Level 4 Same as Level 3 operation
Remarks None

Related None
Restrictions CLR is an operand, and cannot be used as an I/O port name.

## IP

Use this command to view current Internet Protocol (IP) address information and access related values.
Level $0 \quad$ Not applicable
Level 1 ..... IP
Use this command to display the current IP address, subnet mask, gateway address, and the Ethernet hardware address.
Example:

```
SSU_2000->ip
```

The IP Address is 255.25.52.5
The Subnet Mask is 255.255 .255 .0
The Default Gateway is 0.0.0.0
The Ethernet Address is 00A06E000CCC
Level 2 Same as Level 1 operation
Level 3 Same as Level 2 operation, with the following additions:
IP \{ADDR | MASK | GATE $\}$ ip_dotted_address
ADDR Change the Internet Protocol (IP) address
MASK Change the subnet mask
GATE Change gateway address
Level 4 Same as Level 3 operation
Remarks When you change a network address, you must restart the CommunicationsModule in order for the changes to take effect.
Related None
Restrictions The IP address is in the decimal dotted address format (for example:
192.168.70.224). No name server is allowed.

## KEEPALIVE

Use this command to support a "keep alive" mode that, based on a user settable time an event is generated by the SSU2000 to alert the upstream support system that the SSU2000 and associated communication path is functional.

## Level 0: <br> NA

## Level 1: KEEPALIVE

Allows users to display keep alive settable time
Level 2: $\quad$ Same as level 1 operation
Level 3: Same as Level 2 operation with the following additions:
KEEPALIVE [TL1 | SNMP] [time]
The above options are:
TL1 Sets the TL1 session keep alive time
SNMP Sets the SNMP session keep alive time

## time $\quad$ Settable in minutes, minimum is 1 minute, maximum is 60 minutes. If 0 minutes are specified, it means 'keep alive' is disabled

Level 4: $\quad$ Same as level 3 operation
Remarks: None
Related: None
Restrictions: The ICS session in RS232 or telnet is not affected

## LOGIN

Use this command to change the active logon name and access level. The user is logged on as the new user name and access level when the password is verified.

## Level 0 LOGIN [user name]

If you do not provide a user name, the system prompts you for one. When you enter a user name, the system prompts you for a password. The password entry is echoed as '*' characters. If the user name and password match an entry in the user table, the user is logged on at the assigned access level. After five minutes (default) of inactivity on the port, the user is automatically logged off.

Level 1 Same as Level 0 operation
Level 2 Same as Level 0 operation
Level 3 Same as Level 0 operation
Level 4 Same as Level 0 operation
Remarks Use this command to access various levels of the system. This is the only way to change access levels for a port and provides a back door entry. This entry is based on a random number generation based from the current day of year information from the unit.

DATUM can provide the password of the day. This process helps to prevent lost or forgotten user passwords. The password generation for each day is unique, so that if a password is given out for a specific day, it changes the next day for security measures.

The administrator level user name is ADMIN. There is also a GUEST entry, with a null password, that is always present to gain access to Level 1.

Related BYE, USERS, DOY, COMM
Restrictions If no user passwords have been entered, this command is not listed in help.

## MSG

Use this command to access the messaging facilities.
Level $0 \quad$ Not applicable

Level 1 Not applicable
Level 2 MSG "message to send"
Use this command to broadcast a message on all active communication sessions.
The maximum length of each message is 60 characters.

## 푼 Note ... <br> The MSG is implemented as an event. It displays a full message in an autonomous event. But, it only saves 20 characters in the event log when a user tries to query it later.

Level 3 Same as Level 2 operation
Level 4 Same as Level 3 operation
Remarks The string must be entered
Related None
Restrictions None

## MTIE

Use this command to display the MTIE data from a selected input port.
Level $0 \quad$ Not applicable
Level 1 MTIE xAy-z [\{A | B \}] startdate [starttime] [stopdate [stoptime]]
MTIE xAy-z [\{A | B \}] starttime [stopdate] [stoptime]
MTIE xAy-z [\{A | B $\}$ ] HISTORY [count]
where:
$\mathrm{A} \mid \mathrm{B}=\mathrm{CLK} \mathrm{A}$ or CLK B; the default is the selected clock output.
starttime This option is used to specify the start time of a specific period of time to be displayed.
stopdate This option is used to specify the date ending a specific period of time to be displayed.
stoptime This option is used to specify the stop time of a specific period of time to be displayed.

If the starttime, stopdate, and stoptime are not specified the system defaults to a 24 hour period.

HISTORY [count] Displays the one-day MTIE history for the last number of days specified in the count parameter.

This command displays the MTIE information calculated on the input module with a specified clock. A start time and stop time are required to perform an MTIE calculation. If these are not specified in the command line, the start time defaults to the last 24 hours, the stop time defaults to the current time.

Note ...
If you specify times and dates, the MTIE that occurred after the starting date and time and before the ending date and time displays.

Specified dates have the format yyyy-mm-dd, and specified times have the format hh:mm:ss. Specified dates and times are not provided in ISO timestamp format, and must be separated by a space. Starttime and stoptime both default to the current time of day. Stopdate defaults to the current date. Startdate defaults to the current date, minus 24 hours.

## MTIE xAy-z [\{A| B \}] HISTORY [count]

A| B specifies Clock A or Clock B. The default is the selected clock output. This command displays the one-day MTIE history for the last one to 100 days.

Level 2 Same as Level 1 operation
Level 3 Same as Level 2 operation
Level 4 Same as Level 3 operation
Remarks Since MTIE involves intensive calculations, you can only specify one port.
Related None
Restrictions None
Example:

## SSU_2000+>mtie 1A10-02

```
MTIE for 1A09-01, on Clock A:
Start Time: 2001-06-24T19:00:00
Stop Time: 2001-06-25T18:20:00
The MTIE ( 0.05 sec) is 5
The MTIE ( 0.10 sec) is 5
The MTIE ( }1.00\textrm{sec})\mathrm{ is }
The MTIE ( }10.00 sec) is 
The MTIE ( }100.00 sec) is 1
The MTIE ( }1000.00 sec) is 1
The MTIE ( }10000.00\textrm{sec})\mathrm{ is 22
The MTIE (100000.00 sec) is 22
2001-06-25T18:20:49 1A05 Rep Pos Set by Rec, Information Locked, TL1A
```


## NTP

Use this command to provide access to the NTP in the unit. It can run as a server application, a client application, and in broadcast mode. The server always runs and the client and broadcast modes are enabled independently by assigning an address and setting a timer.

Level 0: NA
Level 1: $\quad$ NTP
Displays the NTP data: root delay, root dispersion, peer delay, peer dispersion, and peer offset.
Level 2: $\quad$ Same as level 1 operation.
Level 3: NTP ADDPEER \{CLIENT| BROADCAST| BCLIENT\} ip_dotted_address
NTP DELPEER ip_dotted_address
NTP CLRALL
NTP BTIMER \{32|64|128|256|512|1024\}
The above options are:
ADDPEER Add NTP peers (servers) to enable broadcast or client mode
CLIENT The IP for NTP server in client mode
BROADCAST The subnet mask for broadcasting mode
BCLIENT The IP for NTP server in broadcast client mode
DELPEER Removes NTP servers from the peer table
CLRALL Clear all the NTP peer addresses in the unit
BTIMER Set the broadcast timer for 32/64/128/256/512/1024 seconds interval

Level 4: $\quad$ Same as level 3 operation
Remarks: None
Related: None
Restrictions: The maximum number of peers is three. Users can assign a newly created peer to client or broadcast. Normally two peers are used for clients and one peer is for broadcasting (depending upon user requirements).

## NAME

Use this command to view and set the unit name.
Level $0 \quad$ Not applicable
Level $1 \quad$ NAME
Use this command to display the unit name.
Level 2 Same as Level 1 operation
Level 3 NAME unit_name
Sets the current unit name. You can use up to 20 characters for the unit name.This name is for identification purposes only.
Level 4 Same as Level 3 operation
Remarks The name displays as part of the prompt
Related Valid names must start with a letter. If TL1 is to be used, care must be taken in the assignment of the unit name as it is the Target Identification (TID) for that mode.
Restrictions ..... None

## OUTPUT

Use this command to view or set the output module status.
Level $0 \quad$ Not applicable
Level 1 OUTPUT [xAy]
If you do not provide a parameter, all the output module status information in the unit displays. If you provide an output address, the output status and setup information for that output module displays.

- Status Information: Output module status, selected clock, all four clock statuses, redundant partner, output PQL value, and output port status
- Setup Information: Framer type, zero suppression (On or Off), minimum clock level, PLL mask (On or Off)
- If DS1: line length
- If E1: CRC (On or Off), SSM bit position (4-8)
- The alarm level is handled by the ALARM command. The alarm elevation time is handled by ELEVTIME command.


## Example:

SSU_2000->output

```
2001-05-24T18:29:00Z ID: SSU2000 Name: SSU 2000
OUT STA Clk Clk Stat Port Status 1 1 1 1 1 1 1 1 1 1 2
Loc# Sta Sel A B C D Rednt M/S Pql 1 2 3 4 5 6 7 8 9 0 1 2 3 4 5 6 7 8 9 0
---- --- --- -------- ----- --- --- ---------------------------------------------------
2A01 Ok A /Y/Y/Y/Y None 2 / / / / / / / / / / / / / / / / / / / /
```



```
2A03 Ok A /Y/Y/Y/Y None 2 / / / / / / / / / / / / / / / / / / / /
2A04 Ok A /Y/Y/Y/Y None 2 / / / / / / / / / / / / / / / / / / / /
2A05 Ok A /Y/Y/Y/Y None 2 / / / / / / / / / / / / / / / / / / / /
2A08 Ok A /Y/Y/Y/Y None 2 / / / / / / / / / / / / / / / / / / / /
3A08 Ok A /Y/Y/Y/Y None 2 / / / / / / / / / / / / / / / / / / / /
3A11 Ok A /Y/Y/Y/Y 3A12 (S) 2 / / / / / / / / / / / / / / / / / / / /
3A12 Ok A /Y/Y/Y/Y 3A11 (M) 2 / / / / / / / / / / / / / / / / / / / /
1A06 Ok A /Y/Y/Y/N 1A07 (M) NA / / / / / / / / / / / / / / / / / / / /
1A07 Ok A /Y/Y/Y/N 1A06 (S) NA / / / / / / / / / / / / / / / / / / / /
```

Level 2 Same as Level 1 operation
Level 3 Same as Level 2 operation, with the following additions:
OUTPUT xAy $\{$ ESF | D4| CCS| CAS $\}$
OUTPUT xAy-z[\&\&z] \{ENABLE| DISABLE\}
OUTPUT xAy-z[\&\&z] \{133FT| 266FT| 399FT| 533FT| 655FT\}
OUTPUT xAy $\{\mathrm{CRC} \mid \mathrm{ZS}\}\{\mathrm{ON} \mid$ OFF $\}$
OUTPUT xAy SSM $\{4|5| 6|7| 8\}$
OUTPUT xAy LEVEL \{ACQ| LOCK\}
OUTPUT xAy BYPASS \{ON| OFF\}
OUTPUT xAy-z[\&\&z] DUTYCYCLE_CC \{63/37| 50/50\}
OUTPUT xAy-z[\&\&z] COMP_CC\{0ft $|\mathbf{5 0 0 f t}| \mathbf{1 0 0 0 f t}|\mathbf{1 5 0 0 f t}| \mathbf{2 0 0 0 f t}|\mathbf{2 5 0 0 f t}| \mathbf{3 0 0 0 f t} \mid \mathbf{3 5 0 0 f t}\}$
OUTPUT xAy FLTMODE_2048 \{ON| OFF| AUTO\}
Changes settings of a given output module
Options are:
ESF/D4 Use this option to set the T1 framing mode: ESF or D4.
CCS/CAS Use this option to set the E1framing mode: CCS or CAS.
ENABLE Use this option to enable output ports.
DISABLE Use this option to disable output ports.
$133 \mathrm{FT}|266 \mathrm{FT}| 399 \mathrm{FT}|533 \mathrm{FT}| 655 \mathrm{FT}$
Sets the line-length parameters for the output line driver.
CRC $\{\mathbf{O N} \mid \mathbf{O F F}\} \quad$ Enables or disables the CRC setting$\mathbf{Z S}\{\mathbf{O N} \mid \mathbf{O F F}\} \quad$ Enables or disables the zero suppression settingSSM $\{4|5| \mathbf{5}|7| \mathbf{8}\} \quad$ Sets the E1 SSM bit Position

## LEVEL \{ACQ| LOCK $\}$

Sets the minimum clock level to be ACQUIRE or LOCK mode. The output module turns off the output port if the level is below the minimum clock level.

BYPASS $\{\mathbf{O N} \mid \mathbf{O F F}\}$ Enables or disables the bypass mode to support Clock C
DUTYCYCLE_CC Sets the Composite Clock output 63/37 or 50/50 duty cycles

COMP_CC
Sets current line compensation for the Composite Clock output

FLTMODE_2048 Allows the user to turn the output on or off when the output level exceeds 2.1 v threshold

Level 4 Same as Level 3 operation
Remarks None
Related SETUP, STATUS
Restrictions None

## PBO

Use this command to gain access to the phase buildout ( PBO ) in the input module.

Level 0: NA

Level 1: PBO

Display the PBO current mode from each input
Level 2: $\quad$ Same as Level 2 operation.
Level 3: $\quad$ PBO [DISABLE| REPORT| EVENT| NONE]
The options are:
DISABLE PBO disabled

## REPORT PBO Enabled, the PBO events sent out and displayed, but not stored in the COMM event buffer

EVENT $\quad$ PBO Enabled, the PBO events sent out and displayed, but not
stored in the COMM event buffer

NONE PBO Enabled, but no PBO events displayed

Level 4: $\quad$ Same as level 3 operation
Remarks: None

Related: INPUT, PHASE

Restrictions: None

## PHASE

Use this command to access phase history data.
Level $0 \quad$ Not applicable
Level $1 \quad$ PHASE [xAy[-z]] [\{A| B $\}$ ] $\{\mathbf{T 1}|\mathbf{T 1 0 0 |}| \mathbf{T 1 K} \mid \mathbf{T 1 0 K}\}[$ count]
Use this command to view the $100 / 1,000 / 10,000$ seconds phase history information. One second phase is not stored in phase history. If you do not provide a parameter, phase information displays for the selected clock to all inputs that last stored the point.

Example:

## SSU_2000->phase

```
The current phase values with T1:
1A03-01 PhA:2001-05-24T18:29:00, 3
1A04-01 PhA:2001-05-24T18:29:09, 1
1A04-02 PhA:2001-05-24T18:29:09, 1
1A04-03 PhA:2001-05-24T18:29:09, 3
1A05-01 PhA:2001-05-24T18:29:12, 5
1A09-01 PhA:2001-05-24T18:29:12, 1
1A09-02 PhA:2001-05-24T18:29:12, 2
1A09-03 PhA:2001-05-24T18:29:12, NA
1A10-01 PhA:2001-05-24T18:29:13, 1
1A10-02 PhA:2001-05-24T18:29:13, 3
1A10-03 PhA:2001-05-24T18:29:13, 2
1A11-01 PhA:2001-05-24T18:29:14, NA
1A11-02 PhA:2001-05-24T18:29:14, 2
1A11-03 PhA:2001-05-24T18:29:14, NA
```

Level 2 Same as Level 2 operation, with the following additions:

## PHASE [xAy[-z]] ZERO [\{A|B\}]

Use this command to zero the phase error for the desired input port. If you do not provide a parameter, all inputs on both clocks are zeroed.

Level 3 Same as Level 2 operation
Level 4 Same as Level 3 operation
Remarks None
Related STATUS, INPUT
Restrictions None

## PING

Use this command to view network ping (diagnostic) capabilities.

Level $0 \quad$ Not applicable
Level 1 Not applicable
Level 2 PING ip_dotted_address
Use this command to determine if the unit is connected to the network. This command transmits a packet to the specified address and waits for a response. If a response is received, the unit displays a successful command completion message. If no response is received, the unit times-out and prints an unsuccessful command completion message.

Level 3 Same as Level 2 operation
Level 4 Same as Level 2 operation
Remarks No name server is available. The Internet Protocol (IP) address is formatted as a decimal dotted address.

Related None

Restrictions None

## PQLTABLE

Use this command to display or change user-defined Priority Quality Level (PQL) code and text string.

Level $0 \quad$ Not applicable
Level 1 PQLTABLE
Use this command to displays the PQL table setting.
Level 2 Same as Level 1 operation
Level 3 Same as Level 2 operation, with the following additions:

## PQLTABLE FACTORY

## PQLTABLE pql\# [\{DS1| E1\}] UNUSED

PQLTABLE pql\# [\{DS1| E1\}] [SSM n] [DESC str] [STD \{ON| OFF \}]
Use this command to read or set current PQL translation table information. This table provides the translation from the internal Priority Quality Level (PQL) to the Synchronization Status Message (SSM) for the various framing types.

Options are:

FACTORY Use this option to set factory defaults for the table. Both DS1 and E1 are affected.

Pql\# $\quad$ PQL number for the entry. The range is 1 to 16.
DS1 |E1 Use this option to specify which entry to affect. If you do not specify this information, both entries are assumed.

UNUSED Marks this entry as unused in the table

SSM $n \quad$ Use this option to set the SSM value to use for the framing type by specifying a hex number, preceded by $0 \boldsymbol{x}$.

DESC str Use this option to set the descriptive text string for this entry. Use a maximum of 14 characters. You can enclose the string in double quotes to allow entry of spaces and lower-case letters.

STD $\{\mathbf{O N} \mid \mathbf{O F F}\}$ Use this option to set or clear this entry as the standard input type. Only standard entries are matched for input.

Level 4 Same as Level 3 operation
Remarks None

## Related None <br> Restrictions None

Example:
SSU_2000->pqltable

$110 \times 22$

13 0x28 s St4
$0 \times 0 \mathrm{~F}$
14 0x40 s Reserved 0x0F

16 0x7E Unassigned

0x0F Unassigned

## REF

Use this command to access the input reference selection modes and settings.
Level $0 \quad$ Not applicable
Level 1 REF
Use this command to display the current input reference port and selected clock.
Level 2 Same as Level 1 operation
Level 3 Same as Level 2 operation, with the following additions:
REF xAy-z
REF $\{A R|A S| O F F\}$
REF \{PRIORITY| PQL\}
Use the first command REF xAy-z to select a given input port as current input reference.

## ET NOTE ..

If the clock module is already selected as an input reference and is not in AS OFF mode, this command has no effect. If both clocks are gone or in warm-up mode, this command can set an initial input reference port used as the Clock $C$ pass through. Other commands allow you to set input switch methods and input selection modes.

Options are:
\{AR\} Use this option to enable the input AutoReturn switch mode.
\{AS\} Use this command to enable the input AutoSwitch switch mode.
\{OFF \} Use this command when no switch is used.
PRIORITY Use this option to set the PRIORITY as the input selection mode.

[^2]
## 品 NOTE ... <br> Input reference selection order proceeds from highest (1) to lowest (16) PQL valid input port. If there are equal PQL values, then the priority is used to distinguish between them.

PQL Sets the PQL value as the input selection mode
Level 4 Same as Level 3 operation
Remarks None
Related INPUT, CLK, STATUS

Restrictions None
Example:
SSU_2000->ref

2001-06-18T21:29:56Z ID: SSU2000 Name: SSU_2000
Input Reference: 1A03-01
Bypass Clock C Selected: 1A04-01

Clock Selected: 1A01

## RESET

Use this command to reset the clock module through Comm Module.
Level 0: NA
Level 1: NA
Level 2: NA
Level 3: $\quad$ RESET $\{\mathbf{x A y}\}$
Resets a given clock module. It must have an operand to indicated Clock A or Clock B. Any other operand is invalid. This command requires the whole entry 'RESET' be entered to verify that the user really wants to restart that module. This command requires a confirmation (YES | NO). If confirmation failed, it takes no action.

Level 4: $\quad$ Same as level 3 operation
Remarks: None
Related: RESTART
Restrictions: This command uses the COMM module PLD's CLK A/B reset bit to reset the clock module. The software is required to hold the RESET bit for at least for 4 seconds and then writes a zero for that RESET bit.

## RESTART

Use this command to restart the software for a specified module.
Level $0 \quad$ Not applicable
Level 1 Not applicable
Level 2 Not applicable
Level 3 RESTART [xAy]

Use this command to restart the module. If you do not provide a parameter, the command refers to the Communications Module.

This command requires the whole entry RESTART to be entered to verify that you want to restart the module. This command requires a confirmation (YES | NO ). If confirmation fails, no action is required.

Level 4 Same as Level 3 operation
Remarks None

Related None

Restrictions This command is based on the target module. It has the SPI software RESTART command support. This command assumes that the target module is working properly. If the target module does not work, this command has no effect.

## SETUP

Use this command to view the current settings from non-volatile RAM in the entire unit. This includes any user settable information that is currently stored in NVRAM.

The main purpose of this command is to allow for a dump of current configuration of a unit so that you can compare site configurations. In addition, this command allows for storage and restoration of user settings, and the restoration of factory settings.

Level $0 \quad$ Not applicable
Level $1 \quad$ SETUP [xAy]
If you do not specify a parameter, all setup information of every module in the unit displays. If a specified address operand is provided, setup detail information for the target module displays. Module alarm Level is handled by the ALARM command. The alarm elevation time is handled by the ELEVTIME command. For each target module, refer to INPUT, CLK, or OUTPUT for a description.

■ If BUFFER is specified as the module, the command displays nothing.

- If the Communications Module is specified as the module, the command displays: IP address, IP mask, gateway address, communications port settings, total number of users stored, and maximum number of events stored. You can view events from the event log by using the EVENTS command. You can view alarms from each module by using the ALARM command.

Level 2 Same as Level 1 operation
Level 3 Same as Level 2 operation, with the following additions:

## SETUP [xAy] \{FACTORY| USER | SAVE \}

## SETUP 1A2 CONNECTION FACTORY

Options are:

FACTORY Use this option to restore the current setting from the factory settings. If addressed as COMM, connection and user list are not included.

USER Use this option to restore the current setting from user default settings. If addressed as COMM, connection and user list are not included.

SAVE Use this option to save the current setting as the user setting. If addressed as COMM, connection and user list are not included.

## CONNECTION FACTORY

Use this command to restore the current connection configuration in the Communications Module.

## Note ...

Restore the user list to factory settings by using the USER INITUSERTABLE command.

## Level 4 Same as Level 3 operation

# Remarks This command provides a way for the unit to save default settings that the user prefers for operation. The target module restores user defaults in the event that 

 current nonvolatile RAM information in the target module is lost.If user information is not present, or unusable, the target module restores the current factory settings. If the factory settings are also not usable, the software initializes non-volatile RAM with the current program defaults and transfers those setting into non-volatile RAM as the new factory settings.

Related INPUT, CLK, OUTPUT, EVENTS, ALARM
Restrictions None

## SNMP

Use this command to provide access to SNMP user list and provide the SNMP manager IP addresses.

Level 0: NA
Level 1: $\quad$ SNMP [USER | MANAGER]
If this command is used with any operand, it will display the valid SNMP user names and their associated access levels. It also displays the SNMP enabled/ disabled mode, and SNMP manager IP addresses.

USER Displays the valid SNMP user names and their associated access levels

MANAGER Displays the SNMP manager table contents
Level 2: $\quad$ Same as level 1 operation
Level 3: Same as level 2 operation, with the following additions:
SNMP [DISABLE | ENABLE]
SNMP TRAP \{ALARM $\mid$ ALL $\}$
The above options are:
DISABLE Disables the SNMP agent
ENABLE Enables the SNMP agent and allow MIB manager to see the view
TRAP Allows user set filter for SNMP trap (event port)

ALARM Only Alarm Traps sent out
ALL All Traps sent out
Level 4: $\quad$ Same as level 3 operation, with the following additions:
SNMP USER [\{INIT | ADD | MODIFY | DELETE \}]
SNMP MANAGER [INIT | \{ADD | DELETE $\}$ ] [ip_address]
The above options are:
USER SNMP User Table

INIT Clears the whole SNMP user table and only leave the built-in users in the systems. This option clear the table.

ADD
Adds the SNMP user "read community" to the system. If the user exists in the system this option exits with an error. After the read community string is entered, this command prompts for a write community. Write Community entries are echoed as ' $*$ '. Valid write community characters are all upper alphanumerical characters. After the write community string is entered, this command prompts for the user level.

MODIFY Modifies the write community and/ or the access level for the given user. If the user id is not in the system, this command exits with an error. Once the user is entered, this option performs identically to the 'ADD' option.

DELETE Deletes the user from system. If the user id is not in the system, this command exits with an error.
焐 Note ..Except for the first built-in entry, Read community: 'public' andWrite community: 'private', all user added community strings arecapital cases. Maximum is five SNMP user entries which includesthe built-in user.

Note:

## MANAGER SNMP Manager Table

INIT Initializes the SNMP Manager Table to all null IP address
ADD Adds an SNMP Manager IP address into the SNMP Manager Table
DELETE Deletes an SNMP Manager IP address from the SNMP Manager Table
Remarks: The length of read community string and write community string are limited to 10 characters to satisfy TL1 requirements.
Related: USERS
Restrictions: None

## STATUS

Use this command to view the current status of the unit. The status includes a count of the current active alarms and related information, which provides a quick view of unit performance.

| Level 0 | Not applicable |
| :--- | :--- |
| Level 1 | STATUS [xAy] |

If you do not provide a parameter, all status information from every module in the unit displays. If a specified address operand is provided, status detail information for that target module displays. For each target module, refer to INPUT, CLK, or OUTPUT for a description.

- If the Communications Module is specified, the bus connection profile displays within 900 seconds.
- If the buffer module is specified, nothing displays.

Level 2 Same as Level 1 operation
Level 3 Same as Level 1 operation
Level 4 Same as Level 1 operation
Remarks None
Related CLK, OUTPUT, INPUT, EVENTS
Restrictions None

## SYSTIME

Use this command to view the length of time in ISO format that the devices have had power applied.

| Level 0 | Not applicable |
| :--- | :--- |
| Level 1 | SYSTIME [xAy] |

If you do not provide a parameter, length of time for all modules displays.

## Level 2 Same as Level 1 operation

## Level 3 Same as Level 1 operation

Level 4 Same as Level 1 operation
Remarks None
Related None
Restrictions None
Example:

## SSU_2000->systime

```
2001-06-18T21:31:57Z ID: SSU2000 Name: SSU_2000
1A01 0T09:13:35
1A02 5T03:25:59
1A03 4T04:06:37
1A04 3T06:26:05
1A05 4T04:05:48
1A08 4T03:30:10
1A09 9T01:43:29
1A10 9T01:43:31
1A11 9T01:43:32
1A12 0T09:12:35
2A01 9T01:30:59
2A02 0T05:32:39
2A03 9T01:30:53
```


## TDEV

Use this command to view TDEV information from the selected input port.

## Level $0 \quad$ Not applicable

Level 1 TDEV xAy-z [\{A|B\}] startdate [starttime] [stopdate [stoptime]] TDEV xAy-z [ $\{\mathrm{A} \mid \mathrm{B}\}]$ starttime [stopdate] [stoptime]

Use this command to display the TDEV information calculated on the input modules. A|B specifies Clock A or Clock B. The default is the selected clock output.

To perform a TDEV calculation, start and a stop time are required. If none are specified in the command line, the time defaults to the last 24 hours. If the stop time is not specified, the current time is assumed.

This command displays the returned TDEV values and the window sizes for which they are valid. The command also displays the start and stop time for TDEV calculation.

Note ...
If you specify times and dates, TDEV displays that occurred after the starting date and time and before the ending date and time. Specified dates have the format yyyy-mm-dd, and specified times have the format hh:mm:ss.

Specified dates and times are not provided in ISO timestamp format, and are separated by a space. Start time and stop time both default to the current time of day. Stop date defaults to the current date. Start date defaults to the current date, minus 24 hours.

## TDEV xAy-z [\{A|B\}] HISTORY [count]

$\mathrm{A} \mid \mathrm{B}$ specifies Clock A or Clock B. The default is the selected clock output. This command displays the one-day TDEV history for the last one to 100 days.

Level 2 Same as Level 1 operation
Level 3 Same as Level 2 operation
Level 4 Same as Level 3 operation
Remarks Since TDEV is an intensive calculation, you can only specify one port.
Related None
Restrictions None

## Example:

## SSU_2000->tdev 1a9-1



## TIME

Use this command to access the timekeeping facilities.
Level $0 \quad$ Not applicable
Level 1 TIME

Use this command to view the current time within the unit. The time is displayed in the following format:

SSU_2000->time

T18:29:41Z

Level 2 Same as Level 1 operation
Level 3 TIME [T]hh:mm:ss
Use this command to set the current time within the unit.

Level 4 Same as Level 3 operation
Remarks None
Related DATE

Restrictions None

## USERS

Use this command to access the user list.

## Level $0 \quad$ Not applicable <br> Level 1 USERS <br> USERS [MODIFY]

The option is:
MODIFY This option changes password. This does not allow for change of user name or access level.

If this option is not provided, valid user names and their associated access levels display.

Level 2 Same as Level 1 operation
Level 3 Same as Level 2 operation
Level 4 Same as Level 3 operation, with the following additions:
USERS INITUSERTABLE
USERS [\{ADD | MODIFY | DELETE\}]
USERS LOGOFF comm_port
Options are:
INITUSERTABLEUse this option to clear the user table and leave only the built-in (default) system users. This option requires users to confirm their intention to clear the user table by entering the complete INITUSRTABLE command.

| ADD | Use this option to add a user to the system. If the user exists in the system, this option exits with an error. After the user ID is entered, you are prompted for a password. Password entries are echoed as ' $*$ '. Valid password characters are upper case, alphanumeric characters. After you enter the password, you are prompted for the user level (1 through 4). |
| :---: | :---: |
| MODIFY | Use this option to modify the password and access level for a user. If the user ID is not in the system, this command exits with an error. After you enter the user, this option performs identically to the ADD option. |

DELETE Use this option to delete the user from the SSU-2000 system. If the user ID is not in the system, this command exits with an error.
LOGOFF comm_portAllows the ADMIN user to free the other communications port so that it can be reconfigured. The user on the other port is immediately logged off, terminating any data that might have been entered. The valid port names are $\mathbf{L}, \mathbf{A}, \mathbf{B}$, TELA, TELB, TELC, TELD, TL1A, and TL1B.

## Remarks TL1 requires user names and passwords to be limited to 10 characters.

Related LOGIN, BYE
Restrictions None

## VER

Use this command to view the current software version for the Communications Module.
Level $0 \quad$ Not applicable

## Level 1 VER

This command views information as follows (assumes Communications Module Main Code Version A). Current Version:

- Main Code: A.01, 10FEB99

Level 2 Same as Level 1 operation
Level 3 Same as Level 1 operation
Level 4 Same as Level 1 operation
Remarks None
Related INFO

Restrictions None

## WHO

Use this command to view current ports that have users and the port connections.
Level $0 \quad$ Not applicable

## Level 1 WHO

Use this command to view who is logged on all active communication ports. User name and the communication port name display.

## Level 2 Same as Level 1 operation

## Level 3 Same as Level 1 operation

## Level 4 Same as Level 1 operation

Remarks None

Related USERS, LOGIN

Restrictions None
Example:

## SSU_2000->who

```
2001-06-18T21:37:59Z ID: SSU2000 Name: SSU_2000
You are ADMIN, with access level 4, connected to TELB
ADMIN is connected to COML
ADMIN is connected to COMA
ADMIN is connected to COMB
ADMIN is connected to TELA
```


## B. 4 NTP Support

The Network Time Protocol (NTP) is used to synchronize the time of a computer client or server to another server or reference time source, such as a GPS receiver or local timing source.

The SSU-2000 implements the NTP v. 3 (RFC 1305) version. It can run as a server application and a client application. In addition, a broadcast mode may be implemented as either a server or client. The NTP server always runs and the client and broadcast modes are enabled independently by assignment of addresses and setting of timers.

## B.4.1 SERVER MODE

The NTP server application always runs at port 123 (default NTP port) of the unit IP address and responds to requests for time in the NTP format. If the unit has time set from GPS then it indicates it is a primary time source by a 0 in the LI field and a 1 in the STR field. It the unit has time set by the client application then it indicates it is a secondary source by putting a 0 in the LI field and the source server STR + 1 in the STR field.

If the unit time has not been set by one of the above then it indicates that time is not valid by setting the LI field to 3 . Once the unit time has been set by either radio or client then $\mathrm{LI}=0$. Setting time by the keyboard sets (or leaves) $\mathrm{LI}=3$, since this is not an accurate time setting. If the time has been set, and the unit switches to a non-radio reference, then the STR becomes the PQL value for the selected reference input. If the unit enters holdover mode then the STR becomes the PQL of the selected Clock. (PQL is an internal representation of the received or assigned SSM value of the reference. See the SSU-2000 documentation for details.)

## B.4.2 CLIENT MODE

If a valid time server IP other than 0.0.0.0 (default) is assigned AND a client timer other than 0 (default) is set AND no radio time is available, then the unit will request time from port 123 of the assigned server IP at the designated time interval ( 32 to 1024 seconds). Once time is set by the client mode then the server will have $\mathrm{LI}=0$ and $\mathrm{STR}=$ the time source $\mathrm{STR}+1$. A second server IP may be entered and the NTP protocol will check both servers and select the best source per the NTP specifications. An NTP response received in the client mode overrides the time set by keyboard and changes the LI field to 0 as indicated above.

## B.4.3 BROADCAST MODE

If a broadcast address mask other than 255.255 .255 .255 (default) is assigned AND a broadcast timer other that 0 (default) is set, then the unit will send NTP time broadcasts to all devices within the subnet defined by the mask, at the designated time interval ( 600 to 86400 seconds). The LI and STR fields will be set as described in the server mode above.

If a broadcast client address other than 0.0.0.0 (default) is assigned, then the unit will listen for NTP broadcast from that address, and set time accordingly on receipt of the broadcast.

The ICS commands for setting up NTP are described as follows:
Command: NTP

Use this command to provide access to the NTP in the unit. It can run as a server application, a client application, or in a broadcast mode. The client and broadcast modes are enabled independently by assigning an address and setting a timer.

Operation:

Level 0: N/A
Level 1: $\quad$ NTP

Displays the NTP data: root delay, root dispersion, peer delay, peer dispersion, and peer offset.

Level 2: $\quad$ Same as level 1 operation.
Level 3: NTP ADDPEER \{CLIENT| BROADCAST| BCLIENT\} ip_dotted_address
NTP DELPEER ip_dotted_address

NTP CLRALL
NTP BTIMER \{32|64|128|256|512|1024\}

Where the above options are:


#### Abstract

ADDPEER: Add NTP peers (servers) to enable broadcast or client mode CLIENT: The IP address for the NTP server in client mode

BROADCAST: The subnet mask for broadcasting mode BCLIENT: The IP for NTP server in broadcast client mode DELPEER: Remove NTP servers from the peer table CLRALL: Clear all the NTP peer addresses in the unit BTIMER: Set the broadcast timer for 32/64/128/256/512/1024 seconds interval


Level 4: $\quad$ Same as level 3 operation.
Example: If the SSU2000 has a GPS module installed and the module is locked with satellites, it then has UTC time. The SSU-2000 is automatically an NTP SERVER at Stratum Level 1. When the system (with GPS module installed and UTC time) is a SERVER, it cannot operate as a client.

If the system is an NTP server, you can set your system for broadcast mode by the commands:

## NTP ADD BROADCAST XXX.XXX.XXX. 255 and NTP BTIMER NNNN

Note: The broadcast mode only works with class C networks with no gateway.
Example: If your unit IP address is 172.16.18.20, then the broadcast mask may be 172.16.18.255.

Your system can be configured as a client (if you don't have a GPS module installed) by the command:

## NTP ADD CLIENT XXX.XXX.XXX.XXX

This is the most common mode to get timing packets.
If your system is not a server, it can also be configured as a broadcast client to receive timing packets from a broadcast server by the command:

## NTP ADD BCLIENT XXX.XXX.XXX.XXX

For more information on these and other NTP commands, refer to Section B.2, TL1 Command Interface, and Section B.3, Interactive Command Set.

## B. 5 SNMP Protocol

The SSU-2000 SNMP is an SNMP V2 agent that requires Ethernet connectivity. If SNMP is present, port 161 becomes the port of standard SNMP interactive communications, while port 162 becomes the trap port. Since the SSU-2000 SNMP supports all exiting functions, full system control of the SSU-2000 is maintained through SNMP.

The SSU-2000 implements an SNMP agent. A Management Information Base (MIB) Browser or the SNMP Manager is used to access, retrieve, and query information defined by the MIB.

All reports, queries, autonomous messages, control, provisioning, and administration (except for communication port parameters, Set User ID/Password, Set IP assignments, Reset connection, and SNMP community settings) are available through SNMP. Refer to the Datum MIB Specification (I/N 12613250-000-2) for further information. Refer to Section B.2, TL1 Command Interface, and Section B.3, Interactive Command Set, for specific information on the following commands.

## B.5.1 User and Manager Tables

ICS and TL1 commands allow users to:

- Add up to five SNMP user names in the SNMP user table
- Delete/display SNMP user names (read community string) and their associated access levels


## TL1: SET-PRMTR-SNMP-USER: <br> [tid]::ctag::mode,[rd_community],[wr_community],[level];

and
RTRV-PRMTR-SNMP-USER:[tid]::ctag;
ICS: SNMP [USER | MANAGER]

- The factory default setting for read community string is "public"
- The factory default setting for write community string is "private"
- Disable/enable SNMP


## TL1: SET- PRMTR -SNMP-MODE:[tid]::ctag::[mode],[trap_filter];

and
RTRV-PRMTR-SNMP-MODE:[tid]::ctag;

## ICS: SNMP [DISABLE | ENABLE]

- Add/delete the SNMP manager IP address for traps (up to four managers in the SNMP manager table)

```
TL1: SET- PRMTR -SNMP-MANAGER:[tid]::ctag::mode,[ip];
    and
    RTRV-PRMTR-SNMP-MANAGER:[tid]::ctag;
ICS: SNMP TRAP {ALARM | ALL}
```


## B.5.2 Keep Alive Support

SNMP supports a "keep alive" mode based on a user-settable time. An event is generated to alert the upstream support system that the SSU-2000 and associated paths are functional. This mode is only supported in TL1 and SNMP sessions, not in ICS, Telnet, or Hyperterminal sessions. The factory default mode is set to Disabled.

TL1: SET-PRMTR-KEEPALIVE:[tid]::ctag::[t11_time],[snmp_time];
and
KEEPALIVE:[tid]::ctag;
ICS: KEEPALIVE [TL1 | SNMP] [time]

## B.5.3 Shelf Information

Each shelf and distribution unit's description, part number, and revision level can be displayed. Using the following commands with specific options the hardware information can be displayed. Refer to Section B.2, TL1 Command Interface, and Section B.3, Interactive Command Set, for more information.

## TL1: RTRV-CONF:[tid]:[aid]:ctag;

## ICS: CONFIG xAy \{REMOVE| DISABLE| ENABLE\}

## B.5.4 Software Information

Individual module software, part number, and associated revision level can be displayed. Using the following commands with specific options the software information can be displayed. Refer to Section B.2, TL1 Command Interface and Section B.3, Interactive Command Set, for more information.

TL1: RTRV-CONF:[tid]:[aid]:ctag;
ICS: CONFIG SW

## B.5.5 Communications Module Software Version

There are four main executables (software versions) available depending on the featuresadded functions required for the specific application, see Table B-9.

Table B-9. Communications Module Software Versions

| Part Number | Software Version |
| :--- | :--- |
| $24113012-000-0$ | Basic System Load |
| $24113012-001-0$ | Basic + NTP Support |
| $24113012-002-0$ | Basic + SNMP Support |
| $24113012-003-0$ | Basic + NTP and SNMP Support |

## IN THIS ApPENDIX ...

- Ordering Information
- Antenna Kits and Accessories
- Installing Antennas
- Optional Accessories


## Appendix C Antennas

This appendix provides information about optional antennas, antenna kits, part numbers and installation procedures for connecting GPS antennas to the SSU-2000 unit.

## C. 1 Ordering Information

To order any accessory, contact the Datum Sales Department at the following address and phone number, and supply the accessory name and part number ( $\mathrm{P} / \mathrm{N}$ ):

## Datum, Inc.

P.O. Box 14766

Austin, TX 78761-4766 USA
Attention: Sales Department
Phone: (512) 721-4325
Fax: (512) 251-9685
Monday-Friday
9:00 A.M - 5:00 P.M., CST
or E-mail: austinsupport@datum.com

## C. 2 Antenna Kits and Accessories

This section provides a list of antenna kits and accessories as well as descriptions and associated part numbers.

## C.2.1 GPS Antenna with Internal LNA

Datum offers three versions of GPS antennas with 26, 40, 48, and 68 dB internal Low Noise amplifiers (LNAs). These antennas, which are compatible with most commercial GPS receivers, receive, amplify, and filter the L1 (1575.42) signal from GPS NAVSTAR satellites. With the appropriate antenna (see Table C-1), inline amplifier, and coaxial cable, the antenna functions properly up to 305 meters from the radio receiver. The tables and figure listed below provide information about the antenna:

- Table C-1 lists the item number and provides a brief description of each antenna.
- Figure C-1 shows an illustration of the GPS antenna with internal LNA.
- Table C-2 provides specification information for GPS antenna with internal LNA.
- Table C-3 through Table C-5 lists the item numbers and provides a brief description of the antenna accessories available for the GPS series antennas.

Table C-1. GPS Antennas with Internal LNA

| Item Number | Description |
| :--- | :--- |
| $13813150-026-0$ | 26 dB L1 GPS Antenna Kit 10/200 ft. |
| $13813150-040-0$ | 40 dB L1 GPS Antenna Kit 100/400 ft. |
| $13813150-048-0$ | 48 dB L1 GPS Antenna Kit 250/600 ft. |
| $13813150-068-0$ | 68 dB L1 GPS Antenna Kit 650/1000 ft. |

Figure C-1 shows the GPS antenna with internal LNA.


Figure C-1. GPS Antenna with Internal LNA
Table C-2 provides specifications for GPS antennas with internal LNA.

Table C-2. GPS Antennas with Internal LNA Specifications

| Characteristic |  |
| :--- | :--- |
| Mechanical |  |
| Mounting | 4 holes, 1.75 in $\times 1.75$ in $(4.445 \mathrm{~cm} \times 4.445 \mathrm{~cm})$ centers, 0.25 in <br> $(0.635 \mathrm{~cm})$ mounting holes |
| Diameter | 3.5 in $((88.9 \mathrm{~cm})$ |
| Height | $12.94 \mathrm{in}(328.7 \mathrm{~cm})$, including pipe mount |
| Weight | $<3 \mathrm{lbs}(1.4 \mathrm{~kg})$ |
| Environmental |  |
| Temperature | $-40^{\circ} \mathrm{C}$ to $+75^{\circ} \mathrm{C}$ |
| Relative Humidity | $100 \%$ Non-Immersed |
| Altitude | $200 \mathrm{ft} .(60 \mathrm{~m})$ below sea level to $13,000 \mathrm{ft}.(3962 \mathrm{~m})$ above sea level |

## Table C-2. GPS Antennas with Internal LNA Specifications (Continued)

| Characteristic |  |
| :--- | :--- |
| Electrical |  |
| Power | 4.7 to $28 \mathrm{vDC}(5 \mathrm{vDC}$ Nominal) |
| Element | Right Hand Circular |
| Carrier | L1 (1545.42 MHz) |
| Bandwidth | 10 MHz |
| Noise Figure | $<2.5 \mathrm{~dB}$ |
| Output <br> Impedance | 50 ohms |
| Gain <br> Marine 26 <br> Marine 40 <br> Marine 50 | $26.5 \mathrm{~dB} \pm 3 \mathrm{~dB}$ <br> 40 dB minimum <br> 48 dB minimum |

Table C-3 through Table C-5 provides accessories for GPS antennas with internal LNA.

Table C-3. 26dB L1 GPS Antenna Accessory Kit

| Item Number | Description |
| :--- | :--- |
| $12013076-\mathrm{xxx}-0$ <br> ( $\mathrm{xxx}=$ length $)$ | Cable, LMR-400, 10 ft. to maximum of 190 ft . (Customer specified length) |
| $773000-0008$ | Transient Eliminator, 90 Volts, $1.5 \mathrm{GHz}, \mathrm{N}$-Type |
| $12013076-010-0$ | Cable, LMR-400, 10 ft., Right Angle |
| $400302-0500$ | Roll, 3M 2150 Weatherproof Tape |
| $12813080-000-0$ | Crimper Kit, LMR-400 (crimp tool, 2150 tape, LMR preptool, <br> 10 each crimp N-type connectors) |

## Table C-4. $\quad$ 40dB L1 GPS Antenna Accessory Kit

| Item Number | Description |
| :--- | :--- |
| $12013076-\mathrm{xxx-0}$ <br> (xxx $=$ length) | Cable, LMR-400, $70 \mathrm{ft}$. to maximum of 370 ft. <br> (Customer specified length) |
| $773000-0008$ | Transient Eliminator, 90 Volts, $1.5 \mathrm{GHz}, \mathrm{N}$-Type |
| $12013076-030-0$ | Cable, LMR-400, 30 ft., Right Angle |
| $551100-6013$ | Adapter, Right Angle Female to Right Angle Male |

## Table C-4. 40dB L1 GPS Antenna Accessory Kit (Continued)

| Item Number | Description |
| :--- | :--- |
| $12010210-000-0$ | Bracket Assembly, Antenna Mount Right Angle |
| $400302-0500$ | Roll, 3M 2150 Weatherproof Tape |
| $12813080-000-0$ | Crimper Kit, LMR-400 (crimp tool, 2150 tape, LMR preptool, <br> 10 each crimp N-type connectors) |

## Table C-5. 48dB and 68dB L1 GPS Antenna Accessory Kit

| Item Number | Description |
| :--- | :--- |
| $12013076-x x x-0$ <br> (xxx = length) | Cable, LMR-400, 220 ft. to maximum of 970 ft. (Customer specified length) |
| $773000-0008$ | Transient Eliminator, 90 Volts, $1.5 \mathrm{GHz}, \mathrm{N}$-Type |
| $12013076-010-0$ | Cable, LMR-400, 30 ft., Right Angle |
| $551100-6013$ | Adapter, Right Angle Female to Right Angle Male |
| $12010210-000-0$ | Bracket Assembly, Antenna Mount Right Angle |
| $570704-0001$ <br> $(68$ dB Output Only) | GPS L1 inline amplifier, Right Angle (required for lengths >650 ft.) |
| $400302-0500$ | Roll, 3M 2150 Weatherproof Tape |
| $12813080-000-0$ | Crimper Kit, LMR-400 (crimp tool, 2150 tape, LMR preptool, <br> 10 each crimp N-type connectors) |

## C.2.2 Transient Eliminators

Datum offers the FCC-250B-90-1.5NFNF Transient Eliminator for installations that require antenna coaxial lead-in protection. The FCC-250B-90-1.5NFNF Transient Eliminator passes DC power and frequencies in the 1.5 GHz range with non-downconverter L1 GPS antennas. In most installations, the transient eliminator mounts near the point at which the antenna lead enters the facility. Table C-6 provides the transient eliminator specifications.

Table C-6. FCC-250B-90-1.5NFNF Specifications

| Characteristic | Specification |
| :--- | :--- |
| Type | Gas |
| Response Time | $<2$ nanoseconds |
| Impedance | $50 \Omega$ |
| Insertion Loss | $<0.25 \mathrm{~dB} @ 1,575 \mathrm{MHz}$ |
| VSWR | $<1.6: 1 @ 1,575 \mathrm{MHz}$ |
| DC Breakdown Voltage | 90 Volts |

## Table C-6. FCC-250B-90-1.5NFNF Specifications (Continued)

| Characteristic | Specification |
| :--- | :--- |
| Dissipation Capacity | 10,000 Amperes, impulse $8 / 20 \mu \mathrm{sec}$ |
| Connector Type | N -Type |
| Temperature | $-55^{\circ} \mathrm{C}$ to $+70^{\circ} \mathrm{C}$ |
| Relative Humidity | $100 \%$ Non-immersed Altitude $200 \mathrm{ft} .(60 \mathrm{~m})$ below sea level to $13,000 \mathrm{ft}$. <br> $(3962 \mathrm{~m})$ above sea level |

## C.2.3 GPS L1 Inline Amplifier

The GPS L1 Inline Amplifier (item number 570704-0001) option used to boost the signal from the antenna for installation. The amplifier uses LMR-400 cables longer than 650 feet and receives power from the GPS radio receiver through the antenna coaxial cable connections. Table C-7 provides environmental, mechanical, and electrical specifications for the amplifier.

Table C-7. GPS L1 Inline Amplifier Specifications

| Characteristic | Specification |
| :--- | :--- |
| Environmental |  |
| Temperature | $-40^{\circ} \mathrm{C}$ to $+80^{\circ} \mathrm{C}$ |
| Mechanical |  |
| Connectors, (In/Out) | N -Type |
| Gain | $>20 \mathrm{~dB}, 25 \mathrm{~dB}$ typical |
| Dimensions, includes <br> connectors | Height: 1.12 inches <br> Width: 2.0 inches <br> Length: 3.5 inches |
| Dimensions, includes <br> connectors | Height: 28.5 mm <br> Width: 50.8 mm <br> Length: 88.9 mm |
| Electrical | +4.5 vDC to +30 vDC |
| Power | 10 mA, typical |
| Current | $50 \Omega$ |
| Input/Output Impedance <br> (bandwidth at 3dB points) | $>35 \mathrm{~dB}$ |
| Isolation |  |

## C.2.4 GPS L1 Inline Amplifier Assembly

This assembly (item number 11013077-000-0) mounted on an aluminum plate is designed with mounting holes to allow for several mounting configurations. The assembly consists of a GPS inline amplifier, a 90 v L1 Transient Eliminator, and an adapter for connectivity.

## C.2.5 Antenna Coaxial Cables

Datum provides several low-loss cable types, as well as LMR-400 with N-type connectors on both ends.

- Table C-8 lists the optional antenna coaxial cables
- Table C-9 lists the optional antenna coaxial cable crimper kits
- Table C-10 provides antenna cable specifications


## Table C-8. Optional Antenna Coaxial Cables

| Item Number | Description |
| :--- | :--- |
| $12012992-x x x-0$ | Cable, RG-213/U, with N-Type Connectors |
| $12012994-x x x-0$ | Cable, UHF/VHF (B-89913), with N-Type Connectors |
| $12012995-x x x-0$ | Cable, UHF/VHF (B-9913), with N-Type Connectors |
| $12013076-x x x-0$ | Cable, LMR-400 or equivalent, with N-Type Connectors |
| Contact your factory sales office for available cable lengths and specific cable <br> item number. |  |

Table C-9. Optional Antenna Coaxial Cable Crimper Kits

| Item Number | Description |
| :---: | :--- |
| $12813059-000-0$ | Crimp Kit for RG213 (10 each N-Type Connectors, <br> crimp tool, weatherproof tape) |
| $12813060-000-0$ | Crimp Kit for 9913 (10 each N-Type Connectors, <br> crimp tool, weatherproof tape) |
| $12813080-000-0$ | Crimp Kit for LMR-400 or equivalent (10 ea. N-Type <br> connector, crimp tool, weatherproof tape) |

## Table C-10. Antenna Cable Specifications

| Cable Type | Measured Loss <br> (@1.575 GHz dB <br> per foot) | DC Resistance <br> (ohms per foot) | Type Center <br> Conductor | Flammability |
| :--- | :--- | :--- | :--- | :--- |
| RG213/U <br> (Beldon 8267) | 0.093 dB | 0.0030 | Stranded 13 AWG | U/L CSA |
| RG213/U <br> (Beldon 8267) | 0.093 dB | 0.0030 | Stranded $2.62 \mathrm{~mm}^{2}$ | U/L CSA |
| UHF/VHF <br> (Beldon 9913) | 0.058 dB | 0.0027 | Solid 10 AWG |  |
| UHF/VHF <br> (Beldon 9913) | 0.058 dB | 0.0027 | $5.26 \mathrm{~mm}^{2}$ |  |
| UHF/VHF <br> (Beldon 89913) | 0.089 dB | 0.0027 | Solid 10 AWG | Plenum U/L <br> CSA |
| UHF/VHF <br> (Beldon 89913) | 0.089 dB | 0.0027 | $5.26 \mathrm{~mm}^{2}$ | Plenum U/L <br> CSA |
| LMR-400 | 0.051 dB | Shield -.00165 <br> Center -.00139 | $0.109 \mathrm{inch}^{\text {Solid }}$ |  |
| LMR-400 | 0.051 dB | Shield -.00165 <br> Center -.00139 | $0.27686 \mathrm{~cm}^{2}$ Solid |  |

## C. 3 Installing Antennas

This section provides complete installation procedures for GPS site preparation. Before beginning the installation, review Section, Antenna System Grounding and Cable Lead-In Protection, and gather the necessary tools and materials described.

## C.3.1 Antenna Connection Overview

The SSU-2000 chassis has two antenna connections located on the front panel. The antenna connections are made via isolated TNC connector J6 labeled ANTENNA-A and isolated TNC connector J7 labeled ANTENNA-B. The TNCs are DC isolated and AC bypassed to frame ground. These connections are used for radio receiver antenna connections only. The antenna connections (J6 and J7) are connected via the backplane to module slots 3 and 5. When installing GPS antennas, the installed modules must correspond to these connections (for instance, slot 3 to ANTENNA-A and Slot 5 to ANTENNA- B). Installation procedures for GPS antennas are outlined below. Table $\mathrm{C}-11$ outlines the antenna signal connections.

Table C-11. Antenna Signal Connections

| Signal Name | From | To |
| :---: | :---: | :---: |
| Ant-A | A3 P5-A | J6-A |
| Ant-A-RTN | A3 P5-B | J6-B |
| Ant-B | A5 P5-A | J7-A |
| Ant-B-RTN | A5 P5-B | J7-B |

## Antenna System Grounding and Cable Lead-In Protection

In addition to determining where to locate and mount the antenna and cabling, a grounding scheme should be developed. The purpose of the grounding scheme is to provide some protection against voltage surges and static discharge. If transient eliminators are used, they also need to be connected to the perimeter ground system or bulkhead entrance panel that is connected to the perimeter ground system.

CAUTION...
To ensure proper grounding, observe these precautions when installing the antenna:

- Allow no sharp bends in the ground conductors.
- Ensure that no painted surface insulates the transient eliminator or grounding clamps.
- Ensure that ground conductors are bonded to the metal enclosure box (if used) and do not enter through an access hole.
- Do not use soldered connections for grounding purposes.
- Secure all grounding connections with mechanical clamp type connectors.

Before installing the GPS antenna, decide upon a grounding scheme to use to provide protection against voltage surges and static discharge. Observe these guidelines:

- In general, follow local building codes when selecting a grounding scheme, wire size, and installation.
- Connect transient eliminators, if part of the grounding scheme, to earth ground through a conductor.

ㅍ Note ...
Do not connect the outside transient eliminator ground to the inside equipment rack ground. Doing so can defeat the protection afforded by the transient eliminator.

Datum makes no recommendation as to whether to install transient eliminators. Datum can provide suitable transient connectors as an option.

- Use \#10 AWG (minimum) copper ground wire.


## EI Note..

Larger ground conductors provide better transient elimination; that is, the larger the ground conductor, the less likely the chance of transients.

- Never connect antenna systems to the same earth ground connector as heating and cooling systems, elevator or pump motors, or other motors or machinery which can induce noise in the antenna system.


## Antenna Installation Tools and Materials

These standard tools and materials are not supplied in the antenna kit, but may be required for installing the GPS antenna. For a list of antenna kit contents, see Table C-1.

- Four each 0.25 inch ( 6 mm ) fasteners for installing the antenna floor flange
- Extra cable ties or acceptable cable clamps
- \#10 AWG (minimum) copper ground wire
- Eight foot ground electrode
- Custom mounting plates, U-bolts, masonry bolt, and so forth, as needed for mounting to a tower, roof, or wall of a building
- A cable puller may be required for installing the antenna coaxial cable
- Digital voltmeter (DVM)



## CaUtion ...

To prevent damage to connectors, use caution while pulling cable.

## C.3.2 GPS Antenna Installation Procedures

This section provides installation procedures for installing the GPS antenna.

## ㅍN $\quad$ Note ...

Follow local building electrical codes when installing the GPS antenna.

## C.3.2.1 Preparing to Install the GPS Antenna

Before beginning to install the antenna, determine a grounding scheme, and consider the factors that affect the location and environment chosen for the antenna installation. These factors are addressed in the warnings, cautions, and recommendations that follow.

## CaUtion ...

To avoid damage to the GPS antenna, do not place the antenna where high-power radio signals are beamed directly at the unit. Such signals can damage the preamplifier of the GPS antenna.

## Warning ...

To avoid serious injury to personnel or damage to equipment, exercise caution when working near high voltage lines. In particular:

- Use extreme caution when installing the GPS antenna near, under, or around high voltage lines.
- Follow local building electrical codes for grounding using the frame ground lugs on the SSU-2000 chassis.
- The in-line amplifier receives 5 vDC power from the GPS radio receiver, and is supplied on the center conductor of the LMR-400 or equivalent coaxial cable. If the application requires an in-line amplifier, mount the amplifier/plate assembly where the transient eliminator would normally be mounted.
- Datum does not recommend cutting the antenna cables provided in the GPS Antenna Kit.


## Recommendation ...

Consider the following location and environment influences before installing the GPS antenna:

- If possible, provide the antenna with an unobstructed 360degree view of the sky from the horizon.
- In general, do not allow obstructions that obscure the horizon (as viewed from the antenna) by more than 10 degrees.
- Locate the antenna well away from, and preferably in a plane above electrical equipment such as elevators, air conditioners, or other machinery.
- To reduce the risk of lightning damage, do not place the antenna at the highest point of the building.
- Locate the GPS antenna at least 12 feet from metallic objects, if possible.
- Locate the antenna high enough to avoid drifted snow.
- Locate the transient eliminator in a protected area to avoid contact with standing water.
- Locate the antenna within 30 feet of the point at which the antenna cable enters the building.
- Allow at least 10 feet of separation distance between GPS antennas.
- Surfaces above the plane of the unit that are between the antenna and the horizon can produce reflected (multi-path) signals, which can degrade the performance of the radio receiver.


## C.3.2.2 Cutting Antenna Cables



## Recommendation ...

Datum recommends that you coil excess cable to avoid gain mismatch between the GPS antenna and the radio receiver. Coiling the excess cable also allows you to use the factory-installed crimped connector.

## Recommendation ...

Datum does not recommend cutting the antenna cables provided in the GPS Antenna Kits. If you must cut the cables, please ensure that the following requirements are met.

Be aware of these cable and connector requirements before cutting antenna cables:

Cable Requirements - The total cable length from the radio receiver to the antenna must not be shorter than the minimum cable lengths indicated in the GPS Antenna Kits (see Table C-1).

Connector Requirements - The cables provided with the GPS Antenna Kit have factory installed crimped connectors. If you cut these cables, you must supply and add a connector. Datum recommends that you use only crimp-style N -type connectors in the Datum Crimper Kit for this application (see Table C-9).

## C.3.2.3 Selecting the Proper Gain Antenna

When installing the GPS radio receiver, it is important to select the proper gain antenna and coaxial cable that accounts for the insertion loss between the antenna and the radio receiver to avoid under-driving or over-driving the radio receiver antenna input. The gain required at 1575 MHz for a GPS radio receiver input is the manufacturer's specification for the radio receiver to acquire satellites, with some level of signal degradation allowed.

L1 Antenna gains are usually specified as the minimum effective gain. Such antenna gains can have 4.5-10 dB more signal strength at different satellite azimuths and elevations, depending on their reception pattern. The GPS engine requires a signal level at the antenna connector input of the chassis to be between 13.8 dB and 36.8 dB . This tolerance allows for the signal loss of the internal coaxial cable and connectors. The optimal signal level at the radio receiver input is 25.3 dB .

All antenna kits include the GPS L1 antenna, mounting pipe, floor flange, transient eliminator, pre-assembled coaxial cable (for antenna to transient eliminator), roll of 3M 2150 weatherproof tape, and a right angle adapter. All chassis, antennas, transient eliminators, and in-line amplifiers have N -type connectors.

All chassis, antennas, transient eliminators, and in-line amplifiers have N -type connectors.
All antenna kits supplied use LMR-400, or equivalent, low-loss coaxial cable. Other types of coaxial cable are available for GPS antenna applications; however, it is imperative that you calculate the specific cable loss to ensure a signal level between 13.8 dB and 36.8 dB at the antenna connector input. The L1 signal loss of LMR-400 is $1.67 \mathrm{~dB} /$ meter. The L1 signal loss of a 90 v transient eliminator is typically 0.25 dB .

## C.3.2.4 GPS Antenna With a Low Noise Amplifier, 26, 40, 48, or 68 dB

The Marine 26, 40, 48, or 68 dB GPS Antenna with a Low Noise Amplifier (LNA) receives the GPS signal from each satellite, and amplifies the $1,575 \mathrm{MHz}$ (L1) signal and feeds it to the SSU-2000 unit. The amplified L1 signal and 5 vDC power are carried over the coaxial antenna cable connecting the units. The antenna is housed in a weatherproof package suitable for permanent installation in an exposed location.

The antenna-to-radio receiver cable should be kept to the shortest reasonable length. For additional transient eliminator protection requirements, you can install a 250B-90 Gas Tube transient eliminator in series with the antenna coaxial cable.

## C.3.2.5 Installing the Transient Eliminator

If you are installing a transient eliminator, follow these guidelines:

- Transient eliminators should be installed in accordance with your antenna system grounding scheme.
- Mount the transient eliminator within 9 meters of the GPS antenna.
- If required, mount a second transient eliminator near the GPS antenna.

To install the transient eliminator:

```
## NOTE...
Step 6 in the following procedure cannot be done if you cut the cable (as described in Step 1).
```

1. If necessary, cut the coaxial cable and install mating connectors (see the Warning in Section C.3.2.2, Cutting Antenna Cables).
2. Using the DVM, measure the resistance between the center conductor and shield to verify that the center conductor and shield are not shorted together.
3. Connect the longer GPS antenna coaxial cable to the transient eliminator.
4. Connect the ground wire between the transient eliminator and the proper grounding zone (building ground, master ground bar, or other) for the mounting location.

Recommendation ...

Datum does not recommend soldered connections for grounding purposes. All grounding connections should be secured with mechanical clamp connectors.
5. Wrap the connectors with weatherproof tape for added protection.
6. Verify that the antenna coaxial cable center conductor is not shorted to the shield of the cable.

## C.3.2.6 Cabling the GPS Antenna

To route the coaxial cable of the mounted antenna (see Figure C-1):

1. Loosen the four screws securing the top of the antenna in place to gain access to the connector.
2. Route the shorter antenna coaxial cable from the antenna through the floor flange (in the lower half of the antenna base) to the unit.

## 

## Caution ...

To avoid damage to the connectors, do not use the connectors to pull the cable. If at all possible, avoid bundling the coaxial cable with other cables (and possible noise sources). Use appropriate cable-pulling devices when pulling the coaxial cable through conduit or a weather head.
3. Connect the cable to the antenna and run the cable from the antenna through the slot of the floor flange.


## Caution ...

To avoid damage to internal solder connections, do not over-tighten the connector.
4. Replace the four screws to secure the top of the antenna in place with the cable connected.

## C.3.2.7 Mounting the GPS Antenna

To mount the GPS antenna:

- To mount the antenna to any stable flat surface, use the floor flanges supplied in the GPS Antenna Kit. The mounting surface and the local building codes determine the type and number of fasteners, screws, bolts, and so forth, that may be required.
- To mount the antenna on the side of a building or tower, use the optional right angle mounting bracket (Item Number 12010210-000-0, available from Datum).
- To secure the coaxial cable to the mast, use one or more 8 " cable ties or appropriate cable clamps.


## C.3.2.8 Connecting the GPS Antenna

Before connecting the GPS antenna to the SSU-2000 unit, see Section Section C.3.2, GPS Antenna Installation Procedures. Then, follow the instructions below.

1. Before connecting the antenna coaxial cable to the radio receiver, test the DC resistance between the center conductor and the shield using an ohmmeter. The reading should be greater than 1000 ohms but less then 40 Megohms for an active GPS antenna.

If the actual reading is incorrect, you may have a shorted or open cable or transient eliminator (if installed). Therefore, apply the same measurements directly to the GPS antenna. This requires disconnecting the antenna cable at the antenna.

旦 ${ }^{3}$ NOTE ..
The open-circuit range of an individual ohmmeter can cause readings to vary among meters.
2. Secure the free end of the antenna cable to the antenna connector using the right angle adapter provided with the antenna cable.

Recommendation ...

Datum recommends coiling excess cable to avoid gain mismatch between the GPS antenna and the radio receiver. Coiling the excess cable also allows you to use the factory-installed crimped connector.

## C.3.3 Antenna Installation Completeness Checklist

To verify that antenna installation is complete:

- Verify that all power and ground wires are installed correctly and securely.
- Verify that all input and output cables are properly installed.
- Verify that all antenna connectors are secure, tight, and weatherproofed.


## C. 4 Optional Accessories

Table C-12 provides a list of optional accessories which may be used to mount or install the SSU-2000.

Table C-12. Optional Accessories

| Item Number | Description |
| :--- | :--- |
| $00413102-001-1$ | Bracket, rack ear, 23", 2 each required (not included with unit) |
| $22013085-000-0$ | 9 pin-D wire-wrap adapter (not included with unit) |
| $551026-0038$ | Cable RS-232 shielded DB9P to DB9S, $5 \mathrm{ft}.(1.5 \mathrm{~m})$ |

## IN this Appendix ...

- Signal Names and Definitions
- Shelf Module Slot Addressing and Size Assignments
- I/O Connector Grounding


## Appendix D Connector Pinouts

This appendix describes the pinouts for each of the connectors on the SSU-2000 chassis. All the connectors in the following sections are located on the rear panel of the SSU-2000, as shown in Figure D-1.


Figure D-1. SSU-2000 Rear Panel

## D. 1 Signal Names and Definitions

## D.1. $1 \quad$ Power and Ground

Figure D-2 shows the power and ground connections for the SSU-2000 chassis. Table D-2 outlines signal names and definitions for power and ground.


Figure D-2. Power and Ground Connection Pinouts (Covers Removed)

Table D-1. Signal Names and Definitions for Power and Ground

| Name | Description |
| :--- | :--- |
| APWR | -48 V from Power Bus A |
| ARTN | -48 V Return from Power Bus A |
| BPWR | -48 V from Power Bus B |
| BRTN | -48 V Return from Power Bus B |
| LG | Logic Ground, Return for Non-Isolated Signals |
| FG | Frame Ground Safety Ground for Shelf |

## D.1.2 Communication Interfaces

Figure D-3 shows the communications interfaces on the rear panel of the SSU-2000.
Table D-2 describes the signal names, definitions, and pinouts of Communications connectors.


Figure D-3. Communications Interface Connectors Pinout

Table D-2. Signal Names and Locations of Comms Interfaces

| Name | Description | Connector-Pin |
| :--- | :--- | :---: |
| DCD-A | Serial Port A, Data Carrier Detect Control Line | $\mathrm{J} 4-1$ |
| DSR-A | Serial Port A, Data Set Ready Control Line | $\mathrm{J} 4-6$ |
| RXD-A | Serial Port A, Received Data | $\mathrm{J4-2}$ |
| RTS-A | Serial Port A, Request to Send Control Line | $\mathrm{J4-7}$ |
| TXD-A | Serial Port A, Transmitted Data | $\mathrm{J4-3}$ |
| CTS-A | Serial Port A, Clear to Send Control Line | $\mathrm{J4-8}$ |
| DTR-A | Serial Port A, Data Terminal Ready Control Line | $\mathrm{J4-4}$ |
| RI-A | Serial Port A, Ring Indicator Control Line | $\mathrm{J4-9}$ |
| RTN-A | Serial Port A, Signal Return | $\mathrm{J4-5}$ |
| DCD-B | Serial Port B, Data Carrier Detect Control Line | $\mathrm{J5-1}$ |
| DSR-B | Serial Port B, Data Set Ready Control Line | $\mathrm{J5-6}$ |
| RXD-B | Serial Port B, Received Data | $\mathrm{J5-2}$ |
| RTS-B | Serial Port B, Request to Send Control Line | $\mathrm{J5-7}$ |
| TXD-B | Serial Port B, Transmitted Data | $\mathrm{J5-3}$ |
| CTS-B | Serial Port B, Clear to Send Control Line | $\mathrm{J5-8}$ |
| DTR-B | Serial Port B, Data Terminal Ready Control Line | $\mathrm{J5-4}$ |
| RI-B | Serial Port B, Ring Indicator Control Line | $\mathrm{J5-9}$ |
| RTN-B | Serial Port B, Signal Return | $\mathrm{J5-5}$ |

Table D-2. Signal Names and Locations of Comms Interfaces (Continued)

| Name | Description | Connector-Pin |
| :--- | :--- | :---: |
| TX + | Ethernet 10-Base-T, Positive Side of Transmitted Data | J3-1 |
| TX- | Ethernet 10-Base-T, Negative Side of Transmitted Data | J3-2 |
| RX + | Ethernet 10-Base-T, Positive Side of Received Data | J3-3 |
| RX- | Ethernet 10-Base-T, Negative Side of Received Data | J3-6 |

## D.1.3 Local OSC and Antennas

Table D-3 outlines signal names and locations of local Oscillators and antennas.


Figure D-4. Local Oscillator and Antenna Connectors

Table D-3. Signal Names and Locations of Local OSC and Antennas

| Name | Description | Connector-Pin |
| :--- | :--- | :---: |
| LO-A+ | Local Oscillator A, Positive Side of Signal | J1-A (Ctr) |
| LO-A- | Local Oscillator A, Negative Side of Signal | J1-B (Shld) |
| LO-B+ | Local Oscillator B, Positive Side of Signal | J2-A (Ctr) |
| LO-B- | Local Oscillator B, Negative Side of Signal | J2-B (Shld) |
| ANT-A | Antenna A, Center Conductor (Received Signal \& Ant. Power) | J6-A (Ctr) |
| ANT-A-RTN | Antenna A, Return | J6-B (Shld) |
| ANT-B | Antenna B, Center Conductor (Received Signal \& Ant. Power) | J7-A (Ctr) |
| ANT-B-RTN | Antenna A, Return | J7-B (Shld) |

## D.1.4 Alarm Contact Closures

Figure D-5 illustrates the alarm closure connectors on the rear panel of the SSU-2000 chassis. Table D-4 outlines signal names, definitions, and locations of alarm contact closures.


Figure D-5. Alarm Connector Pinout

Table D-4. Signal Names and Locations of Alarms

| Name | Description | Connector-Pin |
| :--- | :--- | :---: |
| LCRT-NO | Local Critical Alarm, Normally Open Contact | TB1-1 |
| LCRT-COM | Local Critical Alarm, Common Contact | TB1-2 |
| LCRT-NC | Local Critical Alarm, Normally Closed Contact | TB1-3 |
| LMAJ-NO | Local Major Alarm, Normally Open Contact | TB1-4 |
| LMAJ-COM | Local Major Alarm, Common Contact | TB1-5 |
| LMAJ-NC | Local Major Alarm, Normally Closed Contact | TB1-6 |
| LMIN-NO | Local Minor Alarm, Normally Open Contact | TB1-7 |
| LMIN-COM | Local Minor Alarm, Common Contact | TB1-8 |
| LMIN-NC | Local Minor Alarm, Normally Closed Contact | TB1-9 |
| RCRT-NO | Remote Critical Alarm, Normally Open Contact | TB2-1 |

## Table D-4. Signal Names and Locations of Alarms (Continued)

| Name | Description | Connector-Pin |
| :--- | :--- | :---: |
| RCRT-COM | Remote Critical Alarm, Common Contact | TB2-2 |
| RCRT-NC | Remote Critical Alarm, Normally Closed Contact | TB2-3 |
| RMAJ-NO | Remote Major Alarm, Normally Open Contact | TB2-4 |
| RMAJ-COM | Remote Major Alarm, Common Contact | TB2-5 |
| RMAJ-NC | Remote Major Alarm, Normally Closed Contact | TB2-6 |
| RMIN-NO | Remote Minor Alarm, Normally Open Contact | TB2-7 |
| RMIN-COM | Remote Minor Alarm, Common Contact | TB2-8 |
| RMIN-NC | Remote Minor Alarm, Normally Open Contact | TB2-9 |

## D.1.5 SDU-2000 Expansion Interface

Figure D-6 illustrates the SDU Interface and the Backup Clock Connector, located on the rear panel of the SSU-2000. Table D-5 outlines signal names, definitions, and locations of the SDU Expansion interface and backup clock connectors.

ss200040
Figure D-6. SDU Interface and Backup Clock Connector Pinouts

Table D-5. Signal Names and Locations for SDU-2000 Interface

| Name | Description | Connector-Pin |
| :--- | :--- | :--- |
| SCLK2+/- | SPI Clock Signal, generated by SPI Master | J8-1\&14 |
| MOSI2+/- | SPI Master Out / Slave In Data line | J8-2\&15 |
| MISO2+/- | SPI Master In / Slave Out Data line | J8-3\&16 |
| SS2+/- | SPI Slave Select line, generated by SPI Master | J8-5\&18 |
| SBUSY2+/- | SPI Slave Busy line, generated by SPI Slave | J8-4\&17 |
| SRQ2+/- | SPI Service Request line, generated by SPI Slave | J8-6\&19 |

Table D-5. Signal Names and Locations for SDU-2000 Interface (Continued)

| Name | Description | Connector-Pin |
| :--- | :--- | :--- |
| CLKAOUT2+/- | Clock A to Output Modules (synced 4 kHz) | $\mathrm{J} 8-7 \& 20$ |
| CLKBOUT2+/- | Clock B to Output Modules (synced 4 kHz) | $\mathrm{J} 8-8 \& 21$ |
| CLKC2+/- | Pass-through Clock from Input to Output Modules (4 kHz) | $\mathrm{J} 8-9 \& 22$ |
| CLKD2+ | Selected Clock via TBNC/BNO to SDU-2000 (Backup 4 kHz) | $\mathrm{J} 9-\mathrm{A}$ |
| CLKD2- | Selected Clock via TBNC/BNO to SDU-2000 (Backup 4 kHz) | $\mathrm{J9-B}$ |
| EXPSP1+/- | Spare Connection to SDU-2000 | $\mathrm{J8-11} \mathrm{\& 24}$ |
| EXPSP2+/- | Spare Connection to SDU-2000 | $\mathrm{J8-12} \mathrm{\& 25}$ |
| SOUT2+/- | SPI Expansion Shelf Select Request, generated by SDU SPI Slave | $\mathrm{J8-10} \mathrm{\& 23}$ |
| LG | Logic Ground Connection | $\mathrm{J8-13}$ |

## D.1.6 50 Pin Connector Input and Output Signals

Table D-6 corresponds the 50 pin I/O signal connectors to the appropriate I/O slot location. The connectors J10 through J18 are hard wired through the backplane to I/O slots A3 through A11.

Table D-6. I/O Slot Locations

| Rear Panel Connector | I/O Slot Location |
| :---: | :---: |
| J 10 | A3 |
| J 11 | A 4 |
| J 12 | A5 |
| J 13 | A6 |
| J 14 | A7 |
| J 15 | A8 |
| J 16 | A9 |
| J 17 | A10 |
| J 18 | A11 |

## ㅍ Note .. <br> The pin assignments for J10 through J18 are identical. The pin assignments outlined in Table D-7 refer to all nine of these connectors.

Table D-7 outlines input and output signal definitions on connectors J10 through J18, the nine 50 pin connectors located on the rear panel of the SSU-2000 Main shelf.


Figure D-7. I/O Connector and Summer Adapter Pinouts

Table D-7. 50 Pin Connector Input/Output Signal Names and Location

| Name | Description | Connector Pin \# |
| :--- | :--- | :---: |
| Cs Fault | Logic Level Input Indicating Problem with Cs Reference | 1 |
| Cs Fault RTN | Return Line for Cs Fault Signal | 26 |
| ITIP 01 | Tip Connection of Input Signal \# 1 | 3 |
| IRING 01 | Ring Connection of Input Signal \# 1 | 28 |
| ITIP 02 | Tip Connection of Input Signal \# 2 | 13 |
| IRING 02 | Ring Connection of Input Signal \# 2 | 38 |
| ITIP 03 | Tip Connection of Input Signal \# 3 | 23 |
| IRING 03 | Ring Connection of Input Signal \# 3 | 48 |
| OTIP 01 | Tip Connection of Output Signal \# 1 | 2 |
| ORING 01 | Ring Connection of Output Signal \# 1 | 27 |
| OTIP 02 | Tip Connection of Output Signal \# 2 | 4 |
| ORING 02 | Ring Connection of Output Signal \# 2 | 29 |
| OTIP 03 | Tip Connection of Output Signal \# 3 | 5 |
| ORING 03 | Ring Connection of Output Signal \# 3 | 30 |
| OTIP 04 | Tip Connection of Output Signal \# 4 | 6 |
| ORING 04 | Ring Connection of Output Signal \# 4 | 31 |

Table D-7. 50 Pin Connector Input/Output Signal Names and Location (Continued)

| Name | Description | Connector Pin \# |
| :---: | :---: | :---: |
| OTIP 05 | Tip Connection of Output Signal \#5 | 7 |
| ORING 05 | Ring Connection of Output Signal \# 5 | 32 |
| OTIP 06 | Tip Connection of Output Signal \# 6 | 8 |
| ORING 06 | Ring Connection of Output Signal \# 6 | 33 |
| OTIP 07 | Tip Connection of Output Signal \# 7 | 9 |
| ORING 07 | Ring Connection of Output Signal \# 7 | 34 |
| OTIP 08 | Tip Connection of Output Signal \#8 | 10 |
| ORING 08 | Ring Connection of Output Signal \# 8 | 35 |
| OTIP 09 | Tip Connection of Output Signal \# 9 | 11 |
| ORING 09 | Ring Connection of Output Signal \# 9 | 36 |
| OTIP 10 | Tip Connection of Output Signal \# 10 | 12 |
| ORING 10 | Ring Connection of Output Signal \# 10 | 37 |
| OTIP 11 | Tip Connection of Output Signal \# 11 | 14 |
| ORING 11 | Ring Connection of Output Signal \# 11 | 39 |
| OTIP 12 | Tip Connection of Output Signal \# 12 | 15 |
| ORING 12 | Ring Connection of Output Signal \# 12 | 40 |
| OTIP 13 | Tip Connection of Output Signal \# 13 | 16 |
| ORING 13 | Ring Connection of Output Signal \# 13 | 41 |
| OTIP 14 | Tip Connection of Output Signal \# 14 | 17 |
| ORING 14 | Ring Connection of Output Signal \# 14 | 42 |
| OTIP 15 | Tip Connection of Output Signal \# 15 | 18 |
| ORING 15 | Ring Connection of Output Signal \# 15 | 43 |
| OTIP 16 | Tip Connection of Output Signal \# 16 | 19 |
| ORING 16 | Ring Connection of Output Signal \# 16 | 44 |
| OTIP 17 | Tip Connection of Output Signal \# 17 | 20 |
| ORING 17 | Ring Connection of Output Signal \# 17 | 45 |
| OTIP 18 | Tip Connection of Output Signal \# 18 | 21 |
| ORING 18 | Ring Connection of Output Signal \# 18 | 46 |
| OTIP 19 | Tip Connection of Output Signal \# 19 | 22 |
| ORING 19 | Ring Connection of Output Signal \# 19 | 47 |
| OTIP 20 | Tip Connection of Output Signal \# 20 | 24 |
| ORING 20 | Ring Connection of Output Signal \# 20 | 49 |

## D. 2 Shelf Module Slot Addressing and Size Assignments

Table D-8 outlines the shelf module slot addressing and size assignments.

Table D-8. Shelf Module Slot Addressing and Size Assignments

| Slot-A | Address | Module Types | Comments |
| :--- | :--- | :--- | :--- |
| 1 | 1 | Clock | Clock A |
| 2 | 2 | Com | Communications |
| 3 | 3 | I/O or Receiver | Input, non-redundant Output, or a Receiver <br> Module |
| 4 | 4 | I/O, Output Pair A | Input or Output, paired with 5 |
| 5 | 5 | I/O, Output Pair A or Receiver | Input, Output, paired with 4, or a Receiver <br> Module |
| 6,7 | 6,7 | I/O, Output Pair B | Inputs, or paired Outputs |
| 8,9 | 8,9 | I/O, Output Pair C | Inputs or paired Outputs |
| 10,11 | 10,11 | I/O, Output Pair D | Inputs or paired Outputs |
|  | $12-15$ | I/O, Extras | Reserved for future I/O |
| 12 | 17 | Clock | Clock B |
|  | 0 | All | Addresses all modules in the Shelf |

## D. 3 I/O Connector Grounding

Table D-9 outlines I/O connector grounding for all connectors.

Table D-9. I/O Connector Grounding

| Name | Connector <br> Type | Reference <br> Description | Termination Type |
| :--- | :---: | :---: | :--- |
| Local OSC A | BNC | J 1 | Body/Shield: Connected to Frame Ground Plane |
| Local OSC B | BNC | J 2 | Body/Shield: Connected to Frame Ground Plane |
| Ethernet 10-Base-T | RJ45 | J 3 | Body/Shield: Connected to Frame Ground Plane |
| Serial Port A | DE9S | J 4 | Body/Shield: Connected to Frame Ground Plane |
| Serial Port B | DE9S | J 5 | Body/Shield: Connected to Frame Ground Plane |
| ANTENNA A | TNC | J 6 | Shield: 0.01 $\mu$ F Bypass to Frame Ground Plane |
| ANTENNA B | TNC | J 7 | Shield: 0.01 $\mu$ F Bypass to Frame Ground Plane |
| SDU Interface | DB25S | J 8 | Body/Shield: Connected to Frame Ground Plane |
| SDU Backup Clk | TBNC/BNO | J 9 | Shield: Connected to Frame Ground Plane |
| I/0-1 | Micro D50S | J 10 | Body/Shield: Connected to Frame Ground Plane |
| I/0-2 | Micro D50S | J 11 | Body/Shield: Connected to Frame Ground Plane |
| I/0-3 | Micro D50S | J 12 | Body/Shield: Connected to Frame Ground Plane |
| I/0-4 | Micro D50S | J 13 | Body/Shield: Connected to Frame Ground Plane |
| I/0-5 | Micro D50S | $\mathrm{J14}$ | Body/Shield: Connected to Frame Ground Plane |
| I/0-6 | Micro D50S | J 15 | Body/Shield: Connected to Frame Ground Plane |
| I/0-7 | Micro D50S | J 16 | Body/Shield: Connected to Frame Ground Plane |
| I/0-8 | Micro D50S | J 17 | Body/Shield: Connected to Frame Ground Plane |
| I/0-9 | Micro D50S | J 18 | Body/Shield: Connected to Frame Ground Plane |
| RESET | TBNC/BNO | $\mathrm{J19}$ | Shield: 0.01 $\mu$ F Bypass to Frame Ground Plane |
| LG (Logic Ground) | Stake-On | TB3 \& TB4 | Terminal: $1.0 \mu$ F Bypass to Frame Ground Plane |

```
IN this ApPENDIX ...
    - Communications Module Default Settings
    - Stratum 2E and 3E Clock Module Default
        Settings
    - DS1 and E1 Input Module Default
        Configuration
    - GPS Input Module Default Settings
    - DS1 and E1 Output Module Default
        Settings
    - 2048 kHz Output Module Default Settings
    - Composite Clock Output Module Default
        Settings
    - Priority Quality Level (PQL) Table Default
        Settings
    - User Changes to Factory Defaults
```


## Appendix E Default Settings

This appendix contains tables that list the factory default settings for the SSU-2000. If you make any changes to the factory default settings, record them in Table E-11 for future reference. Use the "SETUP" command to verify settings.

## E. 1 Communications Module Default Settings

Table E-1 lists settings and factory defaults for the SSU-2000 Communications Module.

Table E-1. Communications Module Factory Default Settings

| Setting | Factory Default |
| :--- | :--- |
| Unit Name | SSU_2000 |
| Module Information <br> configurations | Current Configuration = the configuration that is currently in use. <br> User Default Configuration = configuration the user specifies as the default if <br> the current configuration is invalid or not present. <br> Factory Configuration = the factory default configuration |
| User List configurations | Maximum of 25 users including four built-in users. |
| EIA-232-C Port <br> Comm Port Timeout | All three comm ports are set to 9600 baud, Interactive Mode, CRLF, and Echo on <br> Five minutes for all (Interactive Mode). (Note: the unit should have one user <br> added; that is, not in the INITUSERTABLE state). If it is in the <br> INITUSERTABLE state, no timeout is applied. <br> No Timeout is assigned for the TL1 Mode. |
| Ethernet IP Address | IP Address 0.0.0.0 <br> Gateway Address 0.0.0.0 <br> Network Mask 255.255.255.0 |

## E. 2 Stratum 2E and 3E Clock Module Default Settings

The Stratum 2E and 3E Clock module are software configurable via one of the serial or ethernet ports. Table E-2 lists settings and factory defaults for the Clock module.

Table E-2. Stratum 2E and 3E Clock Module Default Settings

| Setting | Factory Default |
| :--- | :--- |
| Stratum 2E and 3E Clock Module Defaults |  |
| Warmup Time | 1200 seconds |
| Min Tau Limit | 300 seconds |
| Max Tau Limit | If 2E, 10000 seconds <br> If 3E, 500 seconds |
| Min Tau | 300 seconds |
| Max Tau | If 2E, 9000 seconds <br> If 3E, 450 seconds |
| Clk Switch AR | On |
| Input Switch | AutoReturn (AR) |
| Input Selection Mode | Priority |
| Local Oscillator (LO) | On |
| Frequency Offset | 57 ppb |
| Elevation Time | 86400 seconds |

## E. 3 DS1 and E1 Input Module Default Configuration

The DS1 Input Module or E1 Input Module maintains factory default and current user configuration information in nonvolatile memory. This information is retrieved at power up and is modified by commands from the Communications Module.The DS1 Input Module or E1 Input Module maintains factory default and current user configuration information in nonvolatile memory. This information is retrieved at power up and is modified by commands from the Communications Module.

When the current user configuration cannot be used, the input module settings automatically revert to factory defaults. Table E-3 lists factory default settings and ranges for all DS1 Input Module or E1 Input Module software parameters.

Table E-3. DS1 and E1 Input Module Default Configuration

| Configuration Setting | Factory Default | Range |
| :---: | :---: | :---: |
| Input Frequency (for unframed signals) | 1.544 for DS1 Input Module <br> 2.048 MHz for E1 Input Module | $\begin{aligned} & 1 \mathrm{MHz}, 1.544 \mathrm{MHz}, 2.048 \mathrm{MHz} \text {, } \\ & 5 \mathrm{MHz}, 10 \mathrm{MHz} \end{aligned}$ |
| Framing Type | ESF for DS1 Input Module CCS for E1 Input Module | D4 or ESF for DS1 Input Module CAS or CCS for E1 Input Module |
| Zero Suppression | On | On/Off |
| CRC | Off | On/Off |
| SSM | Off | On/Off |
| Provisioned PQL | 4 for DS1 Input Module <br> Note: PQL 4=STU <br> 4 for E1 Input Module | 2,3,4,5,6, or 8 |
| Priority | 0 | 0 to 10 (0 = Monitor) |
| E1 SSM Bit Position | 8 (Not applicable for DS1 Input Module) | 4 to 8 |
| Cesium Fault Nominal | Off | Low/High/Off |
| Gain | Off | On or Off ( 20 dB ) |
| Input Signal Error Limit (LOS, AIS, OOF, BPV, CRC) | Defaults are: <br> LOS: <br> 10 seconds (Err Cnt) <br> 5 seconds (Clr Cnt) <br> AIS: <br> 12 seconds (Err Cnt) <br> 5 seconds (Clr Cnt) <br> OOF: <br> 14 seconds (Err Cnt) <br> 5 seconds (Clr Cnt) <br> BPV, CRC: <br> 16 seconds (Err Cnt) <br> 5 seconds (Clr Cnt) | 1 to 100 for LOS and AIS <br> 1 to 10,000 for BPV, CRC and OOF |
| MTIE Limits | See Table E-4 and Table E-5 | 1 to 10,000 |
| MTIE Limit 1 Alarm Mode | MINOR | Ignore, Report, Minor, Major, or Critical |
| MTIE Limit 2 Alarm Mode | MAJOR | Ignore, Report, Minor, Major, or Critical |
| Alarm Initial Severity | MINOR (except LOS and Level 2 MTIE, which are MAJOR) | Ignore, Report, Minor, Major, or Critical |
| Alarm Initial Delay | 0 seconds | 0 to 86,400 seconds |

Table E-3. DS1 and E1 Input Module Default Configuration (Continued)

| Configuration Setting | Factory Default | Range |
| :--- | :--- | :--- |
| Alarm Elevation Time | 86,400 seconds | 0 to 500,000 seconds |
| Port Status | Disabled | Enabled/Disabled |
| Port Name | Not applicable | Any user selected string from 0 to 20 <br> characters |

## E.3.1 MTIE Limits for the DS1 Input Module

Table E-4 provides MTIE limits for the DS1 Input Module configuration and factory defaults and settings.

Table E-4. DS1 Input Module - MTIE Limits

| Time <br> (seconds) | Set Limit L1 <br> (nanoseconds) | Set Limit L2 <br> (nanoseconds) | Clear Limit L1 <br> (nanoseconds) | Clear Limit L2 <br> (nanoseconds) |
| :---: | :---: | :---: | :---: | :---: |
| 10 | 260 | 325 | 230 | 290 |
| 100 | 440 | 550 | 400 | 490 |
| 1000 | 810 | 1010 | 730 | 910 |
| 10000 | 880 | 1100 | 790 | 990 |
| 100000 | 1600 | 2000 | 1440 | 1800 |

## E.3.2 MTIE Limits for the E1 Input Module

Table E-5 provides MTIE limits for the E1 Input Module configuration settings and factory defaults and ranges.

Table E-5. E1 Input Module - MTIE Limits

| Time <br> (seconds) | Set Limit L1 <br> (nanoseconds) | Set Limit L2 <br> (nanoseconds) | Clear Limit L1 <br> (nanoseconds) | Clear Limit L2 <br> (nanoseconds) |
| :---: | :---: | :---: | :---: | :---: |
| 10 | 80 | 100 | 70 | 90 |
| 100 | 800 | 1000 | 700 | 900 |
| 1000 | 1600 | 2000 | 1400 | 1800 |
| 10000 | 1170 | 2835 | 2000 | 2500 |
| 100000 | 4260 | 5330 | 3800 | 4800 |

## E. 4 GPS Input Module Default Settings

The GPS Input Module maintains factory default and current user configuration settings. The configuration settings for the GPS Input Module are provided in Table E-6.

Table E-6. GPS Input Module Default Configuration Settings

| Configuration Setting | Factory Default | Range |
| :---: | :---: | :---: |
| Position (GPS only) <br> Latitude (+ = North, $-=$ South) <br> Longitude (+ = East, - = West) <br> Height <br> Averages <br> PDOP <br> Pos Mode | $\begin{aligned} & 0 \\ & 0 \\ & 0 \\ & 300 \\ & 0 \\ & \text { Calc } \end{aligned}$ | $\begin{aligned} & \text { +/- } 90 \text { degrees } \\ & \text { +/-180 degrees } \\ & -60 \text { to } 4,000 \text { meters } \\ & 10 \text { to } 3600 \\ & 1 \text { to } 10 \\ & \text { User/Calc } \end{aligned}$ |
| Min Elevation for position | 5 | 0 to 50 degrees |
| Min PDOP for position | 3 | 1 to 10 |
| Min Elevation for timing | 10 | 0 to 50 degrees |
| Module Status | Enabled | Enabled Disabled |
| Priority | 0 | 0 to 10 |
| Sigma limit | 25 | 10 to 1000 US |
| PQL | 2 | 1 to 16 |
| Disabled SV list | Not applicable | Up to 31 SV numbers |
| Min PDOP for position | 3 | 1 to 10 |

## E. 5 DS1 and E1 Output Module Default Settings

Table E-7 lists settings and factory defaults for the SSU-2000 DS1and E1 Output Module.

Table E-7. DS1 and E1 Output Module Default Settings

| Setting | Factory Default | Range |
| :---: | :---: | :---: |
| DS1 Module |  |  |
| Enable/Disable Outputs | Disabled | Settable for each output port |
| Minimum Clock Level | Acquire | Acquire/Lock |
| Bypass Mode | ON | ON - Clock $C$ will be selected if it is the only one available OFF - Clock C will not be selected even if no other clock is available |
| Framing | ESF | D4/ESF |
| Line Length | 0-133 ft | $\begin{aligned} & 133-266 \mathrm{ft} \\ & 266-399 \mathrm{ft} \\ & 399-533 \mathrm{ft} \\ & 533-655 \mathrm{ft} \end{aligned}$ |
| Zero Suppression | ON | $\begin{aligned} & \text { ON - B825 } \\ & \text { OFF - AMI } \end{aligned}$ |
| E1 Module |  |  |
| Enable/Disable Outputs | Disabled | Settable for each output port |
| Minimum Clock Level | Acquire | Acquire/Lock |
| Bypass Mode | ON | ON - Clock C will be selected if it is the only one available OFF - Clock C will not be selected even if no other clock is available |
| Framing | CAS | CCS/CAS |
| Zero Suppression | ON | $\begin{aligned} & \text { ON - HDB3 } \\ & \text { OFF - AMI } \end{aligned}$ |
| CRC | ON | ON/OFF |
| SSM Bit Selection | Default SSM bit selection -8 | Possible SSM bit selection 4, 5, 6, 7, and 8 |

## E. 62048 kHz Output Module Default Settings

The 2048 kHz Output module maintains factory default and current user configuration settings. The configuration settings for the 2048 kHz Output Module are provided in Table E-8.

Table E-8. 2048 kHz Output Module Configuration

| Configuration Setting | Factory Default | Range |
| :--- | :--- | :--- |
| Port State | Disabled | Disabled/Enabled |
| Min Clock | Acquire | Acquire/Lock |
| Framing | Not applicable | Not applicable |
| Zero Suppression | Not applicable | Not applicable |
| CRC | Not applicable | Not applicable |
| SSM | Not applicable | Not applicable |
| PQL | 4 | Not applicable |
| Bypass | On | On/Off |
| Fault Action | On | Off/On/Auto |
| Other | Not applicable | Not applicable |

## E. 7 Composite Clock Output Module Default Settings

The Composite Clock Output module maintains factory default and current user configuration settings. The configuration settings for the Composite Clock Output Module are provided in Table E-9.

Table E-9. Composite Clock Output Module Configuration

| Configuration Setting | Factory Default | Range |
| :--- | :--- | :--- |
| Port State | Disabled | Disabled/Enabled |
| Min Clock | Acquire | Acquire/Lock |
| Framing | Not applicable | Not applicable |
| Zero Suppression | Not applicable | Not applicable |
| CRC | Not applicable | Not applicable |
| SSM | Not applicable | Not applicable |
| PQL | 4 | Not applicable |
| Bypass | On | On/Off |
| Fault Action | On | Off/On/Auto |
| Other | Duty Cycle of $5 / 8$ | Duty Cycle of $5 / 8$ or $50 / 50$ |

## E. 8 Priority Quality Level (PQL) Table Default Settings

The configuration settings for the PQL table are provided in Table E-10

Table E-10. Default PQL Values

| DS1 |  |  | E1 |  |  |  |
| :---: | :--- | :--- | :--- | :--- | :--- | :--- |
| PQL | SSM | S | DS1 <br> Description | SSM | S | E1 <br> Description |
| 1 | -- |  | Unused | -- |  | Unused |
| 2 | $0 \times 04$ | S | ST2 | $0 \times 02$ |  |  |
| 3 | $0 \times 04$ |  |  | $0 \times 02$ | S | PRC/G.811 |
| 4 | $0 \times 08$ | S | STU | $0 \times 00$ | S | STU |
| 5 | $0 \times 0$ C | S | ST2 | $0 \times 04$ |  | Type II |
| 6 | $0 \times 78$ | S |  | $0 \times 04$ | S | Type V |
| 7 | -- |  | Unused | -- |  | Unused |
| 8 | $0 \times 7 C$ | S | ST3E | $0 \times 08$ |  | Type III |
| 9 | $0 \times 10$ |  |  | $0 \times 08$ | S | Type VI |
| 10 | $0 \times 10$ | S | ST3 | $0 \times 0 \mathrm{~B}$ |  | Type IV |
| 11 | $0 \times 22$ |  |  | $0 \times 0 B$ | S | G.813 Opt 1 |
| 12 | $0 \times 22$ | S | SMC | $0 \times 0 F$ |  | G.813 Opt 2 |
| 13 | $0 \times 28$ | S | ST4 | $0 \times 0$ F |  |  |
| 14 | $0 \times 40$ | S | Reserved | $0 \times 0$ F |  |  |
| 15 | $0 \times 30$ | S | DUS | $0 \times 0$ F | S | DUS |
| 16 | $0 \times 7 E$ | S |  | $0 \times 0 F$ |  |  |

## E. 9 User Changes to Factory Defaults

Table E-11 is provided for recording any user changes to the factory default settings.

Table E-11. User Changes to Factory Default Settings

| Setting | Factory Default | Communications Module Defaults <br> Changes |
| :--- | :--- | :--- |
|  <br> Unit Name <br> CSU_2000 |  |  |
| Module <br> Information <br> configurations | Current Configuration = the configuration that is <br> currently in use <br> User Default Configuration = configuration the user <br> specifies as the default if the current configuration is <br> invalid or not present <br> Factory Configuration = the factory default <br> configuration |  |
| User List <br> configurations | Maximum of 25 users including four built-in users |  |
| EIA-232-C Port | All three comm ports are set to 9600 baud, <br> Interactive Mode, CRLF, and Echo on <br> Comm Port <br> Timeout | Five minutes for all (Interactive Mode). (Note: the <br> unit should have one user added, i.e. not in the <br> INITUSERTABLE state). If it is in the <br> INITUSERTABLE state, no timeout is applied. |
| No Timeout is assigned for the TL1 Mode |  |  |

## Table E-11. User Changes to Factory Default Settings (Continued)

| Setting | Factory Default | User Configuration <br> Changes |
| :--- | :--- | :--- |
| Input Switch | AutoReturn (AR) |  |
| Input Selection <br> Mode | Priority |  |
| Local Oscillator <br> (LO) | On |  |
| Frequency Offset | 57 ppb |  |
| Elevation Time | 86400 seconds |  |
| Warmup Time | 1200 seconds |  |
| Min Tau Limit | 300 seconds |  |
| Max Tau Limit | If $2 \mathrm{E}, 10000$ seconds <br> If $3 \mathrm{E}, 500$ seconds |  |
| Min Tau | 300 seconds |  |
| Max Tau | If $2 \mathrm{E}, 9000$ seconds <br> If $3 \mathrm{E}, 450$ seconds |  |
| CIk Switch AR | On |  |
| Input Switch | AutoReturn (AR) |  |
| Input Selection <br> Mode | Priority |  |
| Local Oscillator <br> (LO) | On |  |
| Frequency Offset | 57 ppb |  |
| Elevation Time | 86400 seconds |  |
| Warmup Time | 1200 seconds |  |

## In this Appendix ...

- Regulatory Requirements


## Appendix F Regulatory Requirements

This appendix provides information about safety and EMC standards and requirements for the SSU-2000.

The SSU-2000 unit is designed to meet these safety and EMC requirements:

- EMC requirements of GR-1089-CORE Issue 2, 12-1997
- SELV equipment requirements for product safety as specified in UL 1950/CSA C22.2, 7-1995

```
IN this ApPeNDIX ...
- General Specifications
- Operating Conditions Specifications
- Power Input and Grounding Specifications
- Input Signal Specifications
- Output Signal Specifications
- Chassis Dimensions
```


## Appendix G Specifications

This section provides specifications for the SSU-2000 unit and for its functional components, such as operating conditions, power inputs, clock inputs and outputs, indicators, EMC and safety standards, and chassis dimensions.

## G. 1 General Specifications

The operating limits for the unit are set to factory default settings as listed in Appendix E, Default Settings.

Table G-1 details the general specifications for a fully populated unit configured with SSU function. Inputs apply only to the SSU function.

Table G-1. General Specifications

| Characteristics | Specification |
| :---: | :---: |
| General |  |
| Architecture | - Main Shelf: 2 clocks, 1 Communications module and 9 mixed I/O modules <br> - Expansion Shelf: 14 output modules and 2 buffer modules <br> - Up to 4 Expansion Shelves per system |
| Long Term Frequency (Accuracy) | Stratum 1 PRS per (ANSI) T1.101 and ITU-T G. 811 |
| Clock Performance | Meets requirements of the Telcordia Technologies (formerly Bellcore) document GR-1244-CORE |
| Reference Signals | Determined by the type of Input module: <br> - GPS navigation signal <br> - DS1 - D4 or ESF <br> - E1 - CAS or CCS <br> - Clock - $1 \mathrm{MHz}, 1.544 \mathrm{MHz}, 2048 \mathrm{kHz}, 5 \mathrm{MHz}, 10 \mathrm{MHz}$ |

## Table G-1. General Specifications (Continued)

| Characteristics | Specification |
| :---: | :---: |
| Sync Status Messaging (SSM) | Compliant with SSM specifications per T1X1.3 TR33, (ANSI) T1.101-1999, and Telcordia Technologies GR-253 and 378-CORE and with applicable parts of ITU-T G. 781 |
| Event Log | Stores at least 500 event history including timestamp, event type, event/ alarm level, and condition causing the event; stores the last 10 events in nonvolatile memory. |
| Configuration Data | Firmware stores factory configuration, customer configuration, current configuration, and board identification information, and provides a command which can be used to restore saved settings. |
| Alarm Levels | Commands can set alarm level to IGNORE, REPORT, MINOR, MAJOR, and CRITICAL. MINOR and MAJOR alarms can be elevated to the next higher level after a user-defined time period. |
| Communications Ports | Three RS-232 Serial Ports: <br> - Serial PORT-A (J4) <br> - Serial PORT-B (J5) <br> - Comms Module Serial Port One Ethernet Port <br> - Ethernet port (10 Base T) |
| Communication Management |  |
| Management Interface | Simple fault, visual and contact closures ICS <br> TL1 <br> SNMP |
| Input Section |  |
| Ports | Maximum of 27 <br> 1 or 3 ports per input module <br> Reference or monitoring capability |
| Signal Type | DS1, E1, 2048 kHz (G. 703 Sec.13), $1.544 \mathrm{MHz}, 2.048 \mathrm{MHz}, 1,5$, and 10 MHz Clocks (user-settable) |
| GPS | Integrated (single or dual) |
| Sync Status Messaging (SSM) | Fully supported |
| Selection Mode | Priority and PQL (user settable) |

## Table G-1. General Specifications (Continued)

| Characteristics | Specification |
| :---: | :---: |
| Performance Measurement |  |
| Resolution | 1 ns |
| Sampling Rate | 40 Hz |
| MTIE and TDEV | Exceeds latest ANSI, ITU-T and Telcordia Technologies standards |
| Clock |  |
| Type (Holdover) | Stratum 2E Rubidium Stratum 3E Quartz |
| Control | DDS (Direct Digital Synthesis) technology Integrated CPU |
| Output Section |  |
| Port | 20 Ports per module for DS/E1, 2048 kHz , and Composite clock |
| Signal Type | ```DS1 E1 2.048 MHz (G703 Sec.13) Composite Clock (CC)``` |
| Distribution Capacity |  |
| Main Shelf | Up to 9 DS1/E1 output modules in Main Shelf 20 outputs per output module |
| SDU-2000 Expansion | Up to 4 Expansion Shelves <br> Up to 14 output modules per expansion shelf with 20 outputs per module Maximum of 1120 outputs in 4 expansion shelves |
| Alarm Closures |  |
| MINOR | Contact closure (NC or NO) 1 Amp Form C |
| MAJOR | Contact closure (NC or NO) 1 Amp Form C |
| CRITICAL | Contact closure (NC or NO) 1 Amp Form C |
| Chassis Power and Grounds |  |
| Power Connections | A \& B Input connections at opposite upper sides of the rear panel |
| DC | -38 to -72.5 vDC, (-48 vDC nominal) |
| DC Power @ -48 vDC | < 240 watts, per chassis |
| Fuse Type/Rating | 2 fuses; GMT-5A |
| Grounds | -48 V return DC, integrated with frame and logic grounds. |

## Table G-1. General Specifications (Continued)

| Characteristics | Specification |
| :---: | :---: |
| Chassis Mechanical |  |
| Width | 17 inches |
| Depth | 11.5 inches |
| Height | 10.5 inches |
| Weight (provisioned) | ~ 27 lbs |
| Chassis Environmental |  |
| Temperature <br> Operational Stratum Levels | $+1.7^{\circ} \mathrm{C}$ to $+49^{\circ} \mathrm{C} @ 8.3^{\circ} \mathrm{C}$ max rate of change per hour GR-1244-CORE Sec. 2.2 |
| Relative Humidity Operational | $5 \%$ to $85 \%$ Non-condensing <br> GR-63-CORE Sec. 4.1.2 ETS 300 019-1 Class 3.1 |
| Temperature Operational Short Term Non-Stratum performance | $-5^{\circ} \mathrm{C}$ to $+50^{\circ} \mathrm{C} @ 30^{\circ} \mathrm{C}$ max per hour rate of change. Duration <96 hours <br> GR-63-CORE Sec. 4.1.2 ETS 300 019-1 Class 3.1 |
| Relative Humidity Operational Short Term | $5 \%$ to $90 \%$ Non-condensing. Duration <96 hours GR-63-CORE Sec. 4.1.2 ETS 300 019-1 Class 3.1 |
| Temperature Storage | $\begin{aligned} & -25^{\circ} \mathrm{C} \text { to }+55^{\circ} \mathrm{C} \text { Duration }<12 \text { months } \\ & \text { GR-63-CORE Sec. 4.1.1 ETS } 300 \text { 019-1 Class } 1.2 \end{aligned}$ |
| Relative Humidity Storage | $5 \%$ to $100 \%$ Non-condensing. Duration <12 months GR-63-CORE Sec. 4.1.1 ETS 300 019-1 Class 1.2 |
| Temperature <br> Transporting | $-40^{\circ} \mathrm{C}$ to $+70^{\circ} \mathrm{C}$ Duration $<3$ months GR-63-CORE Sec. 4.1.1 ETS 300 019-1 Class 2.3 |
| Chassis Environmental |  |
| Relative Humidity Transporting | $5 \%$ to $100 \%$ Non-condensing. Duration <3 months GR-63-CORE Sec. 4.1.1 ETS 300 019-1 Class 2.3 |
| Heat Dissipation | GR-63-CORE Sec. 4.1.4 |
| Altitude | 200 ft . below to 13,000 ft above sea level GR-63-CORE Sec. 4.1.3 |
| Airborne Contaminants | GR-63-CORE Sec. 4.5.2.1 |
| Shock Operational | ETS 300 019-2-3 Class T3.1 |
| Sinusoidal Vibration Operational | GR-63-CORE Sec. 4.4.3 |

## Table G-1. General Specifications (Continued)

| Characteristics | Specification |
| :--- | :--- |
| Seismic Vibration | GR-63-CORE Sec. 4.4.1 Earthquake Zone 4 ETS 300 019-2-3-A1 |
| Shock Transporting | ETS 300 019-2-2 Class T2.2 |
| Sinusoidal Vibration <br> Transporting | GR-63-CORE Sec. 4.4.4 fig. 4-3 |
| Random Vibration <br> Transporting | ETS 300 019-2-2 Class 2.1, 2.2, 2.3, and 2.3 special |
| Packaged Equipment <br> Shock | GR-63-CORE Sec. 4.3.1.2 |
| Unpackaged <br> Equipment Shock | GR-63-CORE Sec. 4.3.2 |
| Electrical Safety | GR-1089-CORE Sec. 7 |
| Material/Component <br> Fire Resistance | GR-1089-CORE Sec. 4.2.3.1 |
| EMC |  |
| Immunity/Resistibility <br> ESD | EN 300 386-2 V1.1.3 Sec. 5.1.1.1 \& 5.1.1.4 <br> GR-1089-CORE Sec. 2 |
| Immunity Radiated | EN 300 386-2 V1.1.3 Sec. 5.1.1.2 <br> GR-1089-CORE Sec. 3.3.1 \& 3.3.2 |
| Immunity Fast <br> Transient | EN 300 386-2 V1.1.3 Sec. 5.1.3.1 \& 5.1.5.1 |
| Immunity Surges | EN 300 386-2 V1.1.3 Sec. 5.1.3.2 |
| Immunity Radio Freq. <br> Conducted | EN 300 386-2 V1.1.3 Sec. 5.1.3.3 \& 5.1.5.2 <br> GR-1089-CORE Sec. 3.3.3 |
| Emissions Radiated | EN 300 386-2 V1.1.3 Sec. 5.1.1.3 <br> GR-1089-CORE Sec. 3.2.1 \& 3.2.2 |
| Emissions Radio Freq. <br> Disturbance voltage | EN 300 386-2 V1.1.3 Sec. 5.1.5.3 <br> GR-1089-CORE Sec. 3.2.4 |
| Interface A <br> (Power Input) | ETS 300 132-2 <br> Part 2: Operated by direct current (dc) |
| Low-Impedance Plane <br> (Grounding) | ETS 300 253 <br> GR-1089-CORE Sec. 9 |
| GR-1089-CORE Sec. 4.5.9 |  |

## Table G-1. General Specifications (Continued)

| Characteristics | Specification |
| :--- | :--- |
|  <br> Receiver Input | EN 61000-4-5 <br> 1 kV tested combination wave generator <br> $(1.2 / 50-8 / 20 ~ \mu \mathrm{~s}) 12$ ohm impedance |
| I/O Adapter Panels |  |

## G. 2 Operating Conditions Specifications

The unit operates at specified parameters in the operating conditions summarized in Table G-2.

Table G-2. Normal Operating Conditions

| Parameter | Minimum | Maximum | Units | Notes |
| :--- | :---: | :---: | :---: | :---: |
| Supply Voltage | -38 | -65 | Volts DC |  |
| Temperature | 0 | 50 | ${ }^{\circ} \mathrm{C}$ | 1 |
| Temperature Rate of Change | - | 8.3 | ${ }^{\circ} \mathrm{C} / \mathrm{Hr}$ |  |
| Relative Humidity | 5 | 85 | $\%$ | 2 |
| Altitude | -200 ft. | $13,000 \mathrm{ft}$. | feet | 3 |

## Notes:

1. Inlet air temperature, limited convection $15 \mathrm{ft} . / \mathrm{min}$.
2. Non-condensing.
3. The maximum operation ambient temperature shall be reduced by $2^{\circ} \mathrm{C}$ for every 984 ft . altitude above 4,921 ft.

The unit is not damaged when exposed to the levels specified in Table G-3, but performance is degraded. The unit returns to specified performance upon returning to specified operating conditions.

Table G-3. Exceptional Operating Conditions

| Parameter | Minimum | Maximum | Units | Notes |
| :--- | :---: | :---: | :--- | :---: |
| Supply Voltage: (48 vDC) | -38 | -75 | Volts, DC | 1 |
| Temperature | -5 | 50 | ${ }^{\circ} \mathrm{C}$ | 2 |
| Relative Humidity | 5 | 90 | $\%$ | 3 |

## Notes:

1. The unit is not damaged if the polarity on the power leads is reversed.
2. At $30^{\circ} \mathrm{C}$ max/hour rate of change.
3. Non-condensing.

## G. 3 Power Input and Grounding Specifications

Table G-4 Provides power input specifications.

Table G-4. Power Input Specifications

| Parameter | Specification |
| :--- | :--- |
| Supply power | -38 to -72.2 Vdc $(-48 \text { Vdc nominal) })^{1,2,3}$ |
| Power, maximum | $<240$ watts at power on |
| Power, typical | $<100$ watts at normal operation |
| Connector | \#6 Ring Terminal Block |
| NoTEs: <br> 1. <br> 2. Reversing the input polarity does not damage the unit. <br> 3. |  |

## G. 4 Input Signal Specifications

Table G-5 details the input signal specifications.

Table G-5. Input Signal Specifications

| Parameter | Dpecification Signals |
| :--- | :--- |
|  | D4/SF or ESF (User Selectable) |
| Framing | 1544 kbit/s |
| Bit Rate | AMI or B8ZS (per (ANSI) T1.102 \& ITU-T G.703 Sec. 5) |
| Format | +3 to -24 dBDSX |
| Amplitude Range | Meets the requirements of Bellcore GR-1244-CORE, Section 4. |
| Jitter and Wander Tolerance | 0 to 255 Intervals per hour (AIS, LOS, OOF, BPV, CRC) |
| Input Error Threshold | 3.3 k $\Omega$ (External termination) |
| Input Impedance | G.703 Sec. 9 Framed E1 |
|  | 2048 kbit/s |
| Type | CAS or CCS (per ITU-TG.703 Sec. 2 \& (ANSI) T1.102 DS1A CRC4 <br> enabled/disabled AMI or HDB3) |
| Bit Rate | +3 to -27 dBTLO |
| Format | Meets the requirements of ITU-T G.823 |
| Amplitude Range | 0 to 255 Intervals per hour (AIS, LOS, LOF, BPV, CRC) |
| Jitter and Wander Tolerance | G.703 Sec. 9 Framed E1 |
| Input Error Threshold | External |
| Type |  |
| Input Termination |  |

## G. 5 Output Signal Specifications

Table G-6 details the input signal specifications.

Table G-6. Output Signal Specifications

| Parameter | Specification |
| :---: | :---: |
| DS1 Signals |  |
| Framing (user selectable) | Outputs: D4/Super Frame (SF) or Extended Super Frame (ESF) |
| Signal Waveshape <br> Rise Time Pulse Width Pulse Interval Duty Cycle | Framed, all ones, Alternate Mark Inversion (AMI) per (ANSI) T1.102 and ITU Rec. G. 703 <br> < 100 nsec <br> < 324 nsec, nominal <br> 648 nsec , nominal <br> 50\% |
| Pulse Amplitude | 2.4 to 3.6 volts peak into $100 \Omega$ |
| Output Jitter | < 0.03 UI |
| Number of Outputs | 20 per module |
| Termination Impedance | $100 \Omega \pm 5 \%$ |
| E1 Signals |  |
| Framing (user selectable) | CAS, CCS |
| Signal Waveshape <br> Rise Time Pulse Width Pulse Interval Duty Cycle | Framed, all ones, Alternate Mark Inversion (AMI) Per ITU Rec. G. 703 Sec. 9 <br> < 100 nsec <br> < 244 nsec, nominal <br> 488 nsec , nominal <br> 50\% |
| Pulse Amplitude | 2.4 to 3.6 volts peak into $120 \Omega$ 1.9 to 2.8 volts peak into $75 \Omega$ |
| Output Jitter | < 0.03 UI |
| Number of Outputs | 20 per module |
| Termination Impedance | $120 \Omega \pm 5 \%$ |

## Table G-6. Output Signal Specifications (Continued)

| Parameter | Specification |
| :---: | :---: |
| Composite Clock Signals ( $64 \mathrm{kbit} / \mathrm{s}$ ) |  |
| Signal Waveshape <br> Duty Cycle <br> Rise Time <br> Pulse Width <br> Pulse Interval <br> Amplitude <br> Termination Impedance | Rectangular ( $62.5 \%$ or $50 / 50$ duty cycle), software selectable, per G. 703 Sec. 4 and GR-378 |
| Number of Outputs | 20 per module |
| 2048 kHz Clock Signals |  |
| Signal Waveshape <br> Rise Time <br> Fall Time <br> Duty Cycle | Per ITU Rec. G. 703 Sec. 13 <br> Square wave <br> < 50 nsec <br> < 50 nsec <br> $50 \% \pm 5 \%$ |
| Amplitude | 1.0 to 1.9 volts peak into $120 \Omega$ .75 to 1.5 volts peak into $75 \Omega$ |
| Jitter | < 0.03 UI |
| Number of Outputs | 20 per module |
| Termination Impedance | $120 \Omega \pm 5 \%$ or $75 \Omega \pm 5 \%$ |

## G. 6 Chassis Dimensions

The overall dimensions of the unit are 10.5 inches high $\times 17$ inches wide $\times 11.5$ inches deep. The unit can be mounted in either a standard EIA 19-inch or 23 -inch rack.

## In this Appendix ...

- American National Standards Institute (ANSI) Documents
- Generic Requirements
- Technical Advisories and Framework Technical Advisories
- Technical References
- EIA/TIA Documents
- Other Reference Documents


## Appendix H Reference Materials

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## NOTE..
Bellcore, or Bell Communications Research, is now Telcordia Technologies, Inc. Many reference documents listed in this section were originally published by Bellcore, but are now available from Telcordia Technologies, Inc.
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## H. 1 American National Standards Institute (ANSI) Documents

1. (ANSI) T1.101-1999, Synchronization Interface Standards for Digital Networks.
2. (ANSI) T1.101-199x, revision of T1X1.3/98-002R2, Synchronization Interface Standard.
3. (ANSI) T1.102-1993, Digital Hierarchy-Electrical Interfaces.
4. (ANSI) T1.105-1995, Synchronous Optical Network (SONET) - Basic Description including Multiplex Structure, Rates and Formats.
5. (ANSI) T1.105.01-1995, Synchronous Optical Network (SONET) - Automatic Protection Switching.
6. (ANSI) T1.105.03-1994, Synchronous Optical Network (SONET) - Jitter at Network Interfaces.
7. (ANSI) T1.105.03a-1995, Synchronous Optical Network (SONET) - Jitter at Network Interfaces - DS1 Supplement.
8. (ANSI) T1.105.03b-1997, Synchronous Optical Network (SONET) - Jitter at Network Interfaces - DS3 Supplement.
9. (ANSI) T1.105.04-1995, Synchronous Optical Network (SONET): Data Communication Channel Protocols and Architectures.Family of Requirements
10. FR-476, OTGR Section 6: Network Maintenance: Access and Testing (Bellcore, 1997 Edition) (A subset of OTGR, FR-439).
11. FR-480, OTGR Section 10: User System Interface (Bellcore, 1997 Edition). (A subset of OTGR, FR-439).

## H. 2 Generic Requirements

1. GR-63-CORE, Network Equipment-Building System (NEBS) Requirements: Physical Protection, Issue 1 (Bellcore, October 1995). (A module of LSSGR, FR-64, TSGR, FR440, and NEBSFR, FR-2063.)
2. GR-78-CORE, Generic Requirements for the Physical Design and Manufacture of Telecommunications Products and Equipment, Issue 1 (Bellcore, September 1997). (A module of RQGR, FR-796 and NEBSFR, FR-2063.)
3. GR-378-CORE, Generic Requirements for Timing Signal Generators, Issue 2 (Bellcore, February 1999).
4. GR-474-CORE, OTGR Section 4: Network Maintenance: Alarm and Control for Network Elements, Issue 1 (Bellcore, December 1997). (A module of OTGR, FR-439.)
5. GR-499-CORE, Transport Systems Generic Requirements (TSGR): Common Requirements, Issue 1 (Bellcore, December 1995). (A module of TSGR, FR-440.)
6. GR-831-CORE, OTGR Section 12.1: Operations Application Messages - Language for Operations Application Messages, Issue 1 (Bellcore, November 1996). (A module of OTGR, FR-439.)
7. GR-1089-CORE, Issue 2, Revision 1, 2-1999, Electromagnetic Compatibility and Electrical Safety- Generic Criteria for Network Telecommunications Equipment

## H. 3 Technical Advisories and Framework Technical Advisories

1. TA-NPL-000286 (not available).
2. TA-NPL-000464, Generic Requirements and Design Considerations for Optical Digital Signal Cross-Connect Systems, Issue 1 (Bellcore, September 1987).
3. TA-NWT-000487 (see GR-487-CORE).
4. TA-NWT-000782, SONET Digital Switch Trunk Interface Criteria, Issue 2 (Bellcore, October 1992).
5. TA-NWT-000983, Reliability Assurance Practices for Optoelectronic Devices in Loop Applications, Issue 2 (Bellcore, December 1993).
6. TA-TSV-001294, Generic Requirements for Element Management Layer (EML) Functionality and Architecture, Issue 1 (Bellcore, December 1992).
7. FA-NWT-001345, Framework Generic Requirements for Element Manager (EM) Applications for SONET Subnetworks, Issue 1 (Bellcore, September 1992).
8. TA-NWT-001385, Generic Requirements for Optoelectronic Devices in Fiber Optic Systems, Issue 1 (Bellcore, April 1993) plus Bulletin 1, January 1994.
9. TR-TSY-000825, OTGR Section 10.A: User System Interface - User System Language, Issue 2 (Bellcore, February 1988). (A module of OTGR, FR-NWT-000439.)
10. TR-TSY-000827, OTGR Section 11.1: Generic Operations Interfaces: Non-OSI Communications Architecture, Issue 1 (Bellcore, November 1988). (A module of OTGR, FR-439.)
11. TR-NWT-000835, OTGR Section 12.5: Network Element and Network System Security Administration Messages, Issue 3 (Bellcore, January 1993). (A module of OTGR, FR439.)
12. TR-OPT-000839 (see GR-839-CORE).
13. TR-NWT-000917, SONET Regenerator (SONET RGTR) Equipment Generic Criteria, Issue 1 (Bellcore, December 1990). (A module of TSGR, FR-440.) TR-NWT-000930, Generic Requirements for Hybrid Microcircuits Used in Telecommunications Equipment, Issue 2 (Bellcore, September 1993). (A module of RQGR, FR-796.)
14. TR-NWT-001112, Broadband-ISDN User to Network Interface and Network Node Interface Physical Layer Generic Criteria, Issue 1 (Bellcore, June 1993).
15. TA-NPL-000286 (not available).
16. TA-NPL-000464, Generic Requirements and Design Considerations for Optical Digital Signal Cross-Connect Systems, Issue 1 (Bellcore, September 1987).
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6. OFSTP-3, Fiber Optic Terminal Receiver Sensitivity and Maximum Receiver Input Power.
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EIA/TIA Standards Sales Office
2001 Pennsylvania, NW
Washington, DC 20006
(202) 457-4963

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## Glossary

## 1 PPS

One pulse per second, which equates to approximately 86,400 times per day.

## 10Base-T

Ethernet local area network (LAN) using twisted pair wiring, the most commonly installed LAN.

## absolute time

A specific date and time of day. Absolute time is entered and displayed using the HH:MM:SS DD-MMMYYYY format. START and END Times may be entered as absolute times.

## Access Identifier (AID)

A part of the TL1 protocol which identifies the shelf, module, and port within the SSU-2000. The AID is used in the message display area of the SynCraft:SSU-2000 window to display SSU-2000 event and alarm messages, and in the SynCraft dialog box titles and labels to identify the SSU-2000 system main and expansion shelves, modules, and module ports.

## acquire

The act of gaining control of a piece of equipment needed in a receiver.

## ACS

Acronym: Advanced Control Solutions

## address

A number used by the computer operating system and software to identify a storage location in memory or on a storage device such as a disk. Also, a unique address value associated with a given device on the data highway or on an Ethernet circuit.

## ADSL

Acronym: Asymmetric Digital Subscriber Line.

## AID

Acronym: TL1 protocol Access Identifier

## AIS

Alarm Indication Signal - A code transmitted downstream in a digital network that shows that an upstream failure has been detected and alarmed. Replaces normal traffic signal when a maintenance alarm indication is activated.

## Alternate Mark Inversion (AMI)

Signaling protocol in which ones are indicated by either a positive or a negative pulse, and zeros by no pulse. The ones alternate between positive going and negative going.

## American National Standards Institute (ANSI)

Standards-setting, non-government organization that develops and publishes standards for transmission codes, protocols, and high-level languages for voluntary use in the United States.

## American Standard Code for Information Interchange (ASCII)

A standard digital encoding scheme for data: a 7-bit binary code represents numbers, letters, symbols, and control codes.

## AMI

Acronym: Alternate Mark Inversion.

## Ampere

The unit of measurement of electric current or the flow of electrons, mathematically equal to watts divided by volts.

## ANSI

Acronym: American National Standards Institute.

## ASCII

Acronym: American Standard Code for Information Interchange.

## Asymmetric Digital Subscriber Line (ADSL)

High-speed transmission technology developed by Telcordia and standardized by ANSI as T1.413. ADSL uses existing UTP copper wires from a telecommunications central office to the subscriber premises and involves ADSL modems at both ends to send high speed digital signals asymmetrically (that is, send more information in one direction).

## Asynchronous Transfer Mode (ATM)

Very high speed transmission technology using high bandwidth, low-delay, connection-oriented, packetlike switching and multiplexing techniques in which each 53-byte fixed-size cell is presented to the network on a start-stop basis (asynchronously).

## audit trail

A record of changes made to a database and to the system where the database resides. The record includes the type of change, when the change was made, and who made it.

## B8ZS

Acronym: Bipolar with 8 Zero Substitution.

## Backdoor Logon

A logon which provides a way of getting into a password-protected system without an assigned password.

## Balun

Balanced/unbalanced, refers to an impedance-matching device used to connect balanced twisted-pair cabling with unbalanced coaxial cable.

## Bellcore

See Telcordia Technologies.

## Binary with 8 Zero Substitution (B8ZS)

Zero suppression scheme associated with DS1.

## Bipolar

In digital transmission, an electrical line-signaling method in which the mark value alternates between positive and negative polarities.

## Bipolar Violation (BPV)

In the digital line coding system that inverts the polarity of alternate one bits, a bipolar violation (BPV) indicates the presence on the carrier line of two consecutive "one" bits of the same polarity.

## B-ISDN

Acronym: Broadband Integrated Services Digital Network. Also BISDN.

## BITS

Acronym: See Building Integrated Timing Supply.

## BITS Clock

See Building Integrated Timing Supply.

## BPV

Acronym: See Bipolar Violation.

## Broadband

Used in Wide Area Network (WAN) terminology to indicate a transmission facility providing bandwidth that is greater than $45 \mathrm{Mbit} / \mathrm{s}$ (T3), generally fiber optic systems, and contrasted with narrowband and wideband.

## Broadband Integrated Services Digital Network (B-ISDN or BISDN)

Broadband ISDN. Loosely defined term that refers to circuits capable of transmitting more than one basic rate ISDN.

## Building Integrated Timing Supply (BITS)

As defined in T1.101, the BITS is the master timing supply for an entire building, which is a master clock and its ancillary equipment. This is the most accurate and stable clock in the building, (i.e., the lowest stratum number of the clocks in the building.) The BITS supplies synchronization sources to all other clocks and timing sources in that building. The BITS therefore is realized by the main TSG, the PRS (if deployed), and any sub-tending TSGs within a building or Central Office. Sub-tending TSGs are slave or expansion TSGs operated from the main or master TSG.

## CAS/CCS

Acronym: See Channel Associated Signaling/Common Channel Signaling.

## CBR

Acronym: See Constant Bit Rate.

## CDMA

Acronym: See Code Division Multiple Access.

## Central Office

In telephony, the Local Exchange Carrier (LEC) switching facility. Also called Local Exchange or wire center. Refers to Class 5 switching office, at which subscribers' local loops terminate; handles a specific geographic area, identified by the first three digits of the local telephone number.

## CEV

Controlled Environment Vault - A temperature- and humidity-controlled housing for electronic or optical equipment.

## Channel Associated Signaling/Common Channel Signaling (CAS/CCS)

Framing modes associated with E1 signaling.

## Clock

Internal timing device that creates a signal, generated by an oscillator. The oscillator creates a uniform electrical frequency from which digital pulses can be created. The clock signal provides a timing reference or base for sampling of signal elements in a transmission link; creates signals to be used in a transmission system to control the timing of certain functions; generate periodic, precisely spaced signals that can be used for timing, relating processor operations, or generating interrupts. The clock may be locked to an external reference signal.

## Clock accuracy

The level of agreement of the frequency of a clock with the ideal frequency, specified as the magnitude of the fractional frequency offset from the ideal frequency. The fractional frequency offset is defined as the difference between the actual and ideal frequency divided by the ideal frequency. The frequency in this definition is generally the frequency averaged over a sufficiently long observation time (typically on the order of one hour to one day) to adequately determine the frequency.

## Clock Module

A module that provides the "clock" functions defined for Clock accuracy (above). Usually, two clock modules are deployed in a TSG or SSU.

## Clock signal

Uniform electrical frequency from which digital pulses can be created to provide a reference for transmission signal elements and for timing functions.

## Clocking

In synchronous communication, a periodic signal used to synchronize transmission and reception of data and control characters.

## CO

Acronym: Central Office.

## Code Division Multiple Access (CDMA)

New form of digital cellular phone service. CDMA is a spread spectrum technology that combines the original information signal with a correlating code, resulting in a signal which occupies a much greater bandwidth than the original but allows several simultaneous conversations to share the same frequency allocation.

## CODEC

COder/DECoder - Device that converts analog signals to digital signals for transmission on digital lines. It also reconverts (digital to analog).

## Communications Module (COMM)

A module within an SSU or TSG that supports user interaction with an SSU or TSG by means of information equipment such as a PC.

## Computer Communication Protocol Interface (CCPI)

A Binary interface developed by Datum to provide a common binary interface to Datum equipment, and used to download software or PLD images to the unit.

## Configuration

The arrangement of modules and parameter settings within a device.

## Constant Bit Rate (CBR)

Data service in which bits are conveyed regularly in time and at a constant rate, carefully timed between source or transmitter and sink or receiver. The data transfer rates established by a timing source or clock.

## Controller

SPI interface controller. The Controller is one of the modules that can be Master, typically either a Clock or Comms module.

## CRC

Acronym: See Cyclic Redundancy Checking.

## CRC4

Cyclic Redundancy Checking protocol used with E1 signaling.

## CRC6

Cyclic Redundancy Checking protocol used with DS1 signaling.

## Critical Alarm

A critical alarm is a message that calls attention to an alarm condition that is potentially traffic-affecting, and may require immediate corrective action. Alarm message that signifies that the output reference is invalid or that the output modules have no clock source. A critical alarm activates the major alarm relays and the CRITICAL LED.

## CSU

Channel Service Unit - A customer premises equipment (CPE) device used to terminate a DS1 or DS0 [56/ $64 \mathrm{Kbit} / \mathrm{s}]$ digital circuit. The CSU must comply with FCC rules and store error information provided by the Extended Super Frame (ESF). The CSU also performs line-conditioning, protection, loop-back and timing functions.

## Cyclic Redundancy Checking (CRC)

A data validation process in which a CRC character, whose value depends on the hexadecimal value of the number of ones in the data block, is added to the data block at the end of a transmission by the transmitting device. The receiving device makes a similar calculation and compares the results to determine if there was a mistake in the transmission.

## D4

In DS1 digital transmission technology, D4 is the fourth-generation channel bank or interface between the T1 transmission system and an analog premises device. D4 and ESF are the framing modes associated with DS1 signaling. D4 utilizes superframes for information transfer; ESF uses extended superframes. D4 framing is also called $\boldsymbol{S F}$.

## Data Communications Equipment (DCE)

Protocol which resolves interface issues between DTE and network. As defined in the RS-232 specification equipment to which DTE is connected, often to enable access to network facilities.

## Data terminal equipment (DTE)

Generally end-user devices, such as terminals and computers, that connect to DCE, which either generates or receives the data carried by the network. The RS-232, V. 35 and X. 21 connections are common DCE to DTE interfaces. The major difference between a DCE and a DTE is that pins two and three are reversed.

## DCE

Acronym: See Data Communications Equipment.

## DCS

Acronym: Digital Cross-Connect System. Also DACS (Digital Automatic Cross-Connect System).

## DDS

Acronym: See Direct Digital Synthesis.

## Dense Wavelength Division Multiplexing (DWDM)

Higher-capacity version of Wavelength Division Multiplexing (WDM), a means of increasing capacity of fiber-optic data transmission systems by multiplexing multiple wavelengths of light onto the same optical fiber.

## Digital Cross Connect (DCS) System

Specialized type of high-speed data channel switch. Standard voice switches switch transmission paths in response to dialing instructions. DCD systems depend on separate, specific instructions, from an operator at a console or from a program, that are given independently of system calls, and that direct the connection of one line to another line.

## Digital Service, Level 1 (DS1)

A $1.544 \mathrm{Mb} / \mathrm{s}$ digital signal consisting of 24 DS0s and a framing bit (193 bits per frame, transmitted 8000 frames per second. May be carried on a T1 facility of other transmission medium.

## Digital Service, Level 3 (DS3)

A 44.736 Mbit/s signal, which may consist of 28 DS 1 signals multiplexed together.

## Digital Subscriber Line Access Multiplexer (DSLAM)

Technology which concentrates traffic in ADSL implementations through Time Division Multiplexing (TDM) at the central office or remote line shelf.

## Direct Digital Synthesis (DDS)

The technique of generating signals at a precise frequency using digital methods to select the output frequency as a fraction of the input clock frequency.

## DLCP

DownLoad Communication Protocol. A subset of the Datum Computer Communication Protocol (CCPI) that is used when downloading new program/ PLD images to the unit.

## Download

Receive data into a computer or ROM from another computer, as for example, receiving updated software from a host computer into Flash ROM.

## DS1

Acronym: Digital Service, Level 1.

## DS3

Acronym: Digital Service, Level 3.

## DSLAM

Acronym: Digital Subscriber Line Access Multiplexer.

## DTE

Acronym: Data Terminal Equipment.

## DTE/DCE Switch

2PDT slide switch located on the rear panel of SSU-2000 which allows user to select either DTE (default, connection to PC ) or DCE (connection to modem) type serial port connections.

## DWDM

Acronym: Dense Wavelength Division Multiplexing.

## E1

A digital circuit with standardized characteristics that operates at $2.048 \mathrm{Mbit} / \mathrm{s}$. This standard is widely used in Europe as the rough equivalent of a DS1 (E1 provides thirty $64 \mathrm{Kbit} / \mathrm{s}$ channels, six more than a DSS1).

## E3

A digital circuit with standardized characteristics that operates at 34 Maps. this standard is widely used in Europe for inter-carrier communications as the rough equivalent of a DS3.

## Earth Ground

The connection of an electrical system to earth. This connection is necessary to provide lightning and static protection and to establish the zero-voltage reference for the system.

EIA-232
See $R S$-232.

## Electromagnetic compatibility (EMC)

The ability of equipment or systems to be used in their intended environments within designed efficiency levels without causing or receiving degradation due to unintentional EMI (electromagnetic interference). EMI can be reduced by using proper shielding techniques and grounding.

## Electromagnetic Interference (EMI)

Electromagnetic interference. Radiation leakage outside of a transmission medium that results (mainly) for the use of high-frequency wave energy. May be reduced by shielding.

## EMC

Acronym: ElectroMagnetic Compatibility.

## EMI

Acronym: ElectroMagnetic Interference.

## ESD

Acronym: ElectroStatic Discharge

## ESF

Acronym: Extended SuperFrame format.

## Ethernet

A LAN and baseband protocol based on a packet frame that operates at $10 \mathrm{Mbit} / \mathrm{s}$ over coaxial cable and allow terminals, concentrators, workstations, and hosts to communicate.

## Ethernet Address

12 hexadecimal numbers, unique to the system, which identifies a device.

## ETSI

Acronym: See European Telecommunications Standards Institute

## European Telecommunications Standards Institute (ETSI)

European counterpart to the American National Standards Institute (ANSI), founded in 1988 as a result of an initiative of the European Commission, established to produce telecommunications standards for users, manufacturers, suppliers, administrations, and Post Telephone and Telegraph (PTT) administrations.

## Event History

Historical records of activities for a device, usually comprised of event messages indicating a change in the physical or logical state of the device and a timestamp.

## Extended SuperFrame Format (ESF)

A modification of the Superframe (sometimes called D4) framing scheme for DS1. ESF extends the framing pattern from 12 frames to 24 frames. A frame is 192 data bits and one frame bit. The 24 frame bits are a unique pattern of 1 s and 0 s that allows for terminal alignment, frame count, CRC bits, and a $2 \mathrm{Kbit} / \mathrm{s}$ data channel. Framing allows receiving equipment to identify the start and sequence of data in the binary 1.544 million bits per second DS1 stream.

## Facilities Data Link (FDL)

ESF allows $4 \mathrm{Kbit} / \mathrm{s}$ to be used for a facilities data link which supports the communication of various types of monitoring or diagnostic network information used for provisioning and maintenance. Series-21 units use FDL for PQL settings.

## Fault

Hard failure or performance degradation serious enough to threaten network function.

## FlashROM

Flash Read Only Memory - contains software known as firmware. FlashROM can be erased and reprogrammed but persists when power to the device is turned off. FlashROM can be updated by downloading new firmware into the FlashROM (also called Flash Memory).

## FLL

Acronym: See Frequency Lock Loop.

## Frame Generator

Frame generators use certain input timing signals to generate a digital signal having a specific frame format, such as DS1 (ESF or SF). They also accept input PQL from the reference input and convert it to the appropriate sync status message (SSM) for output.

## Frame Ground (FG)

Connected to the equipment chassis to provide protective grounding.

## Framing

A specified pattern of bits which can be used by the receiver to identify the time slots allocated to each sub-channel in multiplexed digital channels. Framing bits may also carry alarm signals and other overhead information.

## Framing Error

Error which occurs when a receiver does not interpret frame bits correctly.

## Frequency

Rate at which a waveform alternates. Frequency measurements are calculated from phase measurements over time.

## Frequency Lock Loop (FLL)

Mechanism whereby a generated signal is locked to a precise frequency relationship with a reference clock signal. See also Phase Lock Loop (PLL).

## FTP

File Transfer Protocol. An application-level data communications program that transfers files. Files are identified, located, segmented, tagged with a header and passed to the next protocol level for transmission. The name comes from TCP but the function is a typical application level program.

## Gbit/s

Acronym: Gigabits per second.

## Generic Requirement (GR)

A document providing criteria to telecommunication technology, equipment, and operation. A prevalent example is a Telcordia (formerly Bellcore) document type that replaces Framework Technical Advisory (FA), Technical Advisory (TA), and Technical Reference (TR) document types. The GR is a living document representing Telcordia Technologies' current view of a technology.

## GHz

Unit of frequency (giga Hertz) equal to one billion Hertz or one thousand megaHertz or cycles per second.

## Global Positioning System (GPS)

System of satellites that transmits its position and time (derived from on-board celestial navigation equipment and atomic clocks), and a pseudo random noise (PRN) code.

## GR

Acronym: Generic Requirement.

## Graphical User Interface (GUI)

A communication method between a computer and users that depends on graphical objects such as windows, menus, and icons. Users access software functions by manipulating the graphical objects using a pointing device or keyboard commands.

## GUI

Acronym: See Graphical User Interface.

## Hertz (Hz)

A unit of frequency equal to one cycle per second (cps). One kilohertz equals 1000 cps ; one megahertz equals 1 million cps; one gigahertz equals 1 billion cps.

## High-Density Bipolar of Order 3

Zero suppression scheme associated with E1. It does not allow more than three consecutive zeros.

## Holdover Mode

Mode of operation in which an internal clock provides the synchronization reference in the event that the internal reference is lost and another suitable reference is not available.

## ICS

Acronym: See Interactive Command Set.

## IEEE 802.3

The standard for Carrier Sense Multiple Access with Collision Detection is one of the most used LAN protocols.

## Impedance

The opposition to an electrical wave based on frequency, resistance, inductance, and capacitance. Measured in ohms. Impedance is said to be matched when all components of a communications channel present the same (normally standardized) average impedance to the communications signal.

## Institute of Electrical and Electronics Engineers (IEEE)

Professional society whose goal is to advance "the theory and practice of electrical, electronics, and computer engineering and computer science," and a significant standards-making body for telecommunications and computing.

## Interactive ASCII Mode

Command set for interaction with telecommunications interfaces via an ASCII terminal (or other serial or network device), and composed of the commands, parameters, responses, and events that are typed at the system prompt or displayed in the user interface.

## Interactive Command Set (ICS)

A set of commands, responses, and events forming an interface with an SSU or TSG or other equipment with which users can interact by means of a computer or terminal that is connected by a serial cable to the equipment.

## International Standards Organization

Paris-based standard organization that define communications and computing standards. Example standards are ISO 7776 High-Level Data Link Control Procedures X.25, and ISO 9001, a rigorous quality assurance standard

## International Telecommunications Union (ITU)

United Nations agency responsible for establishing standardized communications procedures and practices, particularly known for allocation of radio frequencies, including those used by satellites.

## International Telecommunications Union, Telecommunications Services Sector (ITU-T)

Permanent organ of the ITU, responsible for studying technical, operating, and tariff questions, and for issuing recommendations of each with a view to standardizing telecommunications on a worldwide basis.

## Internet Protocol (IP)

The Internet Protocol (IP) address, internally represented as a 32 -bit unsigned value, unique to the network, and consisting of three parts: IP address, internet gateway address, and network mask. All parts take the same form as that of the IP address. The network mask is the specification as to which bits are to be interpreted as the network address, and is a 32 -bit value with ones in all bit positions that are to be interpreted as the network position.

The IP Address consists of three parts: IP address, gateway address, and network mask.

- The IP address is Internet protocol address internally represented as a 32-bit unsigned value. For example, the IP dotted address 192.168.70.224 is internally represented as IP address 0xC0A846E0.
- The gateway address is the Internet gateway address. The format is the same as described for the IP address. The network mask is the specification as to which bits are to be interpreted as the network address.
- The network mask is a 32-bit value with ones in all bit position that are to be interpreted as the network position. For example, the network dotted mask 255.255 .255 .0 represented as network mask as $0 x F F F F F F 00$. The IP address must be unique in the network.


## IP <br> Acronym: See Internet Protocol.

## IP Address

The IP Address consists of three parts: IP address, gateway address, and network mask. The IP address is Internet protocol address internally represented as a 32-bit unsigned value. For example, the IP dotted address 192.168.70.224 is internally represented as IP address 0xC0A846E0. The gateway address is the Internet gateway address. The format is the same as described for the IP address. The network mask is the specification as to which bits are to be interpreted as the network address. The network mask is a 32-bit value with ones in all bit position that are to be interpreted as the network position. For example, the network dotted mask 255.255 .255 .0 represented as network mask as $0 x F F F F F F 00$. The IP address must be unique in the network.

## ITU

Acronym: International Telecommunications Union.

## ITU-T

Acronym: International Telecommunications Union, Telecommunications Services Sector.

## IXC

Acronym: IntereXchange Carrier.

## Jumper

Strictly speaking, a wire connection between equipment and cable on a distribution frame. This term has come to be used for the adapters located on a chassis, to which standard connections are made to the internal logic and circuits.

## kHz

Abbreviation: See kiloHertz.

## kiloHertz

Refers to a unit of frequency equal to 1,000 Hertz.

## LG

Logic Ground

## Light Emitting Diode (LED)

A semiconductor device that emits incoherent light formed by the P-N function. Light intensity is roughly proportional to electrical current flow. A principal light source for optical-fiber transmission used mainly with multi-mode fiber. Also used for visual identification.

## LIU

Acronym: Line Interface Units

## LNA

Low Noise Amplifier

## Local Area Network (LAN)

A user-owned, user-operated, high-volume data transmission facility connecting servers within a confined area. Run by software such as NetWare or Appletalk. Physical transfer is performed by the access method (Ethernet, etc.).

## Local Oscillator (LO)

The internal oscillator.

## Local Terminal (LT)

Computer, laptop, or ASCII terminal which is connected to a network element by a direct serial connection.

## Locked Mode

Operational mode in which the processor controls DDS on the clock input signals in order to maintain the output frequency with respect to the input reference. The processor measures the phase of each input and adjusts the control value based on the phase changes of the reference. The processor also monitors all input signals for MTIE, frequency, and input signal errors such as Loss of Signal (LOS) or Out of Frame (OOF).

## Log On

Process by which users identify and authenticate themselves to a network system or interface. Users typically enter their username and password.

## Loss of Frame (LOF)

Generic term which is used specifically in different signal domains. For example, in the SONET domain, LOS is a condition that indicates that a valid framing pattern could not be obtained.

## Loss of Signal (LOS)

Generic term which is used specifically in different signal domains. For example, in the SONET domain, LOS is a loss of signal condition which is detected physically at the receiver

## LT

Acronym: See Local Terminal.

## MAJOR Alarm

Alarm message that indicates a failure or malfunction of important circuits and requires immediate attention. As an example, it is an alarm message which signifies that the output signals are not synchronized to an input signal.

## Master

SPI interface master. The master is the only module that originates the SPI transfer.

## Maximum Time Interval (MTIE)

A peak-to-peak measure of the longer-term phase-time variations of the significant instants of a signal.

## Mbit/s

Acronym: Megabits per second.

## MegaHertz (MHz)

Refers to a frequency equal to one million Hertz, or cycles per second.

## MINOR Alarm

Alarm message which signifies a condition that is not fatal to synchronization, but which could lead to more significant problems.

## Modem

Modulator/Demodulator - An electronic device used to allow a computer to send and receive data.

## MTIE

Acronym: See Maximum Time Interval Error.
NCO
Acronym: Numeric Controlled Oscillator.

## Network Element (NE)

Processor controlled entities of the telecommunications network that primarily provides switching and transport network functions and contains network operations functions.

## Network Time Protocol (NTP)

NTP is a 64-bit protocol quantifying the absolute time (time of day). The reference scale is Universal Time Coordinated (UTC). It counts the seconds since the year 1900 with a resolution of 232 picoseconds.

## NFOEC

Acronym: National Fiber Optic Engineers Conference.

## Non-Volatile Random Access Memory (NVRAM)

RAM that does not lose its memory when power to it is turned off, and typically used to store software configuration settings.

## NTP

Acronym: Network Time Protocol.

Numeric Controlled Oscillator
A component used in the DDS circuitry.

## NVRAM

Acronym: See Nonvolatile Random Access Memory.

## OAM\&P

Acronym: Operation, Administration, Maintenance, and Provisioning.
OC-N
Acronym: Optical Carrier, Level number. Example OC-12-Optical Carrier, Level 12.

## OOF

Acronym: See Out of Frame.

## Open Systems Interconnection (OSI)

Standard protocol model developed by the Organization for Standardization for communication between systems created by different vendors, the goal of which is to create an open systems networking environment in which any system can share data with any other system on that or a linked network. The model organizes the communications process into seven categories and places the categories in a layered sequence based on the relation of each to the user. In this model, layers 7 through 4 treat the end to end communications between the message source and the message destination; layers 3 through 1 treat network access.

## Organization for Standardization (ISO, IOS)

Often called International Standards Organization, this voluntary, non-treaty, non-governmental organization located in Geneva was chartered by the United Nations to define and publish international standards for all fields other than electrical and electronic engineering.

## Oscillator

An electronic device used to produce repeating signals of a given amplitude or frequency.

## Out of Frame Error (OOF)

Designates an error condition in framing bits, declared when two of four or two of five framing bits are missed.

## Output Module

Provides output sources from the SSU or TSG, or similar equipment.

## Output Port

An output port is a point of access for signals to be transmitted from equipment. In the case of Synchronization Equipment (SE), an output port provides synchronization signals of a specific format. There are typically multiple output ports per output module. (See Port.)

## Password

Word or string of characters which a user or system administrator associates with a username, and which is entered by the user during the login in process to authenticate the username login to the network.

## Phase Locked Loop (PLL)

Mechanism whereby a generated clock signal is locked to a precise phase relationship to a reference clock signal. A signal that is phase locked is also frequency locked. In some equipment, the receiver uses a PLL to derive timing signal information by locking the local clock source to the external timing signal. See also Frequency Lock Loop (FLL).

## Phase Measurement

Phase measurements determine the difference in phase between the input signals and the reference clock.

## PLD

Acronym: Programmable Logic Device (also called LCA or FPGA.)

## PLL

Acronym: See Phase Locked Loop.

## Port

A point of access into a computer, an network, or other electronic device. The physical or logical interface through which one gains access.

## PPS

Acronym: Pulses Per Second. See 1 PPS.

## PQL

Acronym: See Priority Quality Level.

## Primary Reference Clock (PRC)

Any device that provides a PRS quality output signal. PRC is the ETSI and ITU name for a PRS.

## Primary Reference Receiver (PRR)

A radio receiver that provides a PRS quality output signal.

## Primary Reference Source (PRS)

Timing signal with ANSI Stratum 1, or ITU and ETSI PRC accuracy and stability.
Master clocking source in a system or network from which other distributed devices derive their clocking and which enables the system or network to maintain synchronization.

## Priority Quality Level (PQL)

Used internally in to represent the Synchronization Quality Level. See SPI interface document (Datum P/N 12613087-000-2).

## Priority Quality Level (PQL)

PQL settings provide an internal representation of traceability of signal presented at the input ports. The PQL settings can be managed by means of an editable translation table in which PQLs are assigned for provisioning Synchronization Status Messages. PQL information is carried in the FDL of the ESF.

## PRR

Acronym: Primary Reference Receiver.

## PRS

Acronym: Primary Reference Source

## Rack

Aluminum or steel rack onto which equipment is mounted. The telecommunication industry standard rack size is 19 inches ( 48.26 cm ) or 23 inches ( 58.42 cm ) wide at the front. Telecommunication equipment is mounted on the rack and cables are laid in and fastened to the rack.

## Rack mounting ears

Adjustable brackets which attach to the sides of the equipment chassis to allow a 19-inch ( 48.26 cm ) chassis to be mounted in a standard 23-inch ( 58.42 cm ) rack.

## Rb oscillator

Rubidium oscillator, typically used in Stratum 2 or Stratum 2E clock modules.

## RJ-45

The 9-pin connector used for data transmission over flat or twisted standard telephone wire. Flat wire is used for serial data communications up to 19.2 Kbps to PBXs , modems, printers, or printer buffers. Twisted wire is used for connecting to a 10Base-T local area network. Connectors are keyed or non-keyed. Keyed male connectors have a key or small square bump on the end; keyed female connectors are shaped to accommodate the key.

RS-232
Also known as EIA/TIA-232-E. A set of standards specifying electrical, functional, and mechanical interfaces for communicating serially between computers, terminals, and modems. The interface established by EIA to specify functions of interchange circuits, electrical characteristics, and connectors.

## RS-232-C

The industry standard for a 25-pin interface that connects computers with various forms of peripheral equipment; i.e., modems, printers, etc.

## RS-232-D

An EIA-specified physical interface, with associated electrical signaling, between data circuit-terminating equipment (DCE) and data terminal equipment (DTE); the most commonly employed interface between computers and modems.

## SDH

Acronym: See Synchronous Digital Hierarchy.

## SDU

Acronym: Synchronization Distribution Unit.

## SE

Acronym: Synchronization Element.

## SEM

Acronym: See Synchronization Element Manager.

## SNMP

Acronym: See Simple Network Management Protocol.

## SPI

A hardware and software interface that is used to communicate to any devices connected to a Telecom or network unit.

## Serial Transmission

The sequential transmission of the bits constituting an entity of data over a data circuit.

## Shielding

Protective enclosure surrounding a transmission medium, such as coaxial cable, designated to minimize electromagnetic leakage.

## Simple Network Management Protocol (SNMP)

A system control interface that is based on a client server query-response mode. A manager is the client generating the queries, while an agent is the server generating the responses.

## Slave Clock

A clock which is normally locked to a reference timing signal. Also referred to as subtending.

## SONET

Acronym: Synchronous Optical NETwork.

## SPI

Acronym: Serial Peripheral Interface.

## SSM

Acronym: See Synchronization Status Message.

## SSP-IDCS

Acronym: Software Switching Platform Integrating DCS.

## SSU

Acronym: See Synchronization Supply Unit.

## ST2E Rb Clock

Stratum 2E Rubidium clock module. Uses the Rubidium oscillator and meets or exceeds the performance requirements for ANSI and Telcordia Technologies (Bellcore) Stratum 2, ITU Type II and ETSI clocks.

## Stratum 1

Stratum 1 is the highest quality or performance level in terms of accuracy and stability of a frequency source specified in T1.101, and refers to a Primary Reference Source.

## Stratum Levels

Standard T1.101 defines levels of performance of clocks in a synchronized network in terms of accuracy and stability. Stratum 1 is the highest level of performance and stratum 4 is the lowest.

## Synchronization

Timing of network transmissions by a master clock.

## Synchronization Element Manager (SEM)

Software interface for managing performance, configuration, security, fault, alarm, and event reporting for synchronization elements.

## Synchronization Status Message (SSM)

Sync Status Messages - Defined bits used to transmit the traceability of the sync reference signal and the quality of the clock being used to sync the outputs.

## Synchronization Status Message (SSM)

Method by which synchronization network elements can communicate the traceability of their synchronization quality levels. SSMs take the form of identifiers embedded within the reference signals, and are used as synchronization sources for Timing Signal Generators (TSGs) and other network elements (NEs). The identifiers carry information about the quality of the synchronization source to which the particular synchronization signal is traceable. Identifiers also indicate whether the signal is available for use as a synchronization source. SSMs are especially useful in avoiding timing loops, while allowing the TSG or NE to autonomously reconfigure to the most suitable synchronization source available.

## Synchronization Supply Unit (SSU)

Equipment that performs the function of reference timing signal selection, processing, and distribution that provides the frequency characteristics of slave clocks for telecommunications synchronization.

## Synchronous Digital Hierarchy (SDH)

The ITU-T standard for synchronous data transport on optical interfaces, similar to the SONET standard.

## Tbit/s

Acronym: TeraBits per second. $10^{12} \mathrm{bits} / \mathrm{sec}$

## TCP/IP

Acronym: Transmission Control Protocol/Internet Protocol.

## TDEV

Acronym: See Time Deviation.

## TDM

Acronym: See Time Division Multiplex.

## Telcordia Technologies

Current name of the organization that was formerly Bellcore.

## Time Deviation (TDEV)

A measure of the longer-term expected phase-time variations (wander) of a signal as a function of integration time. TDEV also provides information on the spectral content of the phase-time noise of a signal.

## Time Division Multiplex (TDM)

Technology for sharing communication path between multiple sources, accomplished by transmitting a number of separate data, voice, or video signals simultaneously over one communications medium by sampling data, quickly interleaving sample (pieces of each signal), transmitting samples one after another, and reconstructing at the end. The goal is to pack more conversations of all data types onto fewer phone lines, in effect, substituting electronic capability for more copper line.

Time of Day (TOD)
Time and date information.

## Timing Signal Generator (TSG)

Device which generates and distributes network synchronization signals, generally in a variety of waveforms.

## Tip and Ring

Two wires, positive and negative, needed for a connection.

## TL1

Acronym: Transaction Language One.

## Transaction Language One (TL1)

A Telcordia interface standard used in the telecommunications industry for $\mathrm{O}, \mathrm{A}, \mathrm{M}, \& \mathrm{P}$ functionality.

## Transmission Control Protocol/Internet Protocol (TCP/IP)

Two of the protocols from a suite of networking standards developed by the U.S. Department of Defense in the 1970s to support a global system of interconnected networks.

## TSG

Acronym: See Timing Signal Generator.

## Turn up

Power up or on.

## Universal Time Coordinated (UTC)

Time scale maintained by cooperating international agencies including the US Naval observatory, the Bureau International des Poids et Mesures, and the International Earth Rotation Service. UTC is the standard official time and forms the basis of a coordinated dissemination of standard frequencies and time signal.

## Username

The name by which each user is known in the network administration. Each user must enter a username when logging in to identify the user to the network. Each username is also associated with a password, which validates the username, and an access level which determines the degree of access granted to the user.

## VCXO

A crystal oscillator (Voltage Controlled Crystal Oscillator) whose clock frequency is determined by the magnitude of the voltage presented at its input. Such oscillators are typically a component of a hardware PLL or FLL.

## Voice/Video over Internet Protocol (VoIP)

The VoIP Forum was established in 1996 by Cisco Systems as a working group of the International Multimedia Teleconferencing Consortium (IMTC).

## VoIP SynCBR

Acronym: Voice/Video over IP Sync Constant Bit Rate.

## Volt

A unit of measurement of electromotive force. A voltage is always expressed as the potential difference in available energy between two points. One volt is the force required to produce a current of one ampere through a resistance or impedance of one ohm. See Direct Current.

## Watchdog Timer

Mechanism used to trigger an event or an escape from a process unless a timer is periodically reset. For example, a time may indicate the maximum period of time that a network connection will remain open before expiring.

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[^0]:    $\overline{\overline{\#}}$
    Note ..
    External, customer-supplied padding can be affixed to attenuate the output level to meet Composite Clock specifications.

[^1]:    豆
    Note ...
    If you specify times and dates, events that occurred after the starting date and time and before the ending date and time display. Specified dates have the format yyyy-mm-dd, and specified times have the format hh:mm:ss.

    Specified dates and times are not provided in ISO timestamp format, and are separated by a space. Start time and stop time default to the current time of day. Stop date defaults to the current date. Start date defaults to the current date, minus 24 hours.

[^2]:    In Note..
    Input reference selection order proceeds from highest (1) to lowest (10) priority valid input port. If there are equal priorities, the PQL value is used to distinguish between them.

